

Online Learning with Sublinear Best-Action Queries

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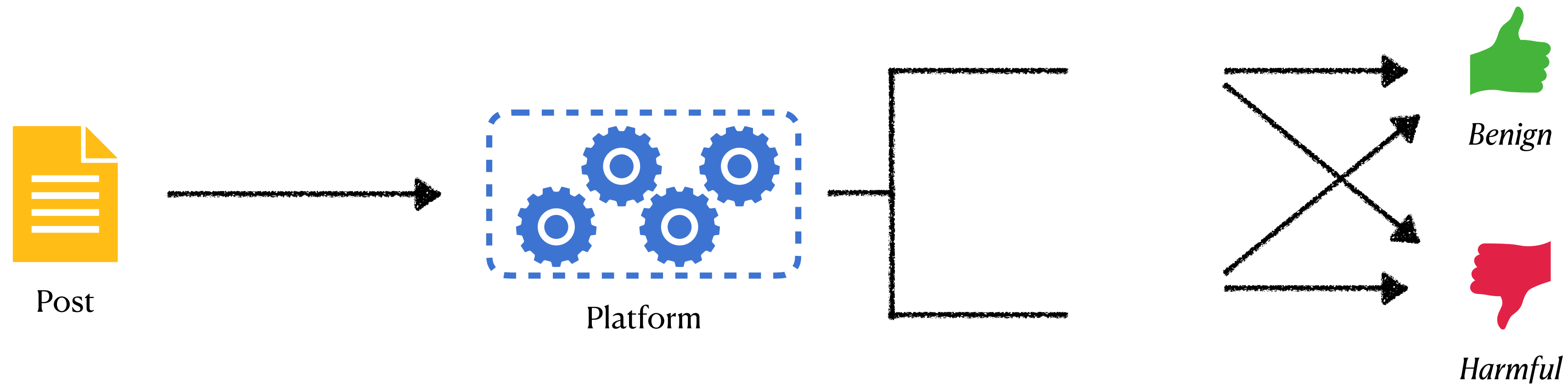
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Example: Online Platforms

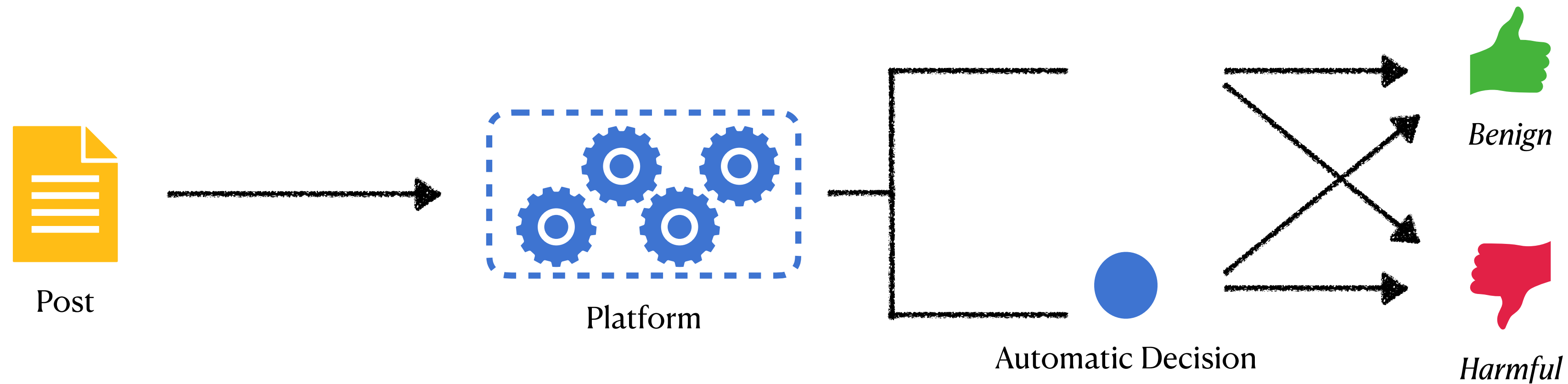
How to continuously moderate posted content



- Posts come one after the other and platform has to flag content as harmful or not

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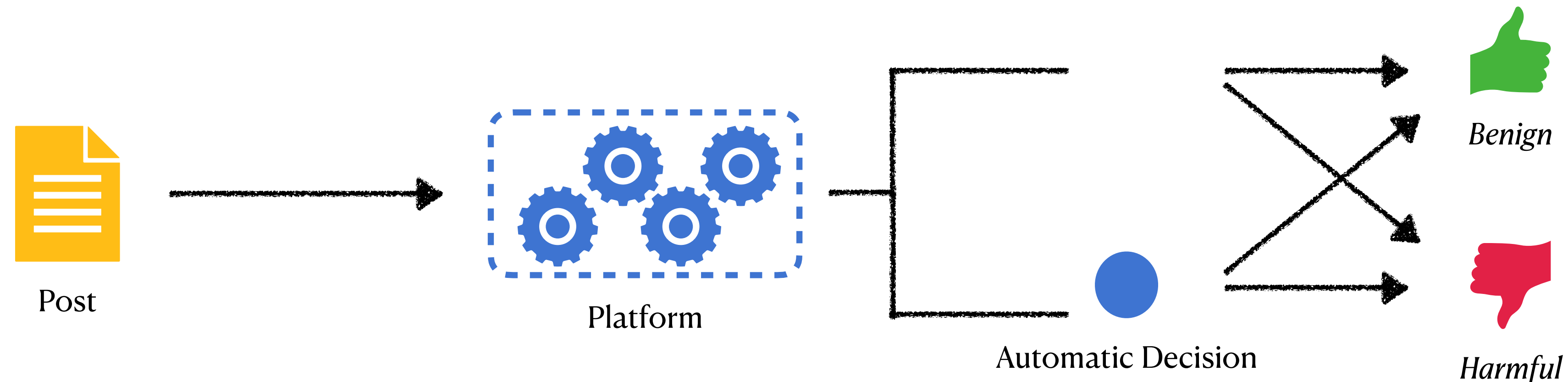
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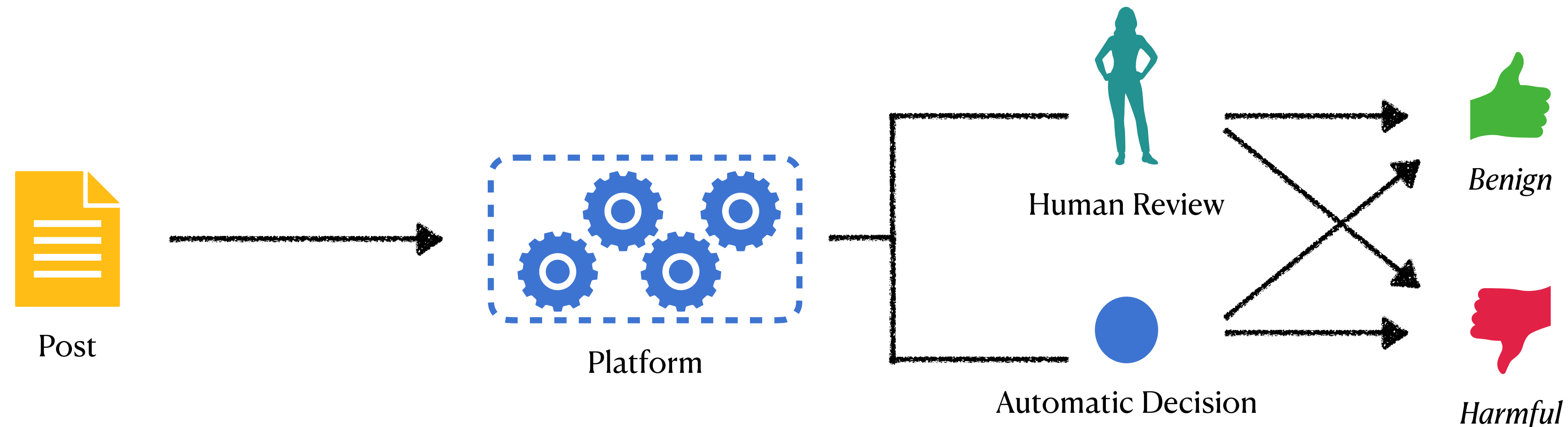
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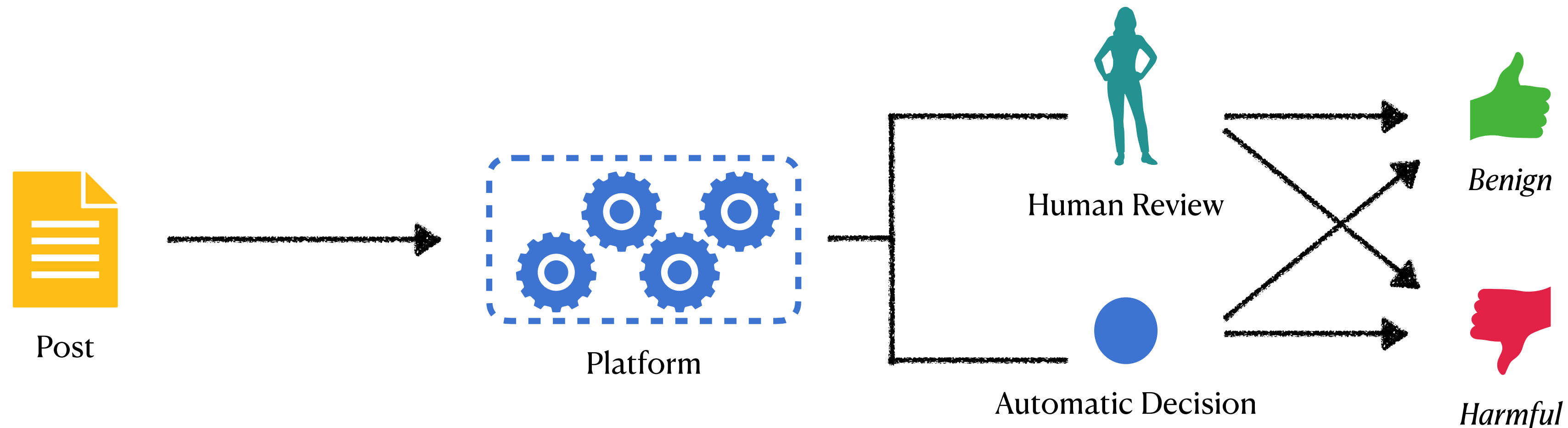
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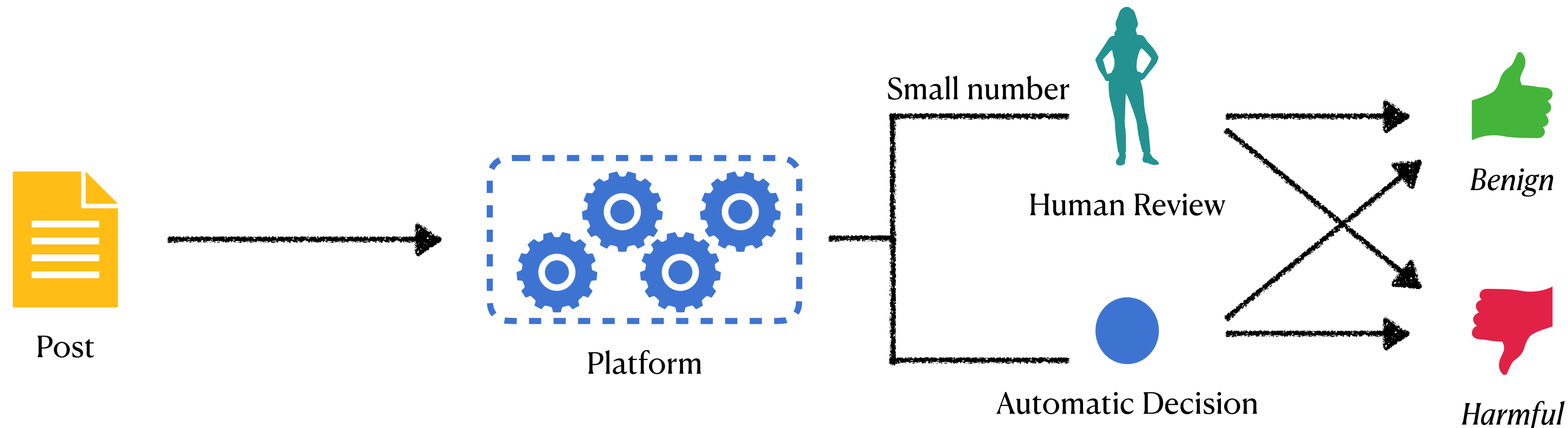
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Learning Protocol

Online Learning with Best-Action Queries

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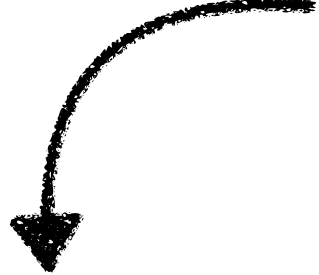
Learning Protocol

Online Learning with Best-Action Queries

- **Setting:** n possible actions and k best-action queries available
- **For time $t = 1, \dots, T$:**
 1. A **(hidden)** loss $\ell_t(i)$ arrives for each action $i \in [n]$
 2. The learner
 - A. Either takes action i_t at time t
 - B. Or is told the identity of the best action i_t^* at time t , and takes it
 3. The learner incurs a **(hidden)** loss $\ell_t(i_t)$ or $\ell_t(i_t^*)$
 4. A feedback z_t is revealed

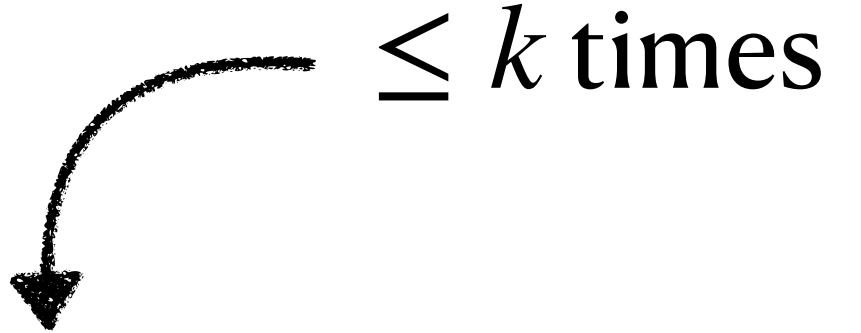
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-  $\leq k$ times

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- We study two types of feedback regimes
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- We want to understand how the **regret** grows:

$$R_T := \sum_{t \in [T]} \mathbb{E}[\ell_t(i_t)] - \min_{i \in [n]} \sum_{t \in [T]} \ell_t(i)$$

Our Results

Upper and Lower Bounds

Regret	Classical No Query	Low Query	Sublinear Query
Full feedback	$k = 0$ $R_T \in \Theta(\sqrt{T})$	$k \in O(\sqrt{T})$ $R_T \in \Theta(\sqrt{T})$	$k \in \Omega(\sqrt{T})$ $R_T \in \Theta\left(\frac{T}{k}\right)$
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- **Full feedback:** Hedge on *true* losses equipped with k uniform random queries across the time horizon (+ refined analysis)
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Future

- What about **bandit feedback, feedback graphs, partial monitoring feedback?**
- What if queries are **not perfect?**

Thank you!