



復旦大學

# Convex Potential Mirror Langevin Algorithm for Efficient Sampling of Energy-Based Models

Zitao Yang<sup>1</sup>, Amin Ullah<sup>2</sup>, Shuai Li<sup>3</sup>, Fuxin Li<sup>4</sup>, Jun Li<sup>1</sup>

<sup>1</sup>Fudan University    <sup>2</sup>Boeing Research and Technology

<sup>3</sup>University of Bonn    <sup>4</sup>Oregon State University

yangzt21@m.fudan.edu.cn

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# Outline

- 1 Introduction
- 2 Background
- 3 Proposed Method: CPMLA
- 4 Theoretical Analysis
- 5 Experiments
- 6 Conclusion

# Motivation: Challenges in EBM Sampling

- Energy-Based Models (EBMs) offer flexibility in modeling complex distributions.
- Applications: 3D recognition, image restoration, protein folding.

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- **Challenge:** Sampling relies on MCMC (e.g., Langevin Dynamics), which is often slow and can get stuck, especially in high dimensions or with complex energy landscapes.
- Existing methods to improve sampling still face issues like non-mixing.
- **Goal:** Develop a more efficient and reliable sampling algorithm for EBMs.

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# Background: EBM and Mirror Langevin Dynamics

## Energy-Based Models (EBMs)

- Define probability density via an energy function  $f_{\theta}(x)$ :  
$$p_{\theta}(x) = \frac{1}{Z(\theta)} \exp(f_{\theta}(x)).$$
- Training involves MCMC sampling (e.g., Langevin) to approximate gradients.

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## Mirror Langevin Dynamics (MLD)

- Generalizes Langevin dynamics to non-Euclidean geometries using a *mirror map*  $\nabla G$  derived from a convex potential  $G$ .
- Can accelerate convergence and adapt to data geometry.
- **Limitation:** Conventional MLD uses fixed mirror maps, which struggle with complex data manifolds.



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# CPMLA: Convex Potential Mirror Langevin Algorithm

**Key Idea:** Use a *dynamic*, learnable mirror map within MLD for EBM sampling.

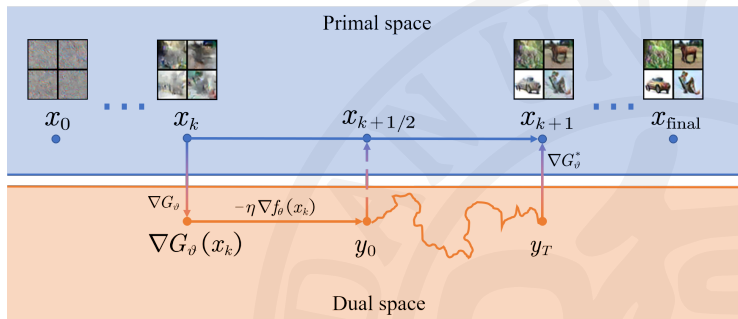
- Mirror Map  $\nabla G_\vartheta$ : Implemented using Convex Potential Flow (CP-Flow).
- CP-Flow uses Input Convex Neural Networks (ICNNs) to guarantee convexity.
- Learns optimal transport map, capturing data geometry.

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- CP-Flow uses Input Convex Neural Networks (ICNNs) to guarantee convexity.
- Learns optimal transport map, capturing data geometry.
- **Cooperative Learning:** Jointly train the EBM ( $f_\theta$ ) and the dynamic mirror map ( $\nabla G_\theta$ ).
  - EBM learns energy function using samples from CPMLA.
  - CP-Flow learns geometry using real data and EBM samples.
  - Creates a virtuous cycle of improvement.

# CPMLA: Algorithm Overview



**Figure:** Overview of CPMLA sampling: Alternating updates between primal (image) and dual (geometry) spaces using the dynamic mirror map  $\nabla G_\vartheta$  and EBM gradients  $\nabla f_\vartheta$ .

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# Theoretical Analysis: Convergence Guarantee

We provide the *first* convergence analysis for MLD with deep neural network mirror maps.

## Theorem (Convergence of CPMLA (Informal))

*Under standard assumptions (Mirror LSI, Self-Concordance, Relative Lipschitz/Smoothness), CPMLA achieves:*

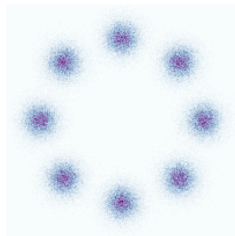
- **Exponential Convergence:** *The distribution of samples  $\rho_t$  converges exponentially fast to the target distribution  $p_{\text{data}}$  in Total Variation distance.*
- **Vanishing Bias:** *The bias approaches zero as the step size  $h \rightarrow 0$ .*
- *Accounts for approximation errors from both the EBM ( $\delta_2$ ) and CP-Flow ( $\delta_3$ ) networks.*

Supports the efficiency and reliability of CPMLA in practice.

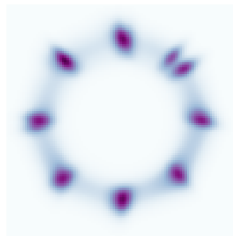
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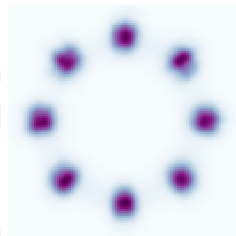
# Experiments: Toy Example - Eight Gaussians



(a) Data



(b) CP-Flow (10 it.)



(c) CPMLA (3 it.)

**Figure:** CPMLA efficiently captures the target distribution, matching CP-Flow's quality in fewer iterations.

Demonstrates faster convergence on synthetic data.

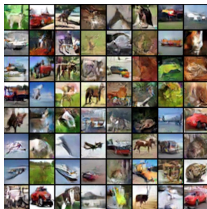


# Experiments: Image Generation Quality (CIFAR-10)

Evaluated on CIFAR-10, SVHN, CelebA (32x32).

Model type	Models	FID↓
Flow+EBM	EBM-FCE	37.30
	CoopFlow (T=30)	21.16
<b>CPMLA (Ours)</b>	<b>CPMLA<sub>p</sub>rt (T=20)</b>	<b>20.85</b>
	CPMLA (T=30)	21.09
Score-Based	NCSN++	2.20
GAN	StyleGAN2-ADA	2.92

Note: Lower FID is better. CPMLA outperforms prior EBM+Flow methods. Comparison to other model classes (Score, GAN) shows EBMs becoming more competitive.



(a) CIFAR-10



(b) SVHN



(c) CelebA

# Experiments: Efficiency vs. CoopFlow (CIFAR-10)

CPMLA demonstrates superior efficiency compared to CoopFlow:

## Inference Speed & Quality:

- Achieves lower FID (20.85 vs 21.16).
- Uses fewer MCMC steps ( $T=20$  vs  $T=30$ ).
- Requires less wall-clock time (15.92s vs 16.84s / 1k images).

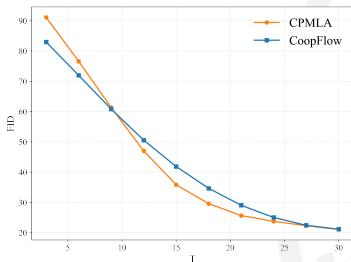


Figure: Faster FID improvement per step.

## Parameter Efficiency:

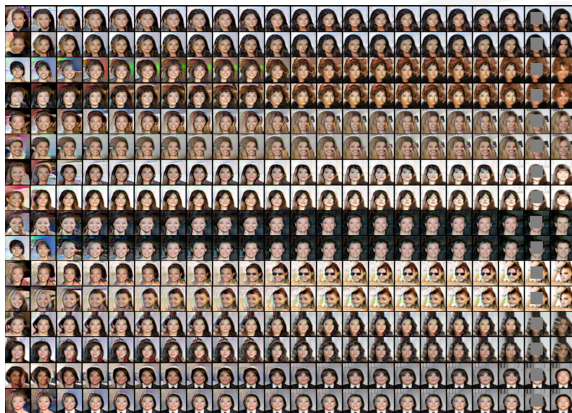
- EBM part size identical (17.13M).
- **Flow part:** CPMLA **0.26M** vs. CoopFlow **28.78M**.
- Better results with **~0.9%** flow params.

## Training Efficiency:

- Faster overall training due to memory efficiency (larger batches possible).
- **10.5h** vs 38h est. (CIFAR-10, 24GB VRAM).

# Experiments: Image Inpainting (CelebA)

Demonstrates applicability to conditional generation tasks.



**Figure:** CPMLA successfully inpaints masked regions on CelebA images over optimization iterations (left to right), compared to masked and original images (last two columns).

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# Conclusion

- Introduced **CPMLA**, a novel algorithm designed for **efficient EBM sampling** using a dynamic mirror map based on CP-Flow.
- **Key Features for Efficiency:**
  - Adapts sampling geometry to the data manifold, potentially speeding up exploration.
  - Achieves exponential convergence with vanishing bias (theoretically proven for DNNs), supporting its reliability.
- **Results:** Demonstrated significant improvements in sampling efficiency (time, parameters, training throughput) compared to related EBM methods on benchmark datasets. Showcased strong performance in image generation, reconstruction, and inpainting.
- CPMLA offers a principled and highly performant approach to EBM sampling, enhancing the practicality of EBMs for complex generative tasks.

# Thank You

For further questions or discussion, please contact:

`yangzt21@m.fudan.edu.cn`