A Cross-Domain Benchmark for Active Learning

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Main Findings

The image domain is an outlier

Our experiments revealed a dependency of the top-performing algorithms on the data domain. While margin sampling performs very well for Tabular, Text, and Semi-Supervised Domains, it comparatively underperforms for image data. Furthermore, for images, least confident sampling performs best, while it performs way worse for other domains. This is an important finding, as the image domain - evidently and outlier - is the most researched domain for active learning. This highlights the importance of testing AL algorithms across as many domains as possible.

3-5 repetitions are not enough to produce consistent results

We computed 100 runs of our top-performing AL method on one dataset. This allows us firstly, to obtain a very strong estimation of the "true" average performance on this particular dataset and secondly, to draw subsets from this pool of 100 runs. Setting the size of our draws to α and sampling uniformly, we can approximate a cross-validation process with α repetitions. Each of these draws (blue lines) can be interpreted as a **reported result in AL literature** where the authors employed α repetitions.



Benchmark	Sampling	# Datasets	# Algorithms	Image	Text	Tabular	Synthetic	Semi-Sup.	Oracle	Repetitions
Beck et al.	Batch	4	7	1	-	-	-	-	-	-
Hu et al.	Batch	5	13	1	1	-	-	-	-	3
Zhou et al.	Batch	3	2	1	1	-	-	-	1	5
Zahn et al.	Single + Batch	35	18	-	-	1	1	-	1	10-100
Munjal et al.	Batch	2	8	1	-	-	-	-	-	3
Li et al.	Batch	5	13	1	-	-	-	1	-	-
Rauch et al.	Batch	11	5	-	1	-	-	-	-	5
Zhang et al.	Batch	6	7	1	-	-	-	-	-	2-4
Bahri et al.	Batch	69	16	-	-	1	-	-	-	2-4
Ji et al.	Batch	3	8	<i></i>						
Lueth et al.	Batch	4	5	1	-	-	-	1	-	3
Ours	Single + Batch	9(14)	11	✓	✓	✓	✓	 Image: A start of the start of	✓	50

Synthetic Datasets

Each dataset was designed to either challenge uncertainty sampling or clustering methods

Synthetic datasets allow us to measure principled shortcomings of well-known AL algorithms. Even though these shortcomings might already be known for some algorithms, they have yet to be tested systematically.



The Diverging Sine dataset is designed to be hard to solve for clustering algorithms. This dataset needs a lot of samples on the left-hand side and progressively less towards the right. The dynamic nature of the sine functions promt clustering algorithms to sample uniformly accross X and therefore oversample the right hand side.





The Honeypot dataset is designed to be hard to solve for uncertainty sampling algorithms. This dataset introduces a noisy region in dataspace where the labels are random. Uncertainty sampling algorithms will heavily oversample this noisy region without improving the classifier much, while clustering algorithms will equally sample from all three regions.

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Results for all Domains

Average rank of each algorithm over datasets and query sizes

Basing our evaluation on ranks allows us to average the performance of algorithms across different datasets and query sizes without risking a skew from different scales. We also employed a paired-t-test instead of the regular t-test and display the significances in Critical Difference Diagrams. The paired-t-test is made possible by specialized seeding in our framework.



Critical Difference Diagrams for each domain across all datasets and query sizes. Lower rank is better. A horizontal bar means that a group of algorithms is not significantly different, based on the paired-t-test.

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