

Exploration-Exploitation-Engagement in Multi-Armed Bandits with Abandonment

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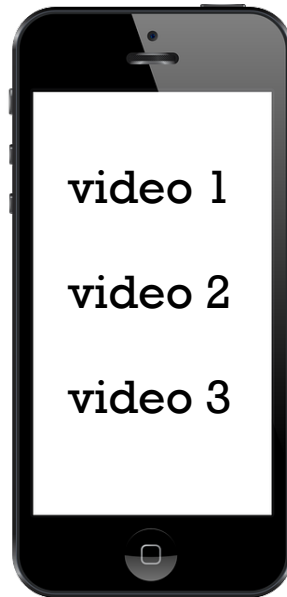
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Joint work with Prof. Xin Liu (Shanghai Tech) and my advisor Prof. Lei Ying (Michigan)

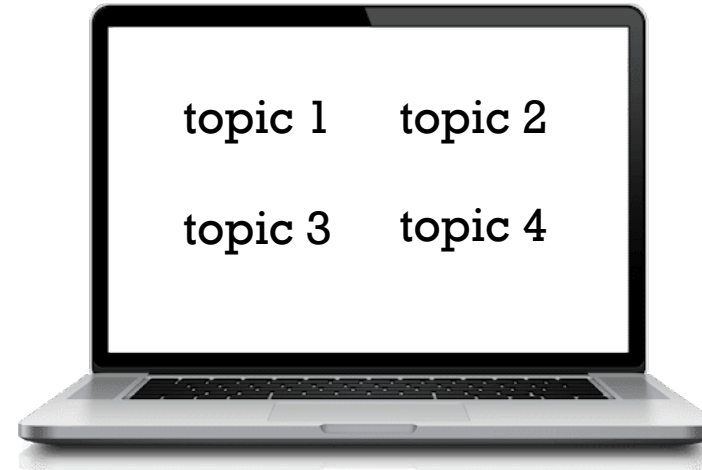


Motivation and Applications

Short video
recommendations



Content recommendations
in online education

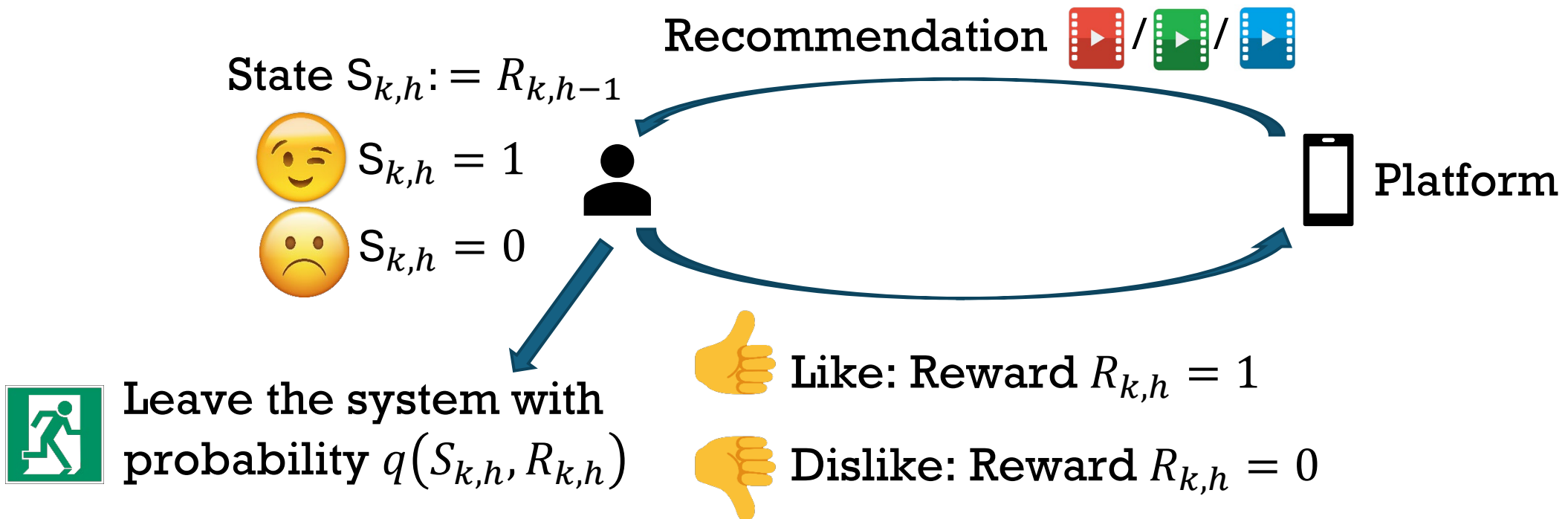


Model: Multi-Armed Bandit (MAB)

The MAB model overlooks **user abandonment**.

Exploration-Exploitation-Engagement: A Simple Model

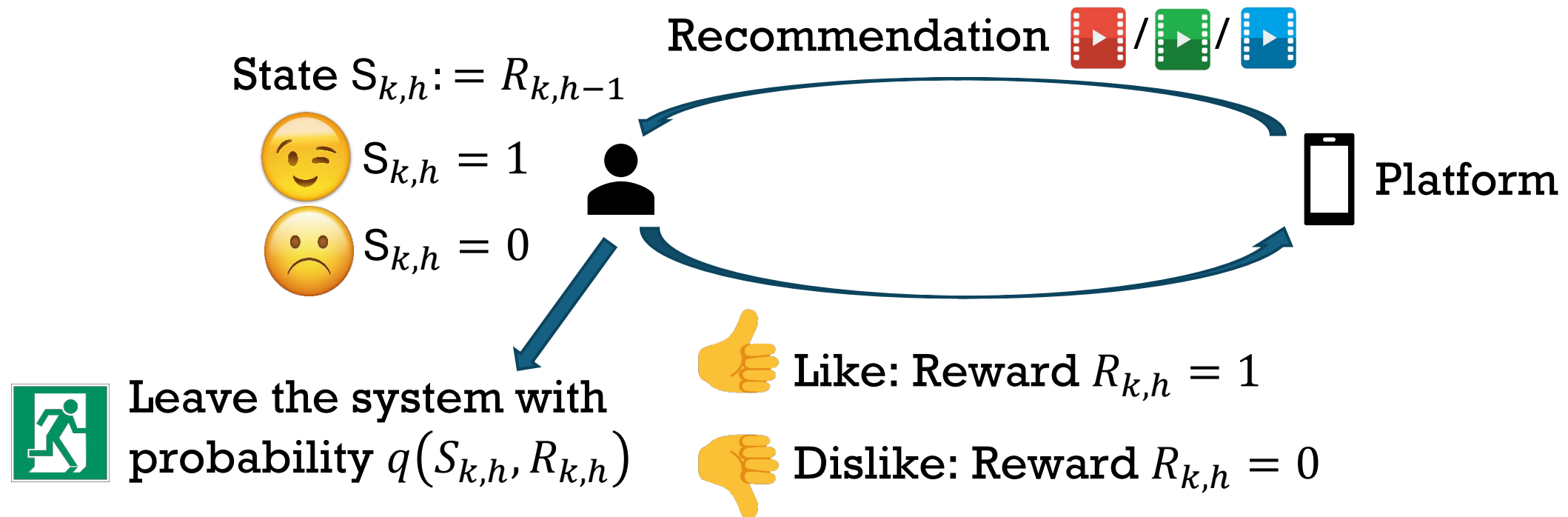
- ❑ M arms $\{a_1, a_2, \dots, a_M\}$
- ❑ Consider K episodes. State at step h of the k th episode is $S_{k,h} \in \{0, 1\}$
- ❑ Bernoulli rewards with mean $\mu(a_i)$



Assumption

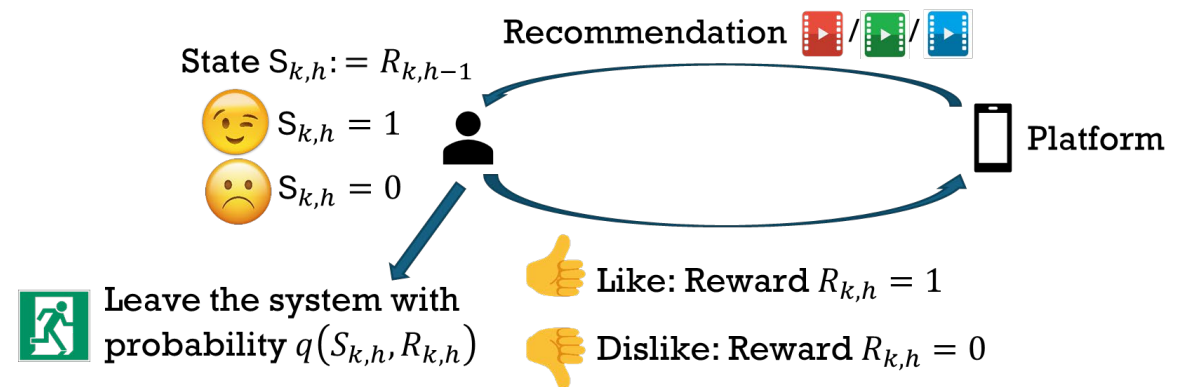
- The user is less likely to abandon the system when getting higher reward

$$q(S_{k,h}=s, R_{k,h}=r) \leq q(S_{k,h}=s', R_{k,h}=r') \text{ if } s+r > s'+r'.$$

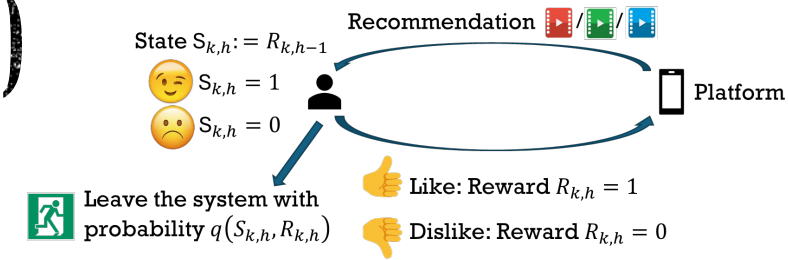


Problem Definition

- ❑ Baseline π^* : A genie-aided, optimal policy is always pulling the arm with the highest mean
- ❑ Regret for a given policy: the difference between the expected total reward achieved by the optimal policy, π^* , and that achieved by the given policy.
- ❑ Goal: minimize the regret



Upper and Lower Confidence Bound (ULCB)



- ULCB --- state-dependent bonus/penalty terms

- When state is **0**, $\tilde{\mu}_t(a) = \bar{\mu}_t(a) - \sqrt{\frac{\log t + 4 \log \log t}{2N_t(a)}}$

↑
sample mean

↑
number of times for which
arm a has been pulled

discourage exploration

- When state is **1**, $\tilde{\mu}_t(a) = \bar{\mu}_t(a) + \sqrt{\frac{\log t + 4 \log \log t}{2N_t(a)}}$

encourage exploration

- Choose arm $a \in \operatorname{argmax}_a \tilde{\mu}_t(a)$

- KL-ULCB --- use KL divergence instead of Euclidean distance.

Main Results

- Theoretically, KL-ULCB is asymptotically optimal. (number of episodes $K \rightarrow \infty$)
- Empirically, KL-ULCB performs significantly better than other algorithms.

