

Aligning embeddings and geometric random graphs

The Procrustes-Wasserstein problem

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The Procrustes-Wasserstein problem



Mathieu Even,
Inria Montpellier



Luca Ganassali,
Paris Saclay



Jakob Maier,
Inria Paris

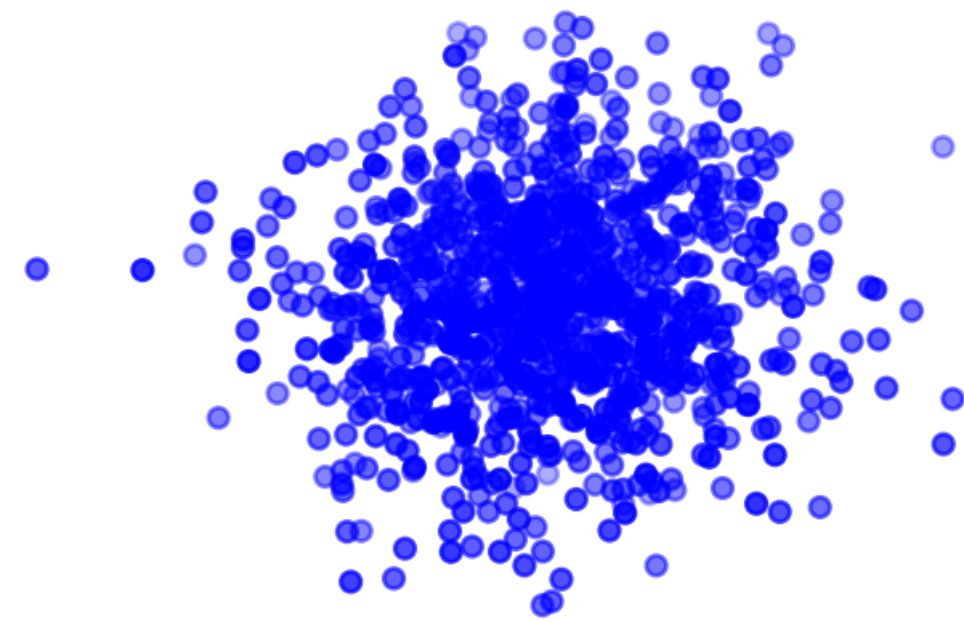


Laurent Massoulié,
Inria Paris

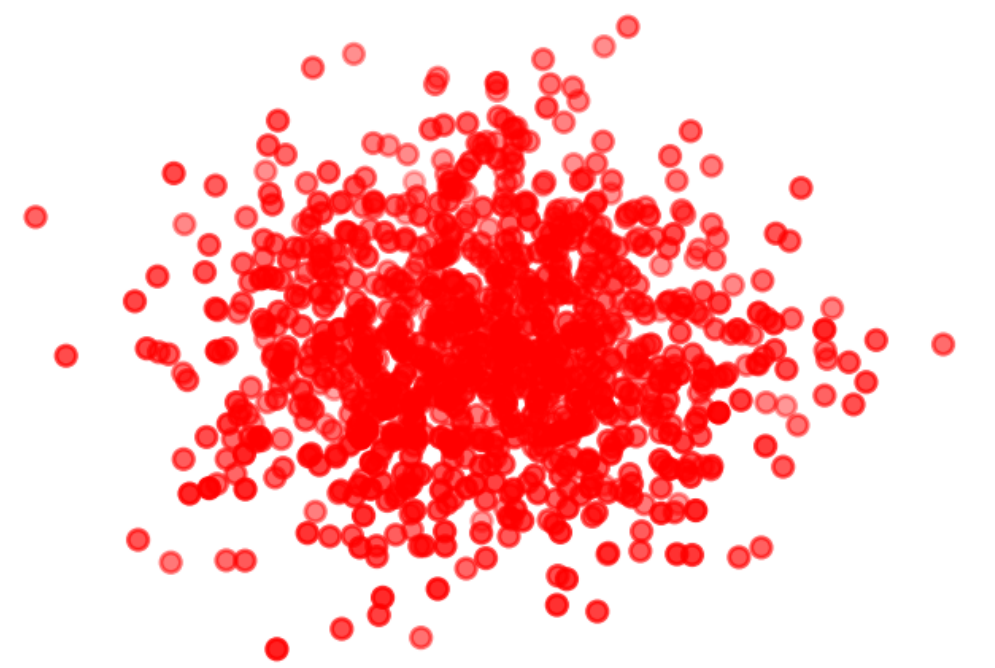
Aligning embeddings

Which x_i corresponds to which y_j ?

\implies find a permutation $\pi \in \mathcal{S}_n$ with $\pi(i) = j$



$$\mathcal{X} = \{x_1, \dots, x_n\} \subset \mathbb{R}^d$$



$$\mathcal{Y} = \{y_1, \dots, y_n\} \subset \mathbb{R}^d$$

Applications:

- Embeddings of different LLMs
- 3D object analysis

If the embeddings are rotation-invariant?

\implies find an orthogonal transformation

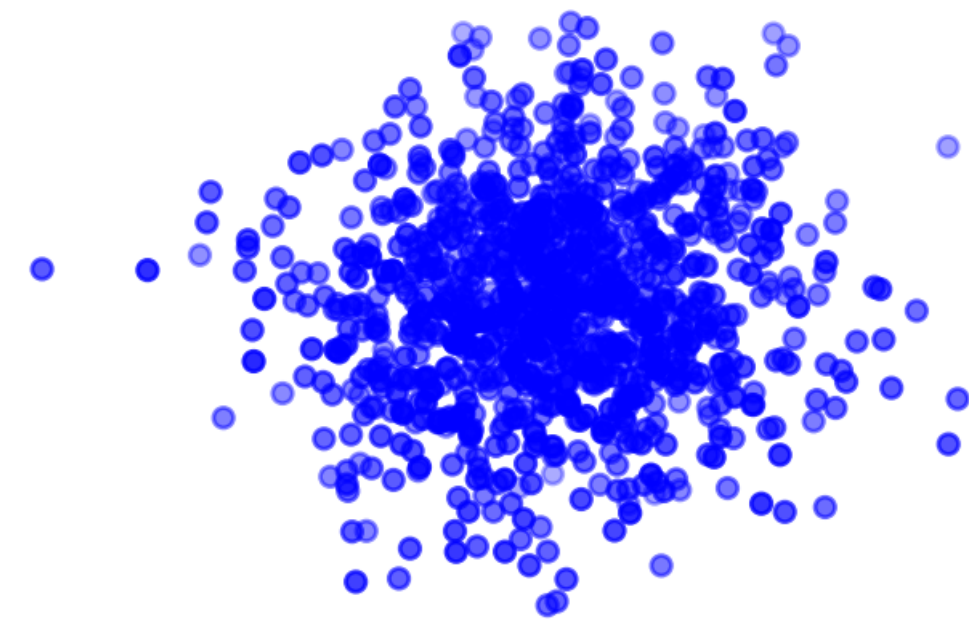
$$Q \in \mathcal{O}(d) \text{ with } Qx_i = y_j$$

Aligning embeddings

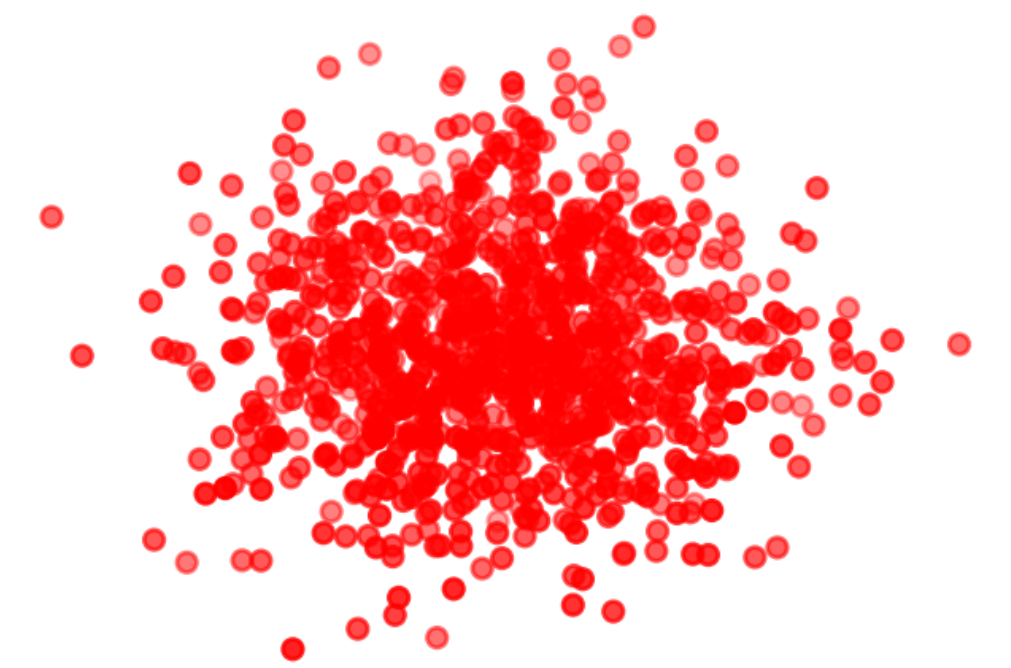
Goal:

Simultaneously find optimal π and Q :

$$\min_{\substack{\pi \in \mathcal{S}_n \\ Q \in \mathcal{O}_d}} \sum_{i=1}^n \|Qx_i - y_{\pi(i)}\|$$



$$\mathcal{X} = \{x_1, \dots, x_n\} \subset \mathbb{R}^d$$



$$\mathcal{Y} = \{y_1, \dots, y_n\} \subset \mathbb{R}^d$$

Algorithm idea 1:
Find initial π , then Ping-Pong

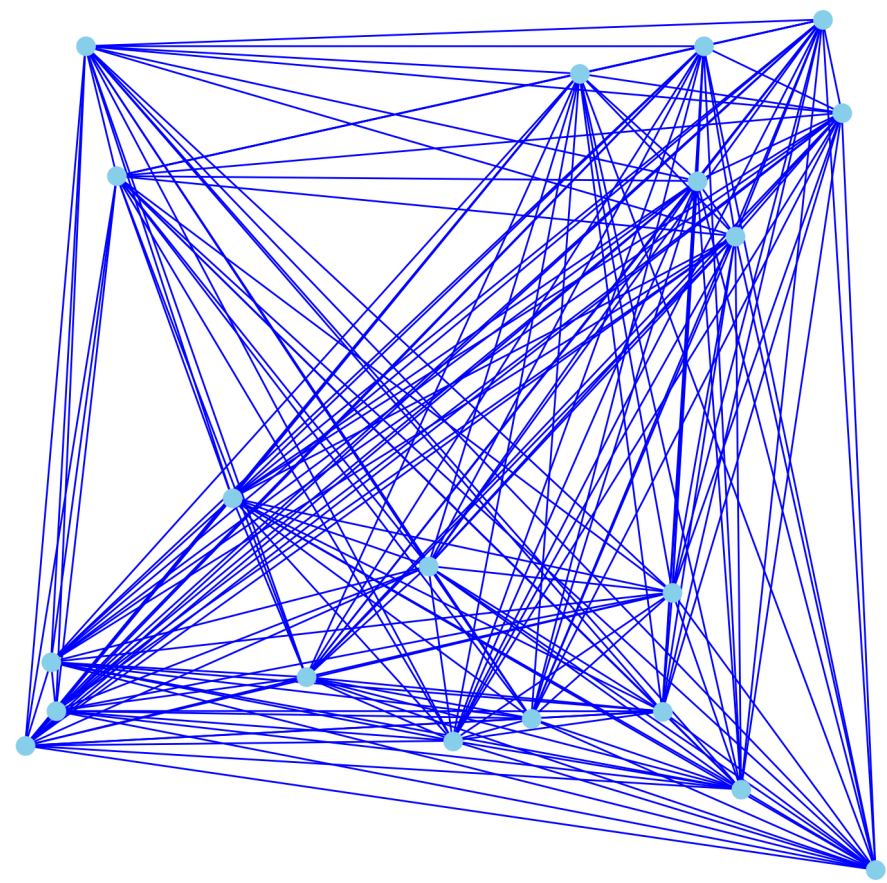
Easy if π is known:

Finding Q requires a single SVD.

Easy if Q is known:

Finding π is the LAP, solved in $\mathcal{O}(n^3)$

Aligning random geometric graphs



Graph A, weight matrix

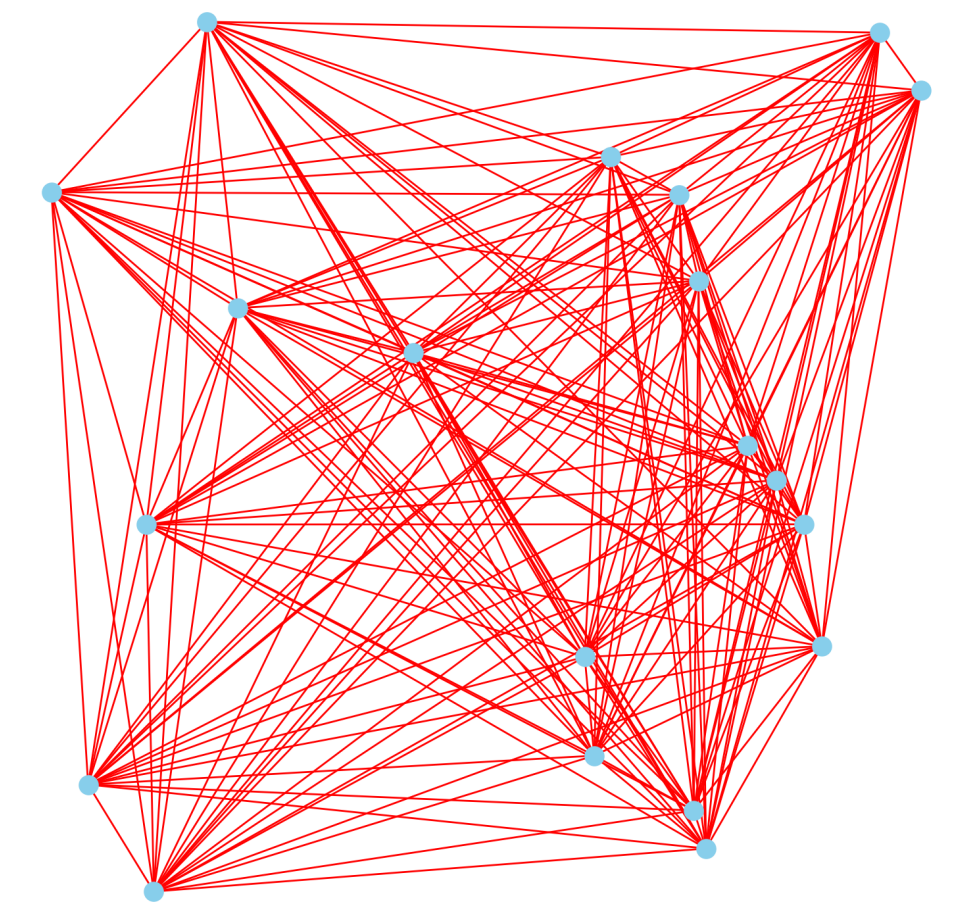
$$A_{ij} = \langle x_i, x_j \rangle$$

invariant under
orthogonal transformation

Goal:

Find the optimal node permutation to
conserve edge weights:

$$\min_{\pi \in \mathcal{S}_n} \sum_{i,j=1}^n |A_{ij} - B_{\pi(i)\pi(j)}|^2$$



Graph B, weight matrix:

$$B_{ij} = \langle y_i, y_j \rangle$$

Algorithm idea 2:

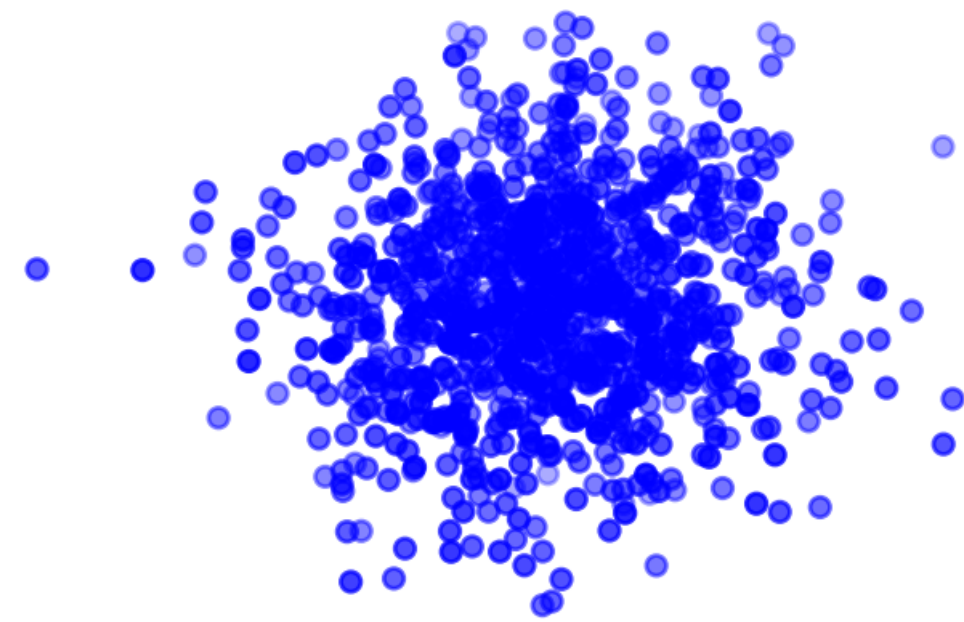
Initialize Ping-Pong with doubly
stochastic approximation of π

Stochastic setting

Goal: retrieve π^\star and Q^\star

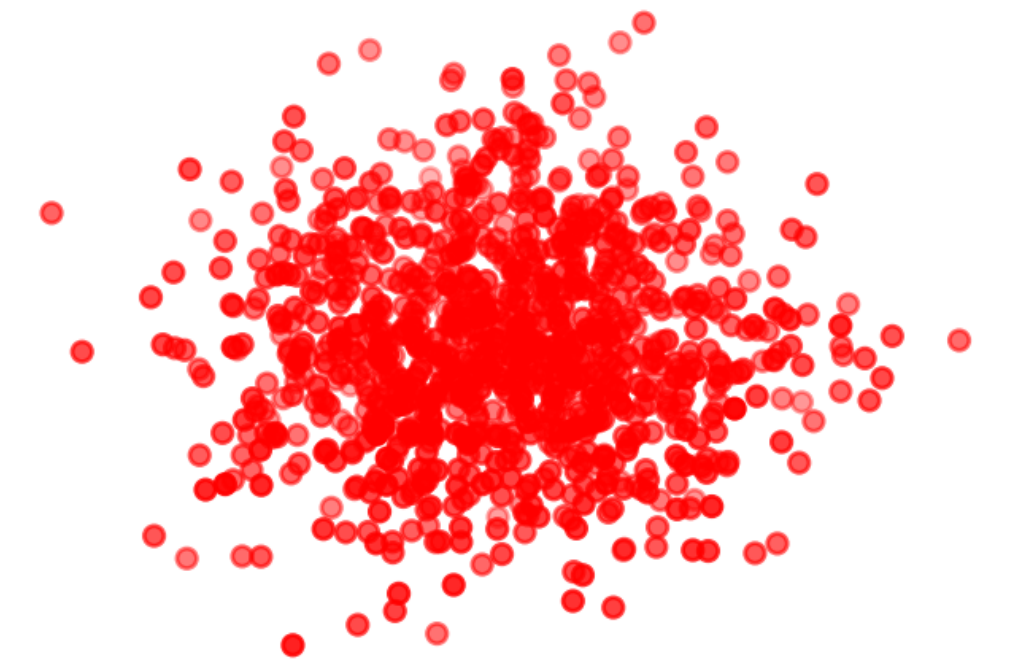
The MLE estimator of these quantities is

$$\hat{\pi}, \hat{Q} \in \arg \min_{\substack{\pi \in \mathcal{S}_n \\ Q \in \mathcal{O}_d}} \sum_{i=1}^n \|Qx_i - y_{\pi(i)}\|$$



$$\mathcal{X} = \{x_1, \dots, x_n\} \subset \mathbb{R}^d$$

$$x_i \sim \mathcal{N}(0, I_d)$$



$$\mathcal{Y} = \{y_1, \dots, y_n\} \subset \mathbb{R}^d$$

$$y_{\pi^\star(i)} = Q^\star x_i + \mathcal{N}(0, \sigma^2)$$

Performance metrics:

$$\text{overlap}(\hat{\pi}, \pi^\star) = \frac{1}{n} \left| \{i : \hat{\pi}(i) = \pi^\star(i)\} \right|$$

$$c^2(\hat{\pi}, \pi^\star) = \frac{1}{n} \sum_{i=1}^n \|x_{\hat{\pi}(i)} - x_{\pi^\star(i)}\|^2$$

L^2 transport cost

Informational results

$$x_i \sim \mathcal{N}(0, I_d)$$

$$y_{\pi^\star(i)} = Q^\star x_i + \mathcal{N}(0, \sigma^2)$$

Low dimension $d \ll \log(n)$

High dimension $d \gg \log(n)$

Result from (Wang et al., 2024):

$$\text{overlap}(\hat{\pi}, \pi^\star) \rightarrow 1 \text{ requires } \sigma \ll \frac{1}{n^{\frac{1}{d}}}.$$

Our result:

$$c^2(\hat{\pi}, \pi^\star) \in o(d) \text{ requires only } \sigma \ll \frac{1}{\sqrt{d}}.$$

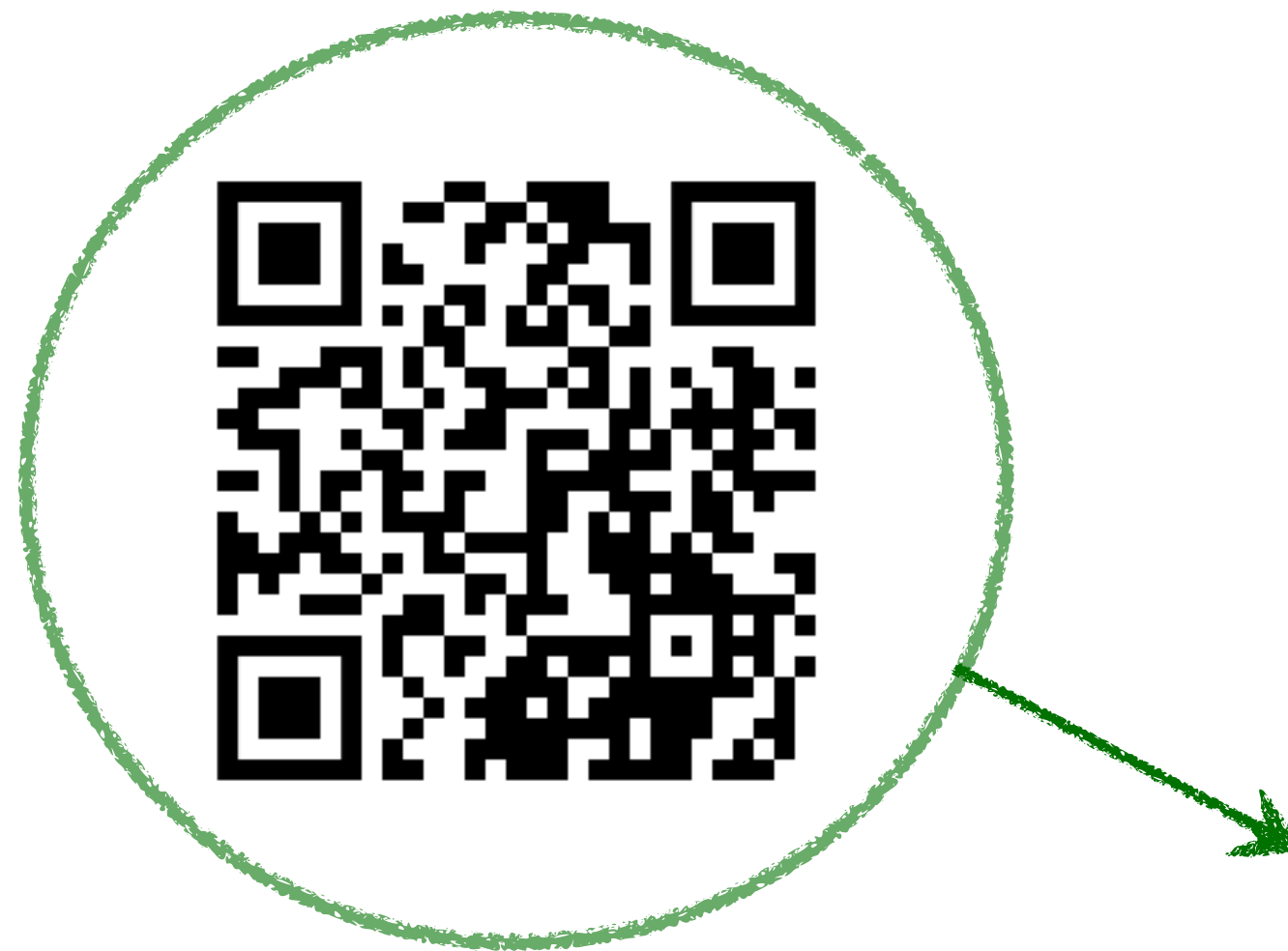
Our result: If $\sigma \rightarrow 0$, then

$$\text{overlap}(\hat{\pi}, \pi^\star) \rightarrow 1$$

and

$$c^2(\hat{\pi}, \pi^\star) \in o(d).$$

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Take a peak!