



# NEURIPS 2025

# Inferring Cosmological Parameters

# with CNN K-Fold Ensembling

An overview of the 6th place solution for the Weak Lensing ML Uncertainty Challenge

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## What is Weak Lensing

- Dark matter does not interact with light directly but has mass, thus indirectly warping light like a black hole.
- Weak lensing is like a kaleidoscope
- Different universes are kaleidoscopes with different shapes in it



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# CNN

- Images classification means CNN
- Not a lot of data
- Perfect function from Weak Lensing Maps to  $\Omega_m$  and  $S_8$  is discrete

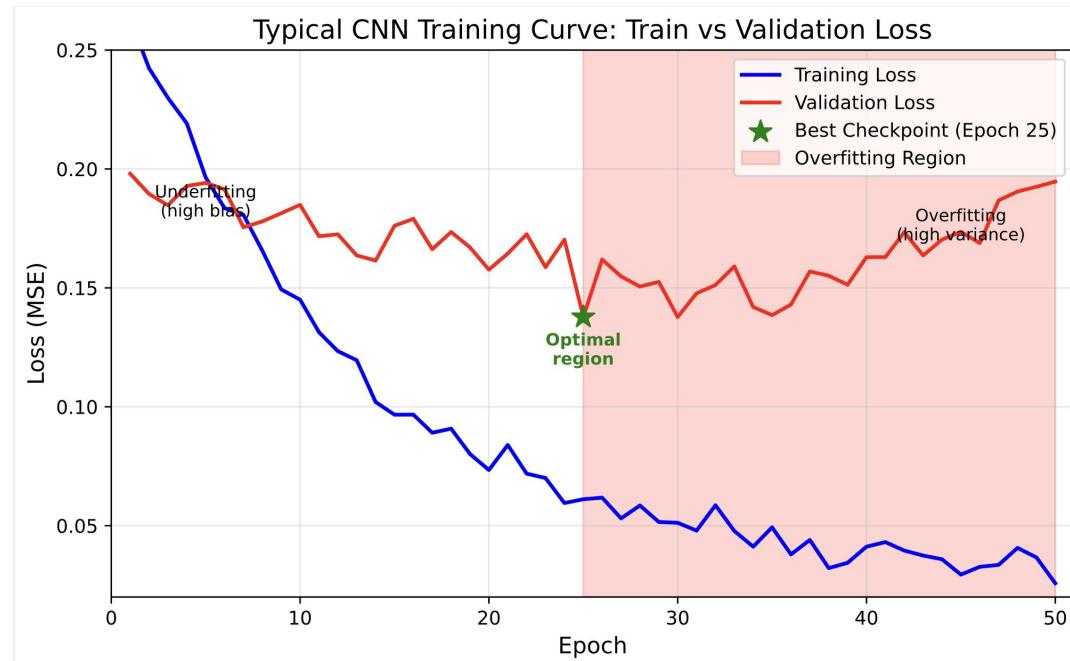


Regnext/Contrastive  
Learning/Attention/Literally  
Anything Else

**Specifically  
Resnet18**

# CNN

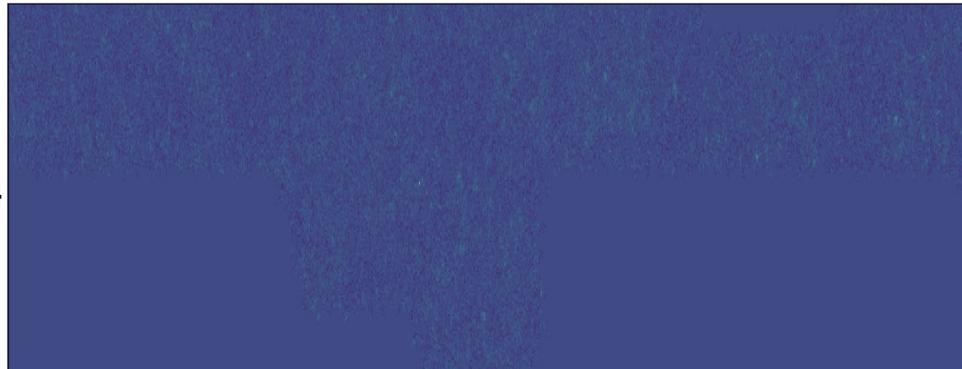
- RepVGG trained on four fifths of the data
- Obvious overfitting
- Model refused to guess exterior points

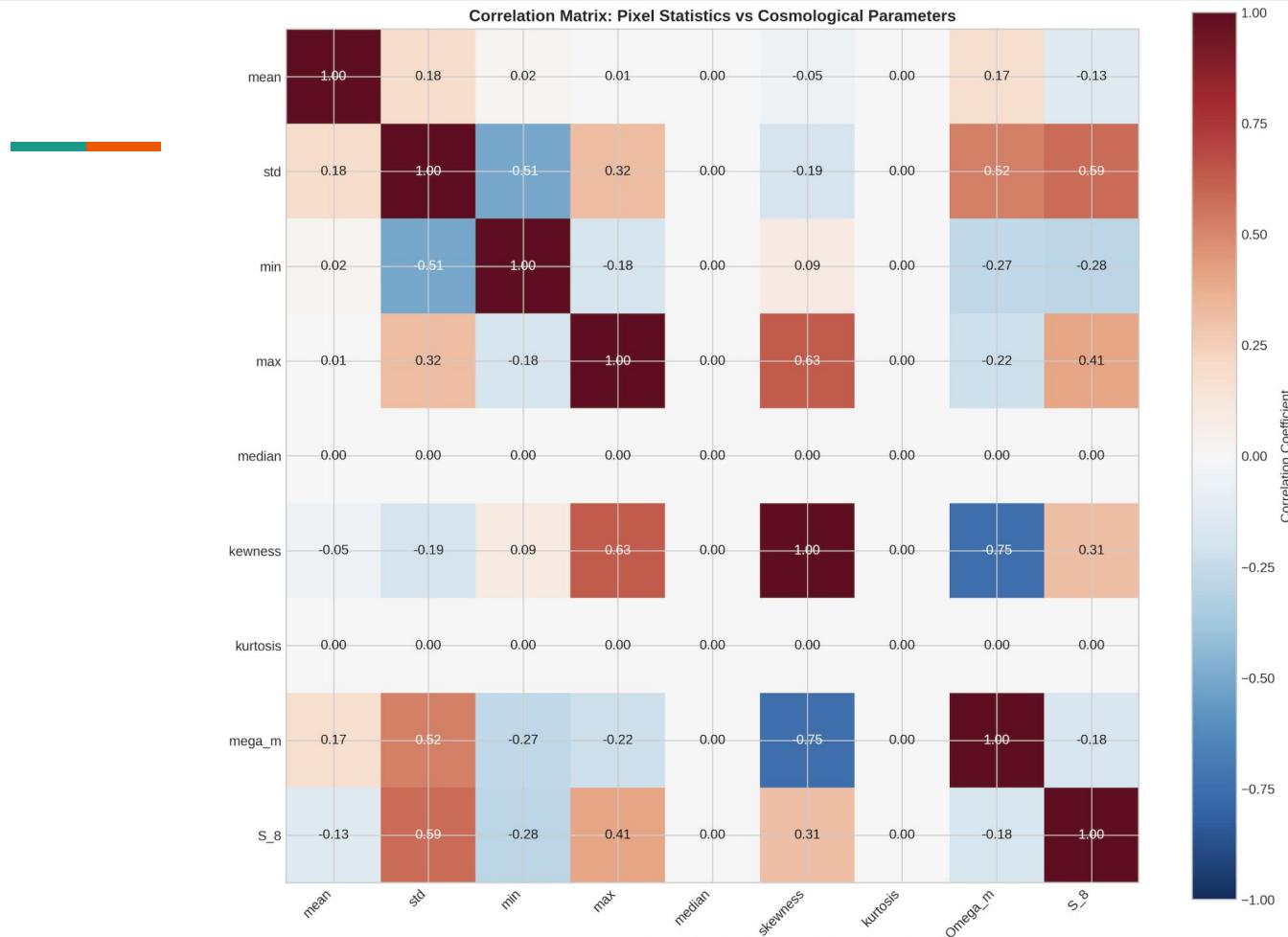


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# Generalization Challenge

- Very Dense Features
- Impossible task for human eyes
- Data analysis reveals some interesting findings

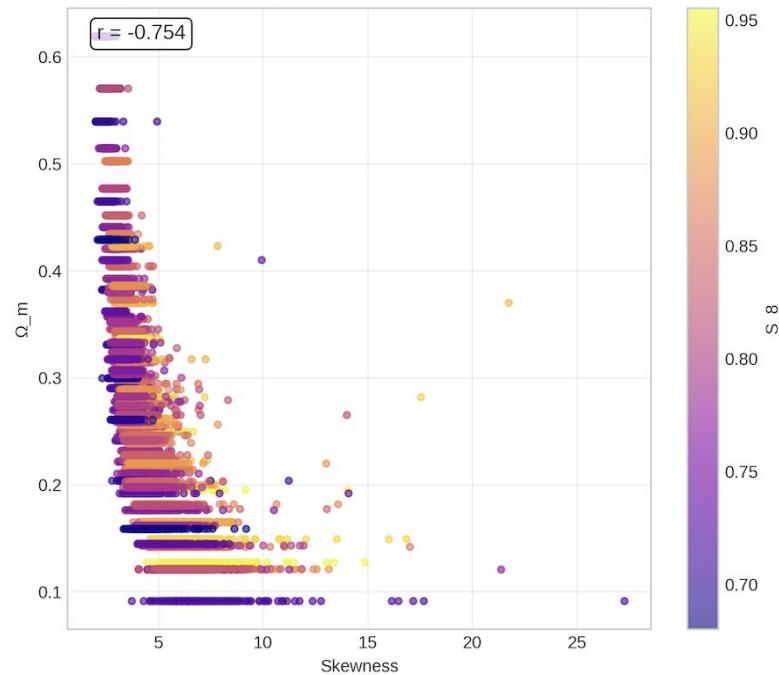




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# Generalization Challenge

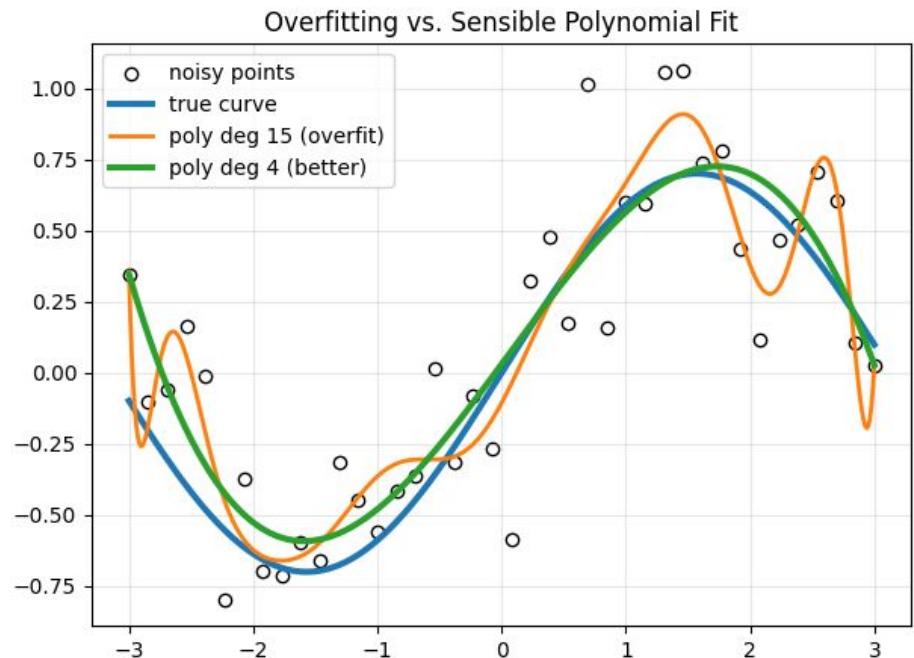
- $\Omega_m$  is most highly correlated to skewness
- $S_8$  is most highly correlated to std
- Very few outliers



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# Generalization Challenge

- Requires Stable Validation Loss
- Larger Models
- Data Augmentation





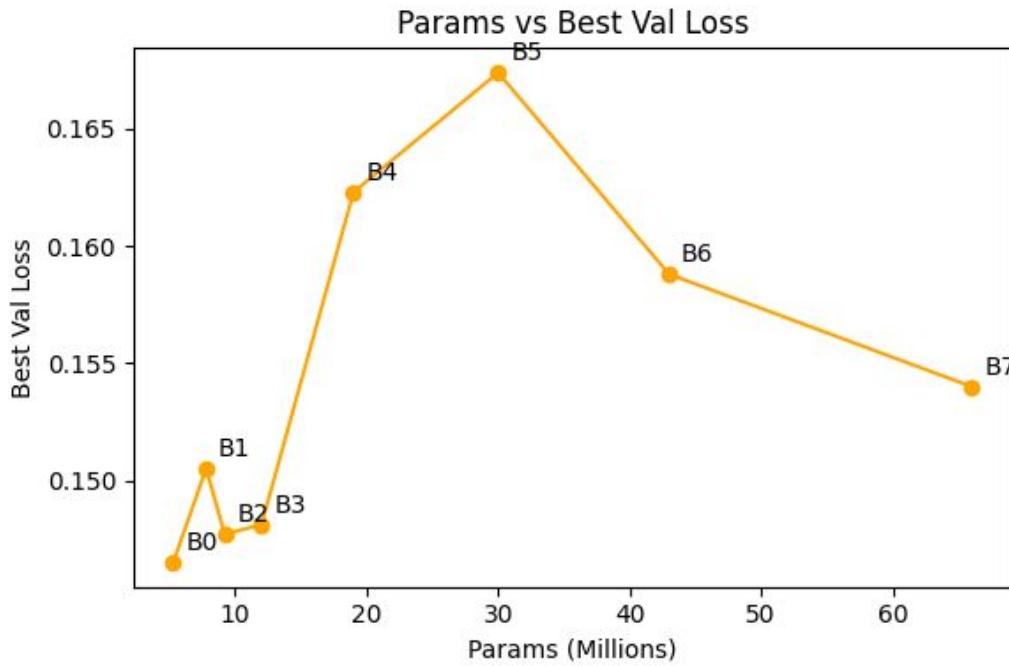
# Double Descent

Model	Params	Time (min)	Best Val Loss	Best Epoch	Train Loss	Gap
B0	5.3M	19.9	0.1465	6	0.1289	0.059
B1	7.8M	24.1	0.1505	15	0.1728	-0.022
B2	9.2M	25.0	0.1477	8	0.1303	0.03
B3	12M	32.4	0.1481	6	0.1429	0.023
B4	19M	41.5	0.1623	9	0.2065	-0.037
B5	30M	56.4	0.1674	3	0.1177	0.051
B6	43M	72.0	0.1588	12	0.1172	0.042
B7	66M	96.4	0.154	6	0.0952	0.073

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# Double Descent

- Performance implies efficient net has double descent behavior on this dataset
- Not feasible to train models larger than B7
- B7 train time 5 times of B0 train time



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# Data Augmentation

## Experimental Setup:

- EfficientNet-B3
- 15 epochs
- Batch size 16
- AdamW with 1e-3 learning rate and 1e-4 weight decay
- MSE Loss

## Tested Augmentations:

- Random Horizontal and Vertical Flips
- Random Rotation
- Dropout
- Random Noise
- Mix-up
- Coordinate Channels

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# Data Augmentation

- Dropout, mixup, and random noise all had negative impact
- Extremely dense problem so any slight change to individual pixel values will deteriorate prediction ability

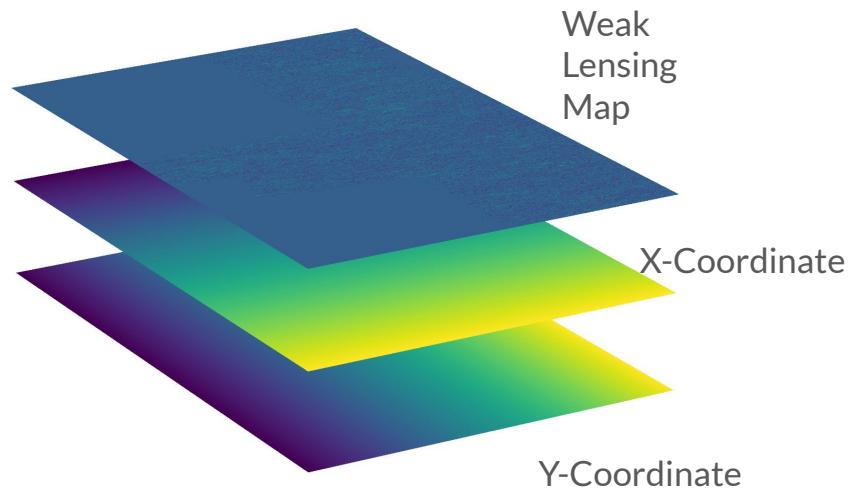
Augmentation	Val MSE	Best Ep.	vs None
None	0.002051	11	1.0×
Flip only	0.002802	11	1.37× ↓
Rotation only	0.001261	5	0.61× ↑
<b>Flip + Rotation</b>	<b>0.000675</b>	15	<b>0.33× ↑</b>



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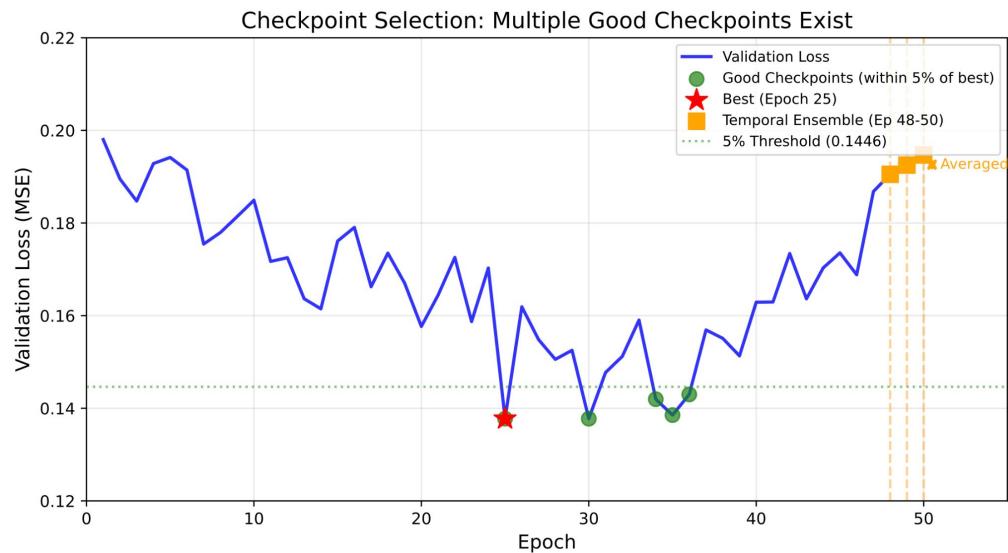
## Coordinate Channels

- Second and third channel inputs became coordinates
- Specific areas may have specific indicators
- Sinusoidal or radial may perform better



# K-Fold & Ensembling

- Does not require perfect convergence
- Decreases variance while keeping bias
- Uses full training data



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# K-Fold & Ensembling

- Does not require perfect convergence dynamics
- Decreases variance while keeping bias
- Uses full training data

For a single model  $f$ , the expected prediction error decomposes as:

$$\mathbb{E}[(y - f(x))^2] = \underbrace{(\mathbb{E}[f(x)] - f^*(x))^2}_{\text{Bias}^2} + \underbrace{\mathbb{E}[(f(x) - \mathbb{E}[f(x)])^2]}_{\text{Variance}} + \underbrace{\sigma_\epsilon^2}_{\text{Irreducible}}$$

where  $f^*(x)$  is the true function and  $\sigma_\epsilon^2$  is irreducible noise.



# Submission

Core Model: RepVGG-D2se CNN regressor → predicts  $(\Omega_m, S_8)$

- Split Across 5 Folds each with equal distribution of cosmologies
- Stability first training:
  - batch size 80
  - Grad accumulation
  - Ghost BatchNorm
- Two Phase Augmentation:
  - Flips and Rotations: Epochs 1-45
  - Just Flips: epochs 45-50
  - Test Time Augmentations
- MCMC Error Bar Estimation
  - 1.2x final scaling

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# K-Fold & Ensembling

- Split each 256 systematics into 5 Folds
- Select top 5 checkpoints among each fold compute inference with TTA
  - All 4 combinations of horizontal and vertical flips
- Throw out the farthest 30% of inferences to the average among all inferences in the fold
- Compute the final predictions for this fold by averaging the remaining inferences

Fold	Val Size	Train Size	Val Index Range
0	5,252	20,604	0–52
1–4	5,151	20,705	52–256

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## K-Fold & Ensembling

- Compute predicted points by averaging the cosmological inferences from the 5 folds
- Compute the error bars on the final model prediction using a weighted average
  - Since all folds are weighted equally  $w_k$  is 0.2

**For  $K$  model predictions  $(\mu_k, \sigma_k)$ :**

$$\sigma_{\text{mix}}^2 = \sum w_k \sigma_k^2 + \sum w_k (\mu_k - \mu_{\text{mix}})^2$$

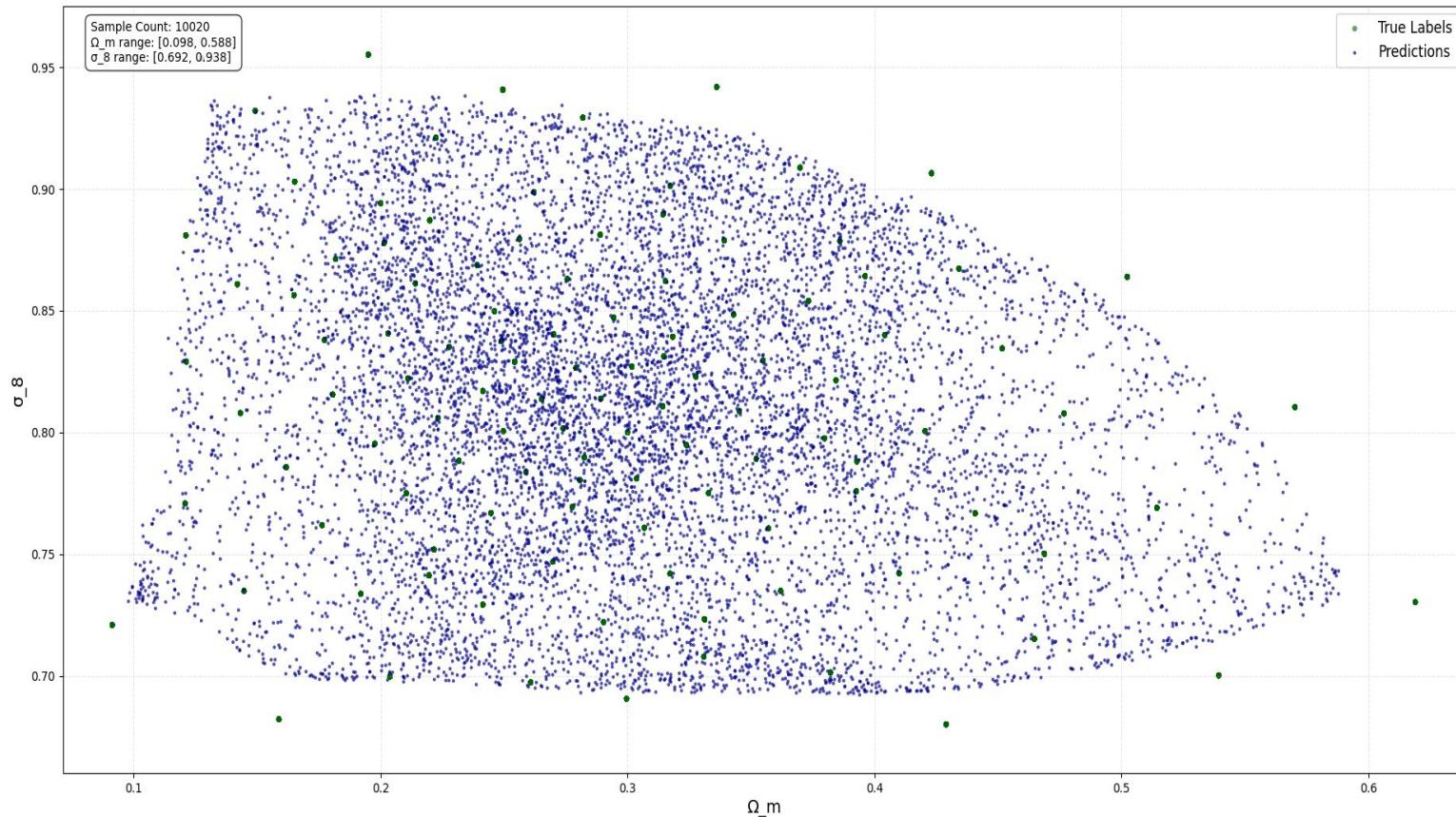


## K-Fold & Ensembling

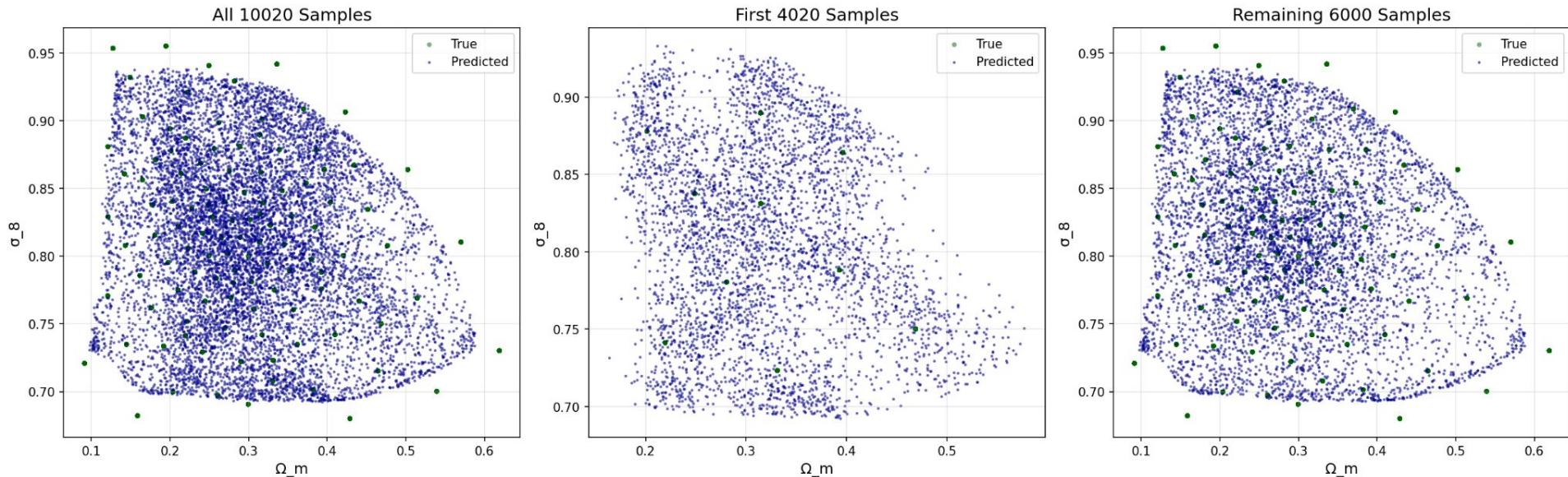
- Don't want to waste all the previous checkpoints
- Combine error bars using the aforementioned weighted average
- At least 0.2 score increase from singular model

Model Family	Weight	Role
<b>RepVGG-D2se</b>	<b>0.50</b>	Primary
EfficientNet-V2-L variants	0.15	Diversity
RepVGG variants	0.15	Diversity
EfficientNet-V2-L additional	0.10	Support
EfficientNet-B7 batch80	0.05	Support
EfficientNet-B7 batch64	0.05	Support

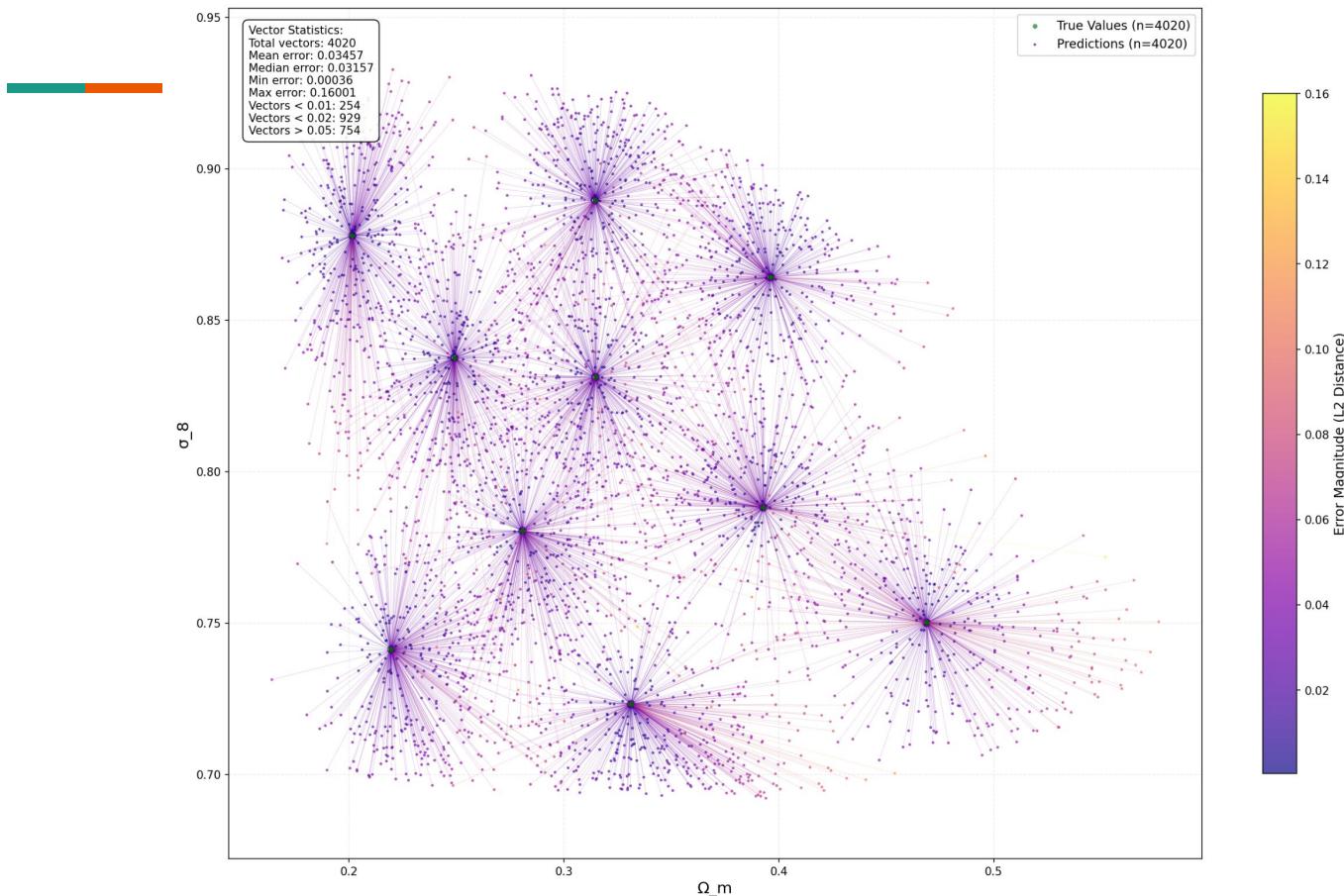
Predicted vs True Labels in Parameter Space  
(10020 samples)



Predicted vs True Labels by Subset

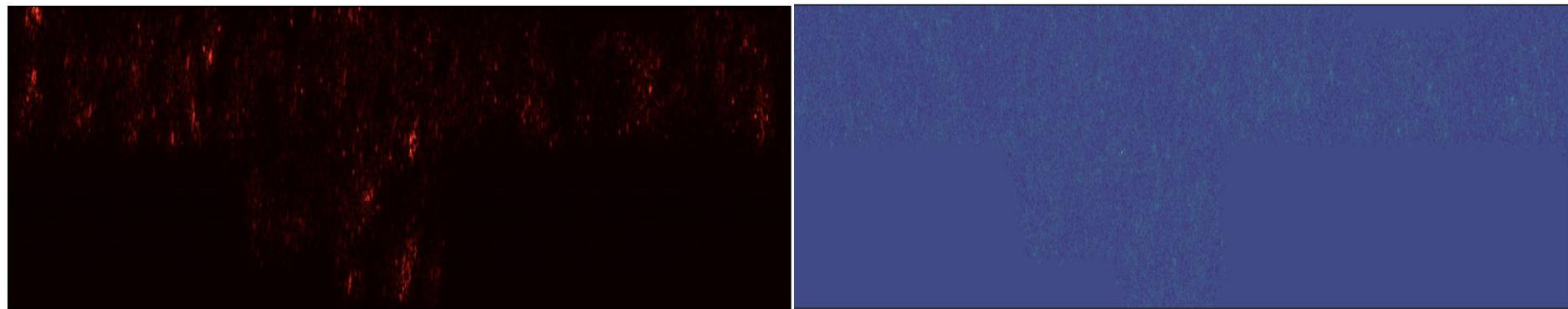


Prediction Vectors: First 4020 Samples  
ALL 4020 vectors shown (Predictions  $\rightarrow$  True Labels)





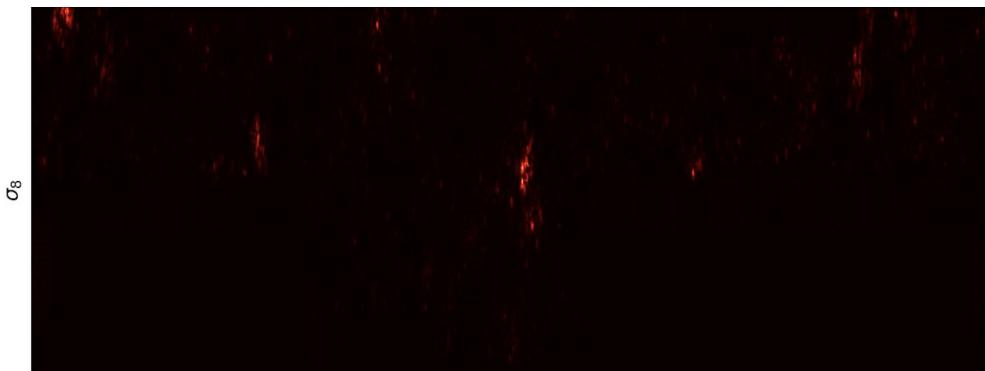
**Activation:  $\Omega_m = 0.3, S_8 = 0.8$**



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## Activation: $\Omega_m = 0.3, S_8 = 0.8$

- $\Omega_m$  tends to depend on aspects of the entire weak lensing map
- $S_8$  tends to depend on a specific few aspects of the weak lensing map
- Requires entire map to make an optimal predictions





# Submission

- 8th place on public test data
- 6th place on private test data

Score	MSE	Coverage
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1. 11.4163	0.1102	0.6951
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2. 10.8722	0.1121	0.6775
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3. 11.1442	0.1111	0.6863
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# Conclusion

Traditional ML Techniques are able to go a long way, but don't get too demotivated if a novel approach does not work.

Questions & Comments

Welcome!