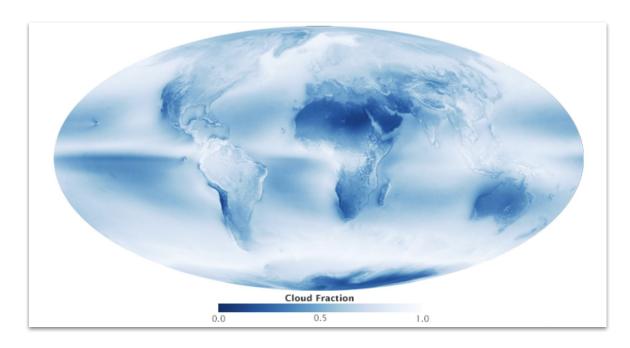


Hangyu Zhou^{1*}, Chia Hsiang Kao^{1*}, Cheng Perng Phoo¹, Utkarsh Mall², Bharath Hariharan¹, Kavita Bala¹

¹Computer Science, Cornell University

² Computer Science, Columbia University

General Problem Setup



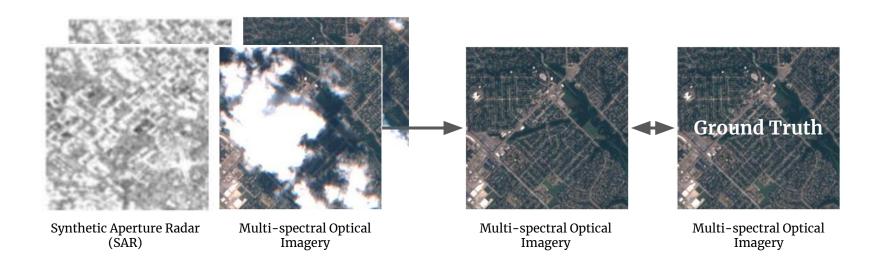
Remote-sensing imagery is promising for Earth observation and environmental monitoring.

But ...

70% of land areas are not completely cloud-free

The averaged cloud fraction over land is 55%

Cloud Removal



Problems with Existing Datasets and Benchmarks

1. **Small** Scale

a. Cannot capture the rich spatial-temporal variations on Earth.

2. **Biased** in Land Cover and Cloud Percentage

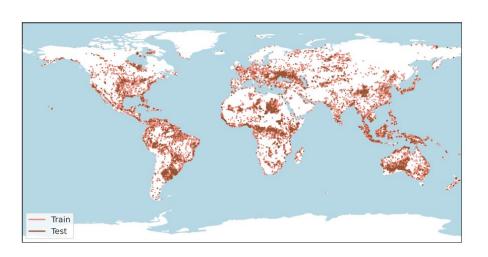
- a. No balancing on land cover distribution.
- b. Some only consider scenarios with cloud coverage < 30%.

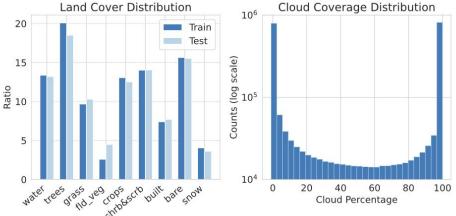
3. **Ill-defined** due to Temporal misalignment

a. In some cases, the input and target (GT) satellite images were months apart.

AllClear Highlights

Key Features: 1) Large-scale (largest to-date); 2) sufficient sampling for all land cover types; 3) no filtering on cloud coverage distribution; 4) small temporal misalignment; 5) stratified evaluation.





SoTA Cloud Removal Models Fail on AllClear Benchmark

Model	Training Dataset	PSNR (↑)	SSIM (†)	SAM (↓)	MAE (\downarrow)
Least Cloudy Mosaicing	-	28.864 29.824	0.836 0.754	<u>6.982</u> 23.58	0.078 0.045
UnCRtainTS [Ebel et al., 2023] U-TILISE [Stucker et al., 2023] CTGAN [Huang and Wu, 2022]	SEN12MS-CR-TS SEN12MS-CR-TS Sen2_MTC	29.009 24.660 27.783	0.898 0.807 0.840	5.972 7.765 8.800	0.039 0.083 0.041
PMAA [Zou et al., 2023a]	STGAN Sen2_MTC	12.455 24.328	0.460 0.768	8.072 8.680	0.240 0.078
DiffCR [Zou et al., 2023b]	STGAN Sen2_MTC	17.998 25.220	0.642 0.744	9.512 9.382	0.117 0.060

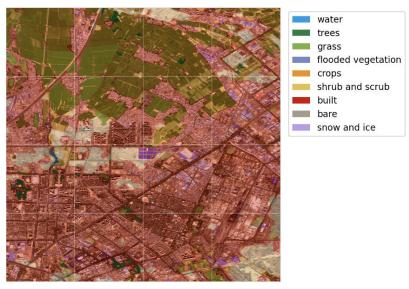
SoTA Model Benefits from Scaling up

Fraction of Data	# data point	PSNR (↑)	SSIM (↑)	SAM (↓)	MAE (↓)
1%	2,786	27.035	0.898	5.972	0.039
3.4%	10,167	28.474	0.906	6.373	0.036
10%	27,861	32.997	0.923	6.038	0.023
100%	278,613	33.868	0.936	5.232	0.021

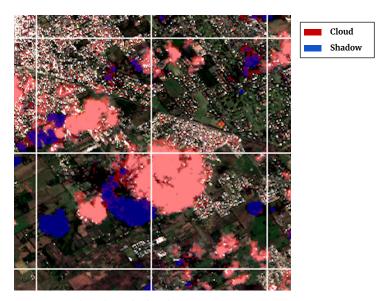
SoTA Model Benefits from Longer Time Sequence Inputs

# Consecutive Frame as Input	PSNR (↑)	SSIM (↑)	SAM (↓)	MAE (↓)
3	28.474	0.906	6.373	0.036
12	30.399	0.919	5.920	0.028

Stratified Evaluation: Land Cover and Cloud Coverage

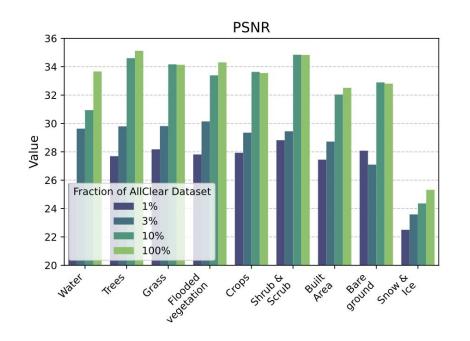


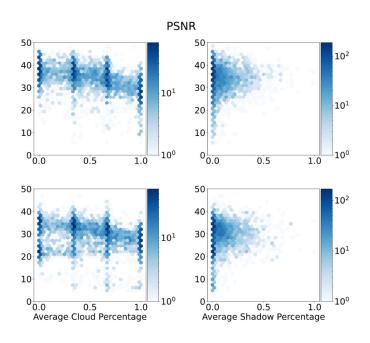
Land Use / Land Cover (LULC) Maps (Source: Dynamic World V1)

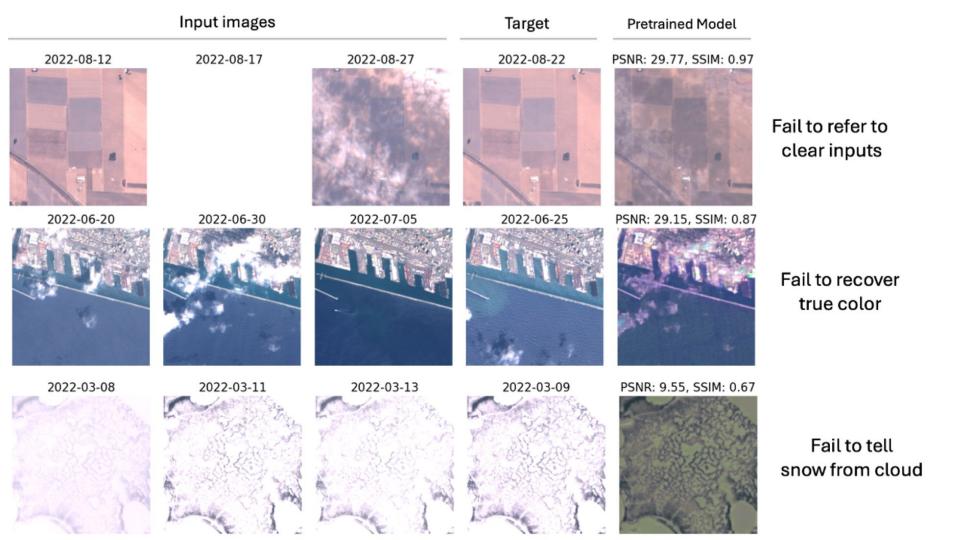


Cloud and Shadow Masks (Source: s2cloudless)

Stratified Evaluation: Land Cover and Cloud Coverage







Model trained Model trained Input images Target on 10% AllClear on full AllClear 2022-07-21 2022-07-31 2022-08-05 2022-07-26 PSNR: 28.66, SSIM: 0.95 PSNR: 38.56, SSIM: 0.98 2022-01-06 2022-01-11 2022-01-21 2022-01-16 PSNR: 27.77, SSIM: 0.93 PSNR: 34.53, SSIM: 0.97 2022-07-21 2022-07-31 2022-08-05 2022-07-26 PSNR: 34.89, SSIM: 0.98 PSNR: 29.05, SSIM: 0.96







Thank you!

Acknowledgements: This research was supported by the National Science Foundation under grant IIS-2144117 and IIS-2403015.



https://allclear.cs.cornell.edu/