

Feint Behaviors and Strategies: Formalization, Implementation and Evaluation

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Feint Behaviors

Widely-used tactics in competitive games:

- Boxing and fencing
- Basketball and football
- Motor racing

. . .

- Electronic games



NPC A's first action - feint



NPC B's first action – step back as defense

NPC A's second action - real attack



NPC B's first action (continue)

NPC B's second action - real attack

Outline

Background and Motivation

Feint Formalization in Action-Level

Feint Formalization in Strategy-Level

Proof-of-Concept Implementation

Evaluation Overview

Background and Motivation

Action-Level Formalization

• Existing works:

- Animate of Feint behaviors as proof-of-concept of character animation techniques [1].
- Learn control strategies from motion clips which incorporate nuanced behaviors like Feint behaviors [2].

• Uniqueness of Feint behaviors:

- (Semi-)palindrome
- Incorporation with other behaviors

Strategy-Level Formalization

• Existing works:

- Neglect Feint behaviors.
- Assume Feint behaviors are glitches of other behaviors, inducing same impact consideration and strategy learning.

• Uniqueness of Feint behaviors:

- Temporal impacts
- Spatial impacts
- Collective impacts

[1] Kevin Wampler, Erik Andersen, Evan Herbst, Yongjoon Lee, and Zoran Popovic. Character animation in two-player adversarial games. *ACM Trans. Graph.*, 29(3):26:1–26:13, 2010.

[2] Jungdam Won, Deepak Gopinath, and Jessica K. Hodgins. Control strategies for physically simulated characters performing two-player competitive sports. *ACM Trans. Graph.*, 40(4):146:1–146:11, 2021.

Our Work Overview

Action-Level Formalization

- Feint characteristics and templates
- Feint behaviors in game steps

Strategy-Level Formalization

- Temporal impacts
- Spatial impacts
- Collective impacts

Concrete and Unified Implementation

- Address action and strategy level formalizations
- Can directly incorporate common MARL models and schemes

Experiments and Evaluation

- Game reward gains
- Diversity gains
- Overhead

Outline

Background and Motivation

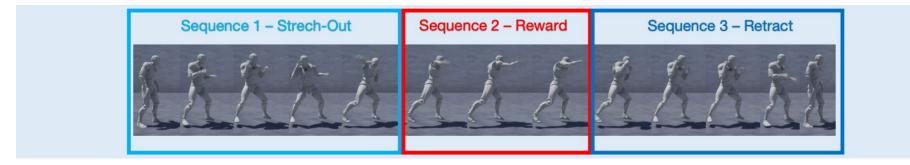
Feint Formalization in Action-Level

Feint Formalization in Strategy-Level

Proof-of-Concept Implementation

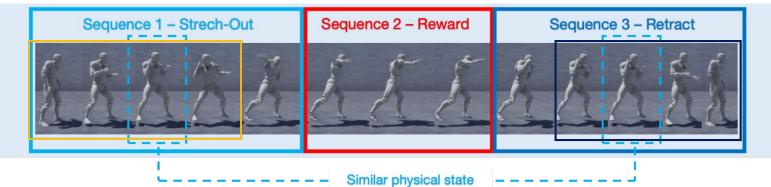
Evaluation Overview

Feint Behavior Characteristics and Templates



Most real-world attack behaviors can be divided into 3 stages.

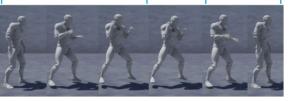
Feint templates can be automatically generated from them.

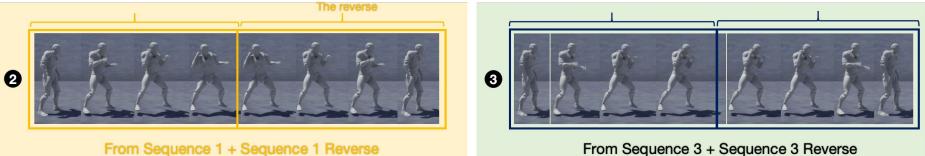


Actions before the similar state in Sequence 1

Actions after the similar state in Sequence 3

From Sequnece 1 + Sequnece 3:





Feint Behavior in Consecutive Game Steps

Dual-Behavior Model

Standalone Feint behavior is meaningless. Need to be combined with other behaviors.

2 Constraints:

- Physical constraint
 - Lead to physically plausible follow-up behaviors.

• Effectiveness constraint

• Enable temporal and spatial advantages.

Successful Feint

Agent - Feint Behavior (Fake punch towards the oppoent's head)



Opponent's response to the Feint - a full for defend for its head

 Temporal Advantage

 Agent - Followed-up attack (Hook towards the oppoent's waist)

 Image: Agent - Followed-up attack (Hook towards the oppoent's waist)

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 Image: Agent - Followed-up attack (Hook towards t

Unsuccessful Feint - Too Short

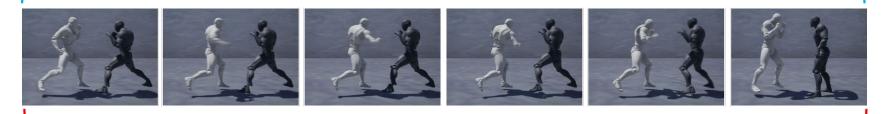
NPC A's first behavior - Feint (too short)

NPC A's second behavior - real attack



NPC B's first behavior - step back as defense

NPC A's second behavior - real attack (no effective reward since NPC B is still defending)



NPC B's first behavior (continue) - step back as defense

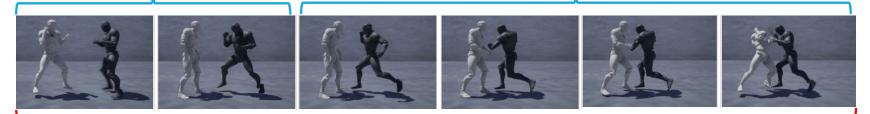
Unsuccessful Feint - Too Long

NPC A's first behavior - Feint (too long)



NPC B's first behavior - step back as defense

NPC A's first behavior (continue) - Feint NPC A's second behavior - real attack (interrupted by NPC B)



NPC B's second action - real attack (effective reward)

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Temporal Dimension: Influence Time

Dynamic short-long term:

$$Rew_{short}(\pi_{i}^{'}, t_{0}, t_{f}, t_{s}, \boldsymbol{\alpha}) = \begin{bmatrix} \sum_{t=t_{0}}^{t=t_{0}+t_{f}} \alpha_{Feint_{t}} R^{i}(s_{t}, a_{t}^{i}, a_{t}^{-i}) \\ \sum_{t=t_{s}f}^{t=t_{0}+t_{s}} \alpha_{attack_{t}} R^{i}(s_{t}, a_{t}^{i}, a_{t}^{-i}) \end{bmatrix}$$

$$Rew_{long}(\pi_{i}^{'}, t_{0}, t_{s}, T, \boldsymbol{\beta}) = \frac{1}{T} \sum_{t=t_{0}+t_{s}+1}^{T} \beta_{t} R^{i}(s_{t}, a_{t}^{i}, a_{t}^{-i})$$

$$Rew_{temporal}(\pi'_{i}, t_{0}, t_{f}, t_{s}, T, \boldsymbol{\alpha}, \boldsymbol{\beta}) = \lambda_{short} Rew_{short}(\pi'_{i}, t_{0}, t_{f}, t_{s}, \boldsymbol{\alpha}) + \lambda_{long} Rew_{long}(\pi'_{i}, t_{0}, t_{s}, T, \boldsymbol{\beta})$$

Spatial Dimension: Influence Range

Model the influence range of Feint behaviors as the **divergence of occupancy measures** (Behavioral Diversity [3]) during policy learning.

Maximize the effective influence range under the influence distribution of Feint.

$$max_{\pi'_{i}}Rew_{spatial}(\pi'_{i},\pi_{-i},s) = D_{f}(\rho_{\pi'_{i},\pi_{-i}}(s) \mid\mid \rho_{\pi_{i},\pi_{-i}}(s))$$

[3] Xiangyu Liu, Hangtian Jia, Ying Wen, Yaodong Yang, Yujing Hu, Yingfeng Chen, Changjie Fan, and Zhipeng Hu. Unifying behavioral and response diversity for open-ended learning in zero-sum games. *CoRR*, abs/2106.04958, 2021.

Collective Impacts: Influence Degree

Jointly model the temporal and spatial impacts of Feint behaviors:

- Aggregate the temporal reward on spatial domain for all agents.
- Aggregate the **spatial reward** on **temporal domain** for all state transitions.

$$Rew_{collective}(\pi_{i}^{'},\pi_{-i}) = \left| \mu_{1} \sum_{\pi \in \{\pi_{i}^{'},\pi_{-i}\}} Rew_{temporal}(\pi,t_{0},t_{f},t_{s},T,\boldsymbol{\alpha},\boldsymbol{\beta}) + \mu_{2} \sum_{s=s_{0}}^{s_{T}} Rew_{spatial}(\pi_{i}^{'},\pi_{-i},s) \right|$$

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Background and Motivation

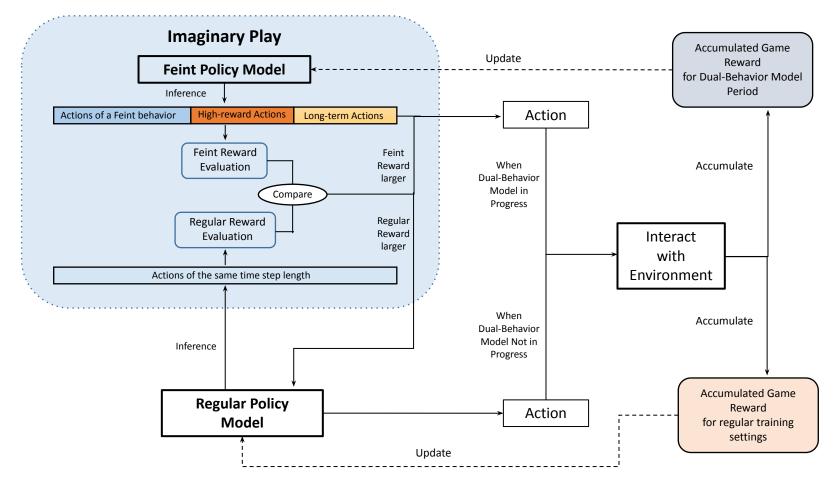
Feint Formalization in Action-Level

Feint Formalization in Strategy-Level

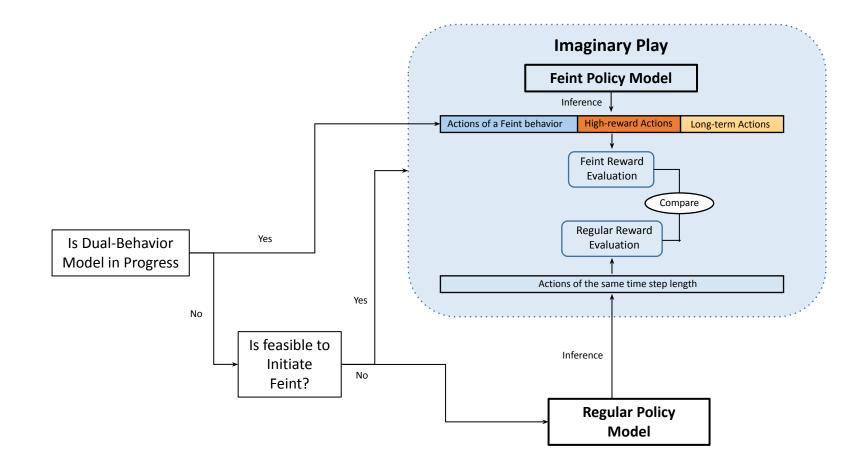
Proof-of-Concept Implementation

Evaluation Overview

A General Implementation Scheme I



A General Implementation Scheme II



Outline

Background and Motivation

Feint Formalization in Action-Level

Feint Formalization in Strategy-Level

Proof-of-Concept Implementation

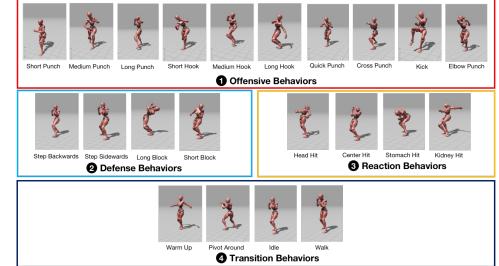
Evaluation Overview

Methodology

Game Scenarios:

- Complex Boxing Game
- Action space: Body movements
- Behaviors: Full set of Mixamo [4].
- Scenarios:
 - 1-vs-1 combat.
 - 3-vs-3 combat.

MARL Models: MADDPG [5], MASAC [6], MATD3 [7], MAD3PG [8]



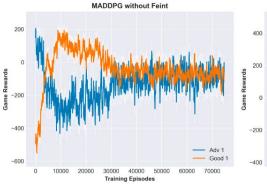
[5] Kevin Wampler, Erik Andersen, Evan Herbst, Yongjoon Lee, and Zoran Popovic. Character animation in two-player adversarial games. ACM Trans. Graph., 29(3):26:1–26:13, 2010.
 [6] Ryan Lowe, Yi Wu, Aviv Tamar, Jean Harb, Pieter Abbeel, and Igor Mordatch. Multi-agent actor-critic for mixed cooperative-competitive environments. In Isabelle Guyon, Ulrike von Luxburg, Samy Bengio, Hanna M. Wallach, Rob Fergus, S. V. N. Vishwanathan, and Roman Garnett, editors, Advances in Neural Information Processing Systems 30: Annual Conference on Neural Information Processing Systems 2017, December 4-9, 2017, Long Beach, CA, USA, pages 6379–6390, 2017.

[7] Shariq Iqbal and Fei Sha. Actor-attention-critic for multi-agent reinforcement learning. In Kamalika Chaudhuri and Ruslan Salakhutdinov, editors, *Proceedings of the 36th International Conference on Machine Learning, ICML 2019, 9-15 June 2019, Long Beach, California, USA*, volume 97 of *Proceedings of Machine Learning Research*, pages 2961–2970. PMLR, 2019.
 [6] Gabriel Barth-Maron, Matthew W. Hoffman, David Budden, Will Dabney, Dan Horgan, Dhruva TB, Alistair Muldal, Nicolas Heess, and Timothy P. Lillicrap. Distributed distributional deterministic policy gradients. In 6th International Conference on Learning Representations, ICLR 2018, Vancouver, BC, Canada, April 30 - May 3, 2018, Conference Track Proceedings. OpenReview.net, 2018.

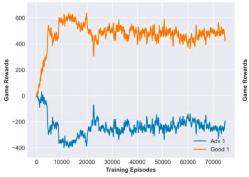
[8] Johannes Ackermann, Volker Gabler, Takayuki Osa, and Masashi Sugiyama. Reducing overestimation bias in multi-agent domains using double centralized critics. arXiv preprint arXiv:1910.01465, 2019.

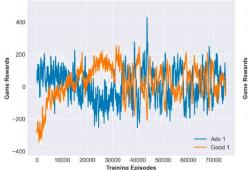
Game rewards Increase in 1-vs-1 Game

Effectively improve the actual game rewards.



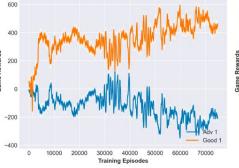
MADDPG with Feint

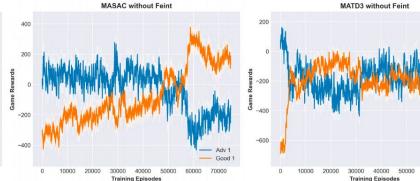




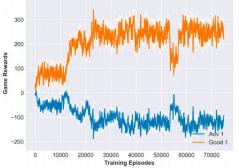
MAD3PG without Feint

MAD3PG with Feint



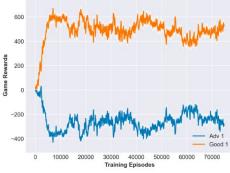


MASAC with Feint



MATD3 with Feint

60000 70000



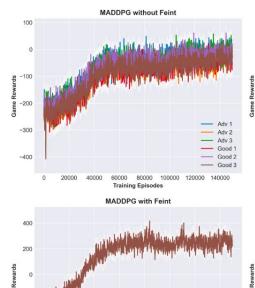
Game rewards Increase in 3-vs-3 Game

Effectively improve the actual game rewards.

400

Good 2

100000 120000 140000



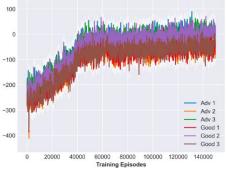
Training Episodes

-200

-400

-600

0 20000 40000 60000 80000

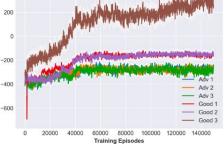


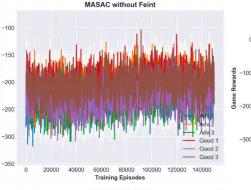
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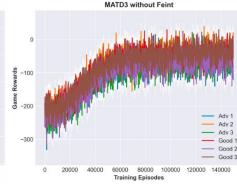
Game

MAD3PG without Feint

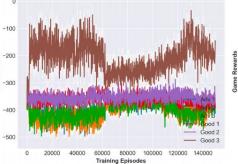




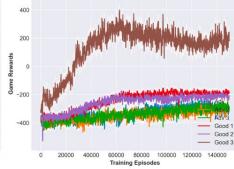






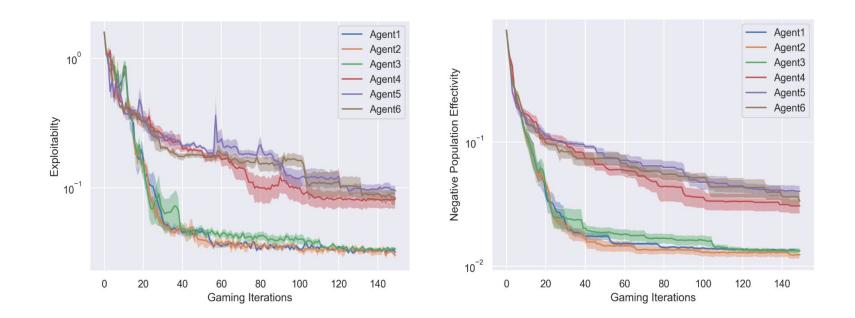


MATD3 with Feint



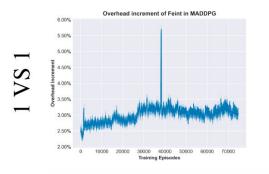
Other Results in the Paper

Diversity gain induced by Feint behaviors.



Other Results in the Paper

Neglectable overheads induced by our formalization.



4.00%

3.50%

3.00%

§ 2.50%

2.00%

0

20000 40000

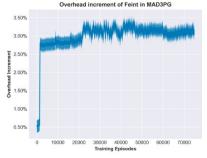
3

3 VS

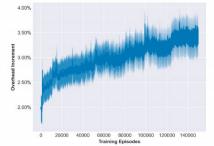
Overhead increment of Feint in MADDPG

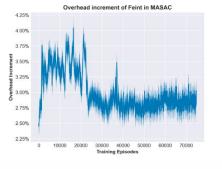
60000 80000 100000 120000 140000

Training Episodes

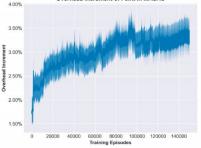


Overhead increment of Feint in MAD3PG





Overhead increment of Feint in MASAC

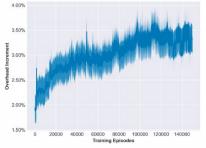




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Overhead increment of Feint in MATD3



Summary

Action-Level Formalization

- Feint characteristics and templates -Palindrome-directed Templates
- Feint behaviors in game steps -Dual-behavior Model

Strategy-Level Formalization

- **Temporal impacts** temporal advantage
- **Spatial impacts** Maximize the spatial diversity impacts
- **Collective impacts** collectively aggregate the temporal and spatial impacts in multi-agent environments.

Concrete and Unified Implementation

- Address action and strategy level formalizations.
- Can directly incorporate common MARL models and schemes.

Experiments and Evaluation

- Game reward gains improvements
- **Diversity gains** improvements
- **Overhead** negligible