

Cross-Scale Self-Supervised Blind Image Deblurring via Implicit Neural Representation

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Background

• Uniform blurring, usually can be described as the convolution:

$$
\bm{y}=\bm{k}\otimes\bm{x}+\bm{n}
$$

• Blind image deblurring (BID): $y \rightarrow (k, x)$

$$
\mathcal{L} = ? \circ ?
$$

• Challenge: solution ambiguity: $y = k \otimes x = \delta \otimes y$

• DNN-based re-parametrization of latent x/k :

$$
\boldsymbol{x}:=\mathcal{G}_{\boldsymbol{x}}(\cdot;\Theta_{\boldsymbol{x}}) \quad \ \boldsymbol{k}:=\mathcal{G}_{\boldsymbol{k}}(\cdot;\Theta_{\boldsymbol{k}})
$$

• Standard self-supervised reconstruction loss:

$$
\mathcal{L}_{sr}(\Theta_{\bm{k}},\Theta_{\bm{x}}):=||\mathcal{G}_{\bm{k}}(\cdot;\Theta_{\bm{k}})\otimes\mathcal{G}_{\bm{x}}(\cdot;\Theta_{\bm{x}})-\bm{y}||_2^2
$$

• Challenge: Overfitting due to the lack of ground truth (GT) data.

$$
\mathcal{G}_{\bm{x}}(\cdot; \hat{\Theta}_{\bm{x}}) \rightarrow \bm{y} \hspace{1cm} \mathcal{G}_{\bm{k}}(\cdot; \hat{\Theta}_{\bm{k}}) \rightarrow \bm{\delta}
$$

Two key questions for self-supervised BID:

Q1: How to formulate a better self-supervised loss?

A1: **A cross-scale loss function**:

Leveraging the resolution-independent properties of Implicit Neural Representation (INR) for latent images/kernels.

Q2: How can we efficiently train the two NN generators to ensure accurate convergence to the latent images and kernels?

A2: **A progressive coarse-to-fine scheme**:

Enhancing training efficiency and ensuring the convergence to GT image/kernel.

$$
L_{\text{fit}}(\Theta_{\bm{k}},\Theta_{\bm{x}}) = \mathcal{M}_f\big(\bm{y}-\bm{k}\otimes \bm{x}\big) = \mathcal{M}_{\text{fit}}\Big(\Phi_{\bm{k}}(\mathbb{I}_{\bm{k}};\Theta_{\bm{k}})\otimes \Phi_{\bm{x}}(\mathbb{I}_{\bm{x}};\Theta_{\bm{x}}),\bm{y}\Big)
$$

where $\mathcal{M}_f(\cdot)$ is some distance metric.

• **Such fitting loss clearly is not sufficient to resolve solution ambiguity!**

- To alleviate over-fitting, the down-sampled version of y , denoted as $y_{\downarrow s}$ for scale s , has often been used to initiate the blur kernel estimate.
- However, $(\mathbf{x} \otimes \mathbf{k})\downarrow_2 \neq \mathbf{x}\downarrow_2 \otimes \mathbf{k}\downarrow_2$
- We present a cross-scale constraint that accurately characterizes the connection between (y, x, k) at different scales:

Proposition 1. For a kernel (filter) k, let g_1, g_2, g_3 denote its associated QMF filters defined by $g_1[m,n] = (-1)^m k[m,n], g_2[m,n] = (-1)^n k[m,n], g_3[m,n] = (-1)^{m+n} k[m,n],$ for any $[m, n] \in \mathbb{I}_k$. Then, we have the following relation between consecutive two dyadic scales:

$$
(\boldsymbol{x\!\!\downarrow}_2) \otimes (\boldsymbol{k\!\!\downarrow}_2) = \frac{1}{4} \big((\boldsymbol{x} \otimes \boldsymbol{k}) \!\!\downarrow_2 + \sum_{d=1}^3 (\boldsymbol{x} \otimes \boldsymbol{g}_d) \!\!\downarrow_2 \big).
$$

Self-supervised cross-scale loss for BID

• We introduce a scale consistency loss across two consecutive scales: For each scale s :

$$
\begin{aligned} L_{\text{cross}}^{(s)}(\Theta_{\boldsymbol{k}},\Theta_{\boldsymbol{x}}) &= \mathcal{M}_c\Big(4(\boldsymbol{x}^{(s)}\mathord{\downarrow}_2)\otimes (\boldsymbol{k}^{(s)}\mathord{\downarrow}_2), (\boldsymbol{x}^{(s)}\otimes \boldsymbol{k}^{(s)})\mathord{\downarrow}_2 + \sum\limits_{1\leq d\leq 3}(\boldsymbol{x}^{(s)}\otimes \boldsymbol{g}_d^{(s)})\mathord{\downarrow}_2\Big) \\ &= \mathcal{M}_c\Big(4(\boldsymbol{x}^{(s+1)})\otimes (\boldsymbol{k}^{(s+1)}), (\boldsymbol{x}^{(s)}\otimes \boldsymbol{k}^{(s)})\mathord{\downarrow}_2 + \sum\limits_{1\leq d\leq 3}(\boldsymbol{x}^{(s)}\otimes \boldsymbol{g}_d^{(s)})\mathord{\downarrow}_2\Big) \end{aligned}
$$

• Ablation study on the \mathcal{L}_{cross} in terms of of PSNR/SSIM.

The scale-consistency loss providing additional regularization for training two INRbased generators.

-
- The blur kernel and the latent image are re-parameterized by two INR models:

$$
\left\{\begin{array}{c} \mathbf{k}[\mathbb{I}_{\mathbf{k}}] = \Phi_{\mathbf{k}}(\mathbb{I}_{\mathbf{k}};\Theta_{\mathbf{k}}) & : & \mathbf{k}[i,j] = \Phi_{\mathbf{k}}([i,j]),\,[i,j] \in \mathbb{I}_{\mathbf{k}}; \\ \mathbf{x}[\mathbb{I}_{\mathbf{x}}] = \Phi_{\mathbf{x}}(\mathbb{I}_{\mathbf{x}};\Theta_{\mathbf{x}}) & : & \mathbf{x}[i,j] = \Phi_{\mathbf{x}}([i,j]),\,[i,j] \in \mathbb{I}_{\mathbf{x}}, \end{array}\right.
$$

• Let $k^{(0)} = k, x^{(0)} = x$ denotes the original scale, we can form both the kernel and the image in a dyadic pyramid:

$$
k^{(s)} = (k^{(s-1)}) \downarrow_2
$$
 and $x^{(s)} = (x^{(s-1)}) \downarrow_2$, for $1 \le s \le S_0$.

• INR enables the model to generate the prediction with higher/lower resolutions from the same learned model, facilitating multi-scale processing and cross-scale interaction.

- **First stage** (Initialization): at the scale S_0 Training the NNs with only the fitting loss $\mathcal{L}_{\text{fit}}^{(S_0)}$.
- **Second stage:** progressive refines the training from the scale S_0 to 0 Training the NNs at the scale *s* with the loss $\mathcal{L}_{\text{fit}}^{(s)} + \lambda \mathcal{L}_{\text{cross}}^{(s)}$.
- **Final stage:** tuning ar the scale 0

Training the NNs at scale 0 with only the fitting loss $\mathcal{L}_{\text{fit}}^{(0)}$.

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Ablation study on the croos scale and progressive training in terms of of PSNR/SSIM.

PSNR results on blind uniform deblurring

• [Lai et al.'s Dataset]: 100 images categorized into five groups, and covers 4 different kernels whose size ranges from 31×31 to 75×75 .

Visual Results

\triangleright Visual results on blind uniform deblurring [Lai Dataset].

▶ Visual results on real blurry image.

Limitation1: Computational cost for processing a large number of images as the method requires training the model for each individual sample. Potential solution: **Meta-learning or Testing-time adaptation.**

Limitation2: Only applicable to handle uniform blurring, as it relies on the convolution model.

Future work: **Extending this approach to handle non-uniform blur.**

Thank you for your attention!