Leveraging Hallucinations to Reduce Manual Prompt Dependency in Promptable Segmentation

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NEURAL INFORMATION PROCESSING SYSTEMS

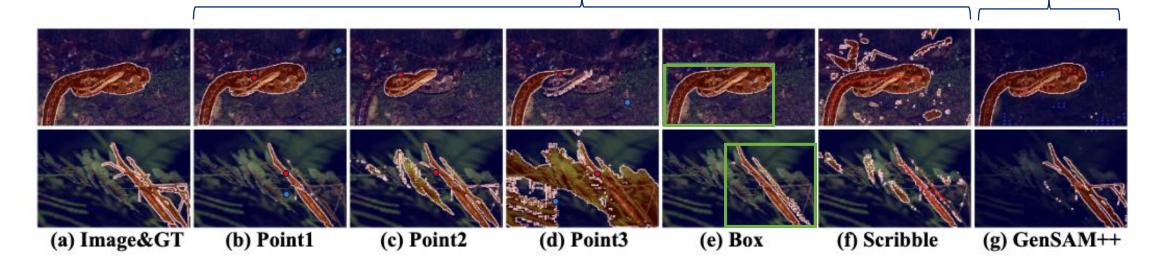






• In SAM, manual point and scribble prompts suffer from **ambiguity in interpreting targets and is sensitive to minor spatial variations**.

instance-specific prompts



Segmentation results using different prompts in SAM with various approaches.

[1] Hu J, Lin J, Gong S, et al. Relax Image-Specific Prompt Requirement in SAM: A Single Generic Prompt for Segmenting Camouflaged Objects[C]//Proceedings of the AAAI Conference on Artificial Intelligence. 2024, 38(11): 12511-12518.

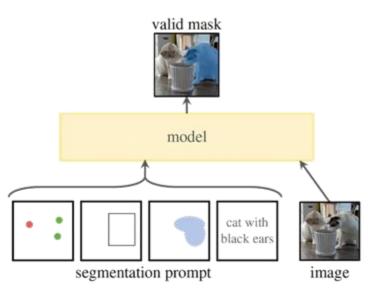
generic prompts

[•] Limitation of current promptable segmentation

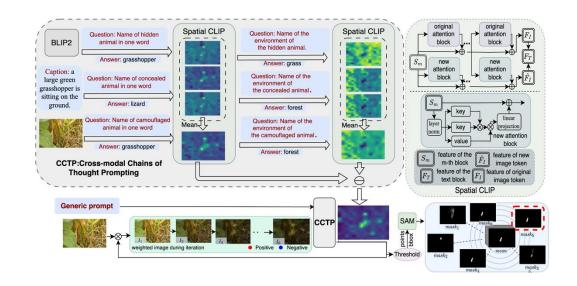
- Segment Anything Model (SAM)
 - Learning from 1.1 billion prompt-mask pairs
 - Better generalization ability

NEURAL INFORMATION PROCESSING SYSTEMS

• Relies on Manual Instance-Specific Prompt

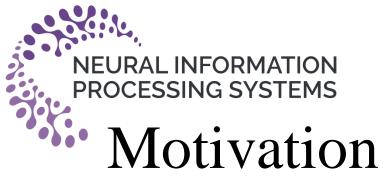


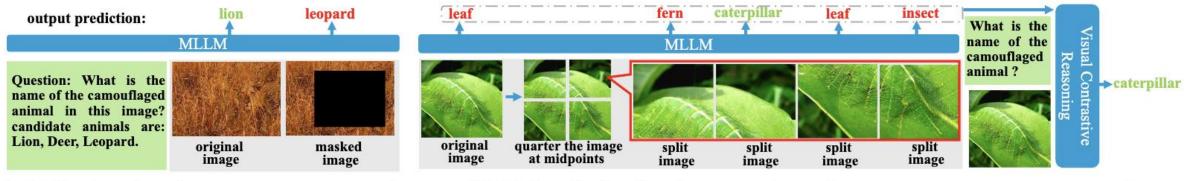
- GenSAM
 - Only need one task-generic prompt for each task
 - Can be generalized to more tasks
 - Generated instance-specific prompts are inaccurate



[1] Kirillov, Alexander, et al. Segment anything. arXiv:2304.02643 (2023).

[2] Hu J, Lin J, Gong S, et al. Relax Image-Specific Prompt Requirement in SAM: A Single Generic Prompt for Segmenting Camouflaged Objects[C]//Proceedings of the AAAI Conference on Artificial Intelligence. 2024, 38(11): 12511-12518.





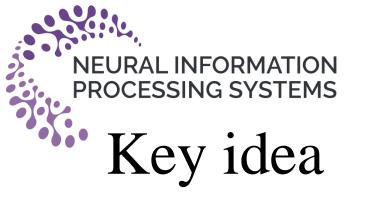
(a) Hallucination by co-occurrence prior.

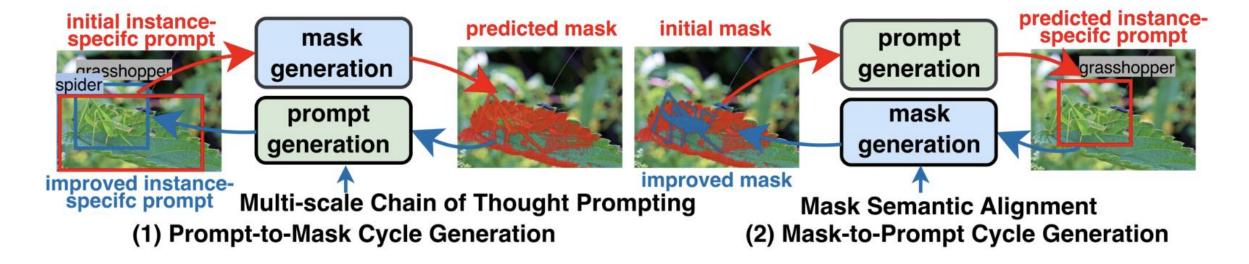
(b) Using hallucinations can benefit accuracte prompt generation.

(a) During MLLM pretraining, leopards often co-occur with grass. If the lion is masked, the model incorrectly identifies it as a leopard based on the grass.

(b) Directly inputting the image into MLLM causes the hidden caterpillar being incorrectly predicted as a leaf. Splitting the image results in interested objects being incomplete or absent, prompting MLLM to induce hallucinations and utilize prior knowledge to predict potential task-related objects within the image.

Our visual contrastive reasoning eliminates the hallucinations and validates the gathered predictions, aiding in the accurate identification of the caterpillar.





An overview of ProMac: Masks created iteratively by the mask generator guide the prompt generator to jointly improve instance-specific prompts and visual masking in segmentation.



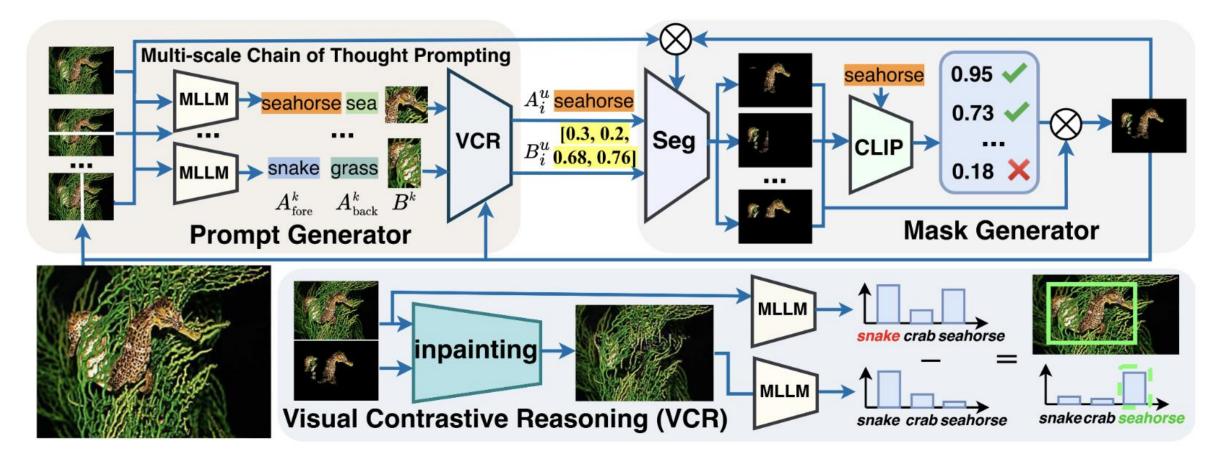




Table 1: Results on Camouflaged Object Detection (COD) under different settings. Best are in **bold**.

	Camouflaged Object Detection													
Methods	Venue	1		EON [CAM	0 [30]		COD10K [14]				
	venue	$M\downarrow$	$F_{eta}\uparrow$	$E_{\phi}\uparrow$	$S_{lpha}\uparrow$	$M\downarrow$	$F_{eta}\uparrow$	$E_{\phi}\uparrow$	$S_{lpha}\uparrow$	$M\downarrow$	$F_{eta}\uparrow$	$E_{\phi}\uparrow$	$S_{lpha}\uparrow$	
Scribble Supervision Setting														
WSSA[62]	CVPR20	0.067	0.692	0.860	0.782	0.118	0.615	0.786	0.696	0.071	0.536	0.770	0.684	
SCWS[60]	AAAI21	0.053	0.758	0.881	0.792	0.102	0.658	0.795	0.713	0.055	0.602	0.805	0.710	
TEL[62]	CVPR22	0.073	0.708	0.827	0.785	0.104	0.681	0.797	0.717	0.057	0.633	0.826	0.724	
SCOD[<u>17]</u>	AAAI23	0.046	0.791	0.897	0.818	0.092	0.709	0.815	0.735	0.049	0.637	0.832	0.733	
SAM-S[29]	ICCV23	0.076	0.729	0.820	0.650	0.105	0.682	0.774	0.731	0.046	0.695	0.828	0.772	
WS-SAM[16]	NeurlPS23	0.046	0.777	0.897	0.824	0.092	0.742	0.818	0.759	0.038	0.719	0.878	0.803	
Point Supervision Setting														
WSSA[62]	CVPR20	0.105	0.660	0.712	0.711	0.148	0.607	0.652	0.649	0.087	0.509	0.733	0.642	
SCWS[60]	AAAI21	0.097	0.684	0.739	0.714	0.142	0.624	0.672	0.687	0.082	0.593	0.777	0.738	
TEL[62]	CVPR22	0.094	0.712	0.751	0.746	0.133	0.662	0.674	0.645	0.063	0.623	0.803	0.727	
SCOD[17]	AAAI23	0.092	0.688	0.746	0.725	0.137	0.629	0.688	0.663	0.060	0.607	0.802	0.711	
SAM[29]	ICCV23	0.207	0.595	0.647	0.635	0.160	0.597	0.639	0.643	0.093	0.673	0.737	0.730	
SAM-P[29]	ICCV23	0.101	0.696	0.745	0.697	0.123	0.649	0.693	0.677	0.069	0.694	0.796	0.765	
WS-SAM[16]	NeurlPS23	0.056	0.767	0.868	0.805	0.102	0.703	0.757	0.718	0.039	0.698	0.856	0.790	
			Tas	k-Gene	ric Pron	npt Setti	ing							
CLIP_Surgey+SAM	Arxiv23	0.147	0.606	0.741	0.689	0.189	0.520	0.692	0.612	0.173	0.488	0.698	0.629	
GPT4V+SAM [43, 29]	Arxiv23	0.180	0.557	0.710	0.637	0.206	0.466	0.666	0.573	0.187	0.448	0.672	0.601	
LLaVA1.5+SAM [37, 29]	NeurlPS23	0.168	0.561	0.718	0.666	0.314	0.401	0.585	0.501	0.170	0.530	0.728	0.662	
X-Decoder [69]	CVPR23	0.124	0.654	0.748	0.716	0.104	0.628	0.745	0.709	0.171	0.556	0.705	0.652	
SEEM [71]	NeurIPS23	0.094	0.011	0.307	0.454	0.192	0.023	0.315	0.404	0.143	0.001	0.280	0.425	
GroundingSAM [29, 38]	ICCV23	0.122	0.662	0.776	0.744	0.157	0.656	0.753	0.707	0.085	0.670	0.813	0.764	
GenŠAM [21]	AAAI24	0.073	0.696	0.806	0.774	0.106	0.669	0.798	0.729	0.058	0.695	0.843	0.783	
ProMaC	Ours	0.044	0.790	0.899	0.833	0.090	0.725	0.846	0.767	0.042	0.716	0.876	0.805	

7



Polyp Image Segmentation Skin Lesion Segmentation Methods Kvasir 25 Venue CVC-ColonDB 51 ISIC 10 $M\downarrow$ $F_{\beta} \uparrow$ E_{ϕ} S_{α} 1 $M\downarrow$ F_{β} 1 E_{ϕ} S_{α} 1 $M\downarrow$ F_{β} 1 E_{ϕ} $S_{\alpha} \uparrow$ 0.578 0.242 0.614 0.128 0.236 0.253 0.514 GPT4V+SAM [43, 29] Arxiv23 0.051 0.246 0.387 0.366 0.334 LLaVA1.5+SAM [37, 29] NeruIPS23 0.491 0.194 0.355 0.357 0.479 0.293 0.400 0.403 0.369 0.473 0.497 0.477 0.327 0.331 0.449 0.202 0.371 0.384 0.338 X-Decoder [69] CVPR23 0.462 0.095 0.315 0.127 0.407 0.570 0.085 0.280 0.284 0.520 0.215 0.367 SEEM [71] NeruIPS23 0.339 0.362 0.250 0.002 0.280 GroundingSAM [29, 38] ICCV23 0.711 0.071 0.195 0.206 0.387 0.353 0.521 0.468 0.301 0.348 0.247 0.533 GenŠAM [21] 0.172 AAAI24 0.244 0.059 0.494 0.379 0.210 0.619 0.487 0.171 0.699 0.744 0.678 ProMaC 0.176 0.243 0.583 0.530 0.166 0.394 0.726 0.573 0.168 0.717 0.689 Ours 0.755

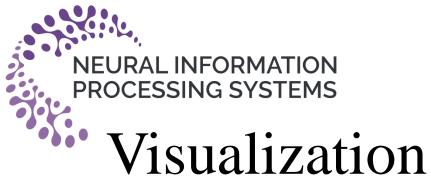
Table 2: Results for Medical Image Segmentation (MIS) under task-generic prompt setting.

Table 3: Result on Transparent Object Segmentation and Open-Vocabulary Segmentation Tasks.

(a) Transparent Object Segmentation.

(b) Open-vocabulary Segmentation.

Methods	GSD [34]	Trans10K-hard [56]	Methods	Venue	Seg. Anno.	Image-Text pairs	VOC	Context	Object
Wethous	$M \downarrow F_{\beta} \uparrow E_{\phi} \uparrow S_{\alpha}$	$\uparrow M \downarrow F_{\beta} \uparrow E_{\phi} \uparrow S_{\alpha} \uparrow$	Wiethous	Venue	beg. Anno.	inage-rext pairs	mIoU ↑	mIoU↑	mIoU↑
GPT4V+SAM [43, 29]	0.312 0.104 0.392 0.30	3 0.288 0.199 0.607 0.512	MaskCLIP[67]	ECCV22	-	-	38.8	23.6	20.6
LLaVA1.5+SAM [37, 29]	0.197 0.202 0.545 0.43	3 0.272 0.167 0.621 0.555	TCL 6	CVPR23	-	CC3M [48], CC12M [7]	51.2	24.3	30.4
X-Decoder [69]	0.191 0.240 0.643 0.43	0 0.568 0.611 0.218 0.280	GroupViT [57]	CVPR22	-	CC12M [7], YFCC14M [53]	52.3	22.4	-
SEEM [71]	0.184 0.224 0.573 0.47	9 0.557 0.501 0.013 0.256	ViewCo 46	ICLR23	-	CC12M [7], YFCC14M [53]	52.4	23.0	23.5
GroundingSAM [29, 38]	0.168 0.230 0.572 0.48	3 0.436 0.415 0.047 0.424	SegCLIP [39]	ICML23	COCO [35]	CC [48]	52.6	24.7	26.5
GenSAM [21]	0.155 0.394 0.700 0.5	9 0.263 0.489 0.612 0.536	OVSegmentor 58	CVPR23	-	CC12M [7]	53.8	20.4	25.1
ProMaC	0.147 0.409 0.723 0.50	9 0.251 0.509 0.654 0.557	ProMaC	Ours	-	-	59.3	30.7	25.2



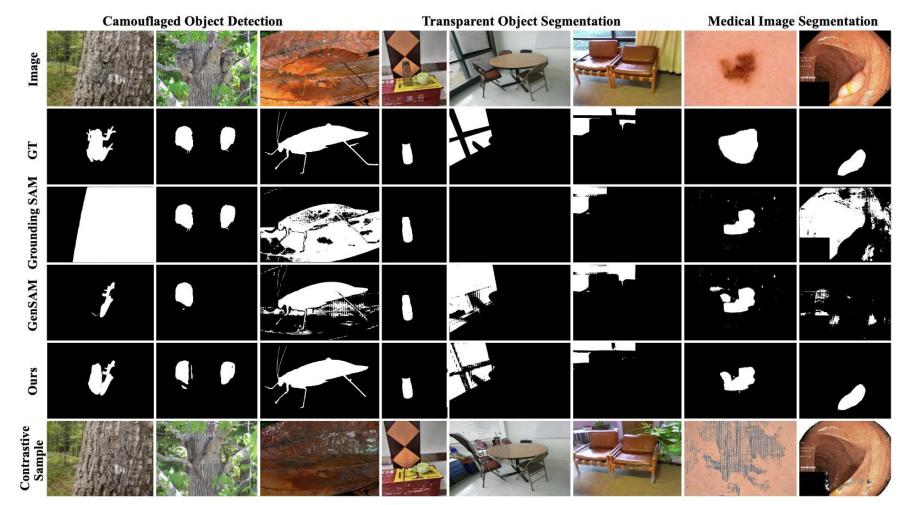


Figure 4: Visualization of various segmentation methods among various segmentation tasks.

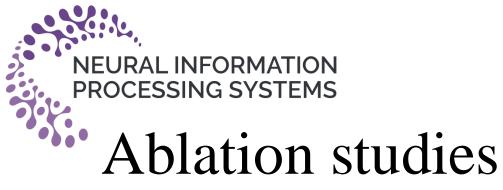


Table 4: Ablation Study on COD and MIS Tasks

_	Method's Variants						IAMEL	EON [50	CVC-ColobNB 51					
Ν	ИСоТ	IVP	ITP	VCR	MSA	$M\downarrow$	$F_{\beta}\uparrow$	$E_{\phi} \uparrow$		$M\downarrow$	$F_{\beta}\uparrow$	$E_{\phi} \uparrow$	$S_{lpha}\uparrow$		
		\checkmark	\checkmark	\checkmark	\checkmark	0.052		0.885							
	\checkmark		\checkmark	\checkmark	\checkmark			0.833							
	\checkmark	\checkmark		\checkmark	\checkmark	0.089	0.685	0.823	0.756	0.177	0.233	0.556	0.524		
	\checkmark	\checkmark	\checkmark		\checkmark	0.061	0.769	0.893	0.815	0.311	0.152	0.460	0.424		
	\checkmark	\checkmark	\checkmark	\checkmark		0.054	0.740	0.884	0.798	0.156	0.220	0.565	0.517		
	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	0.044	0.790	0.899	0.833	0.176	0.243	0.583	0.530		

Table 6: Parameter ablation study on COD10K [14].

(a) Number of iteration I .							(b) Image preprocess strategy.						(c) Visual marker strategy.					
T	cos↑	IoU↑	$M\downarrow$	$F_{\beta}\uparrow$	$E_{\phi}\uparrow$	$S_{lpha}\uparrow$	Scale	$M\downarrow$	$F_{eta}\uparrow$	$E_{\phi}\uparrow$	$S_{lpha}\uparrow$	strategy	$M\downarrow$	$F_{\beta}\uparrow$	$E_{\phi}\uparrow$	$S_{lpha}\uparrow$		
1	0.864	0.563	0.080	0.626	0.818	0.765	Original	0.075	0.535	0.750	0.662	None	0.058	0.690	0.855	0.789		
23	$0.876 \\ 0.879$	$0.589 \\ 0.593$	$0.050 \\ 0.045$	$0.683 \\ 0.702$	$0.859 \\ 0.869$	$0.796 \\ 0.802$	Havel	0.069	0.579	0.775	0.689	Bbox	0.065	0.682	0.836	0.766		
4	0.879	0.601	0.043	0.702	0.809	0.802	Quarters	0.087	0.423	0.673	0.586							
5	0.881	0.602	0.041	0.718	0.875	0.804	Original+Havel	0.042	0.714	0.875	0.804	VCD	0.047	0.705	0.863	0.793		
6	0.882	0.599	0.041	0.721	0.876	0.803	Original +Havel+Quarters	0.049	0.702	0.867	0.796	Ours	0.042	0.714	0.875	0.804		



- We explore how to utilize hallucinations as prior knowledge to assist task-generic promptable segmentation.
- We applied our approach in camouflaged animal detection, medical image segmentation, transparent object detection tasks, achieving promising results.

Code link: https://github.com/lwpyh/ProMaC_code



Thank you!