



Haoxuan Chen^{*1}, Yinuo Ren^{*1},
Lexing Ying^{2,1}, Grant M. Rotskoff^{3,1}

{haoxuanc,yinuoren,lexing,rotskoff}@stanford.edu

** Equal Contribution*

¹ICME ²Department of Mathematics ³Department of Chemistry
Stanford University

November 12, 2024

Accelerating Diffusion Models with Parallel Sampling:

Inference at Sub-Linear Time Complexity

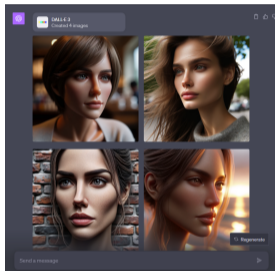
- 1 Introduction
- 2 Algorithm
- 3 Main Results

Section 1:
Introduction



Continuous Diffusion Models

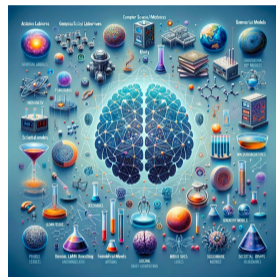
Introduction



(a) DALL-E 3



(b) Stable Diffusion



(c) AI4Science

Figure: Diffusion and flow-based generative models have exerted huge impacts on scientific research in many fields.

Introduction

Problem Setting

- › **Task:** Sample from data distribution p_0 *accurately* and *efficiently*

Introduction

Problem Setting

- › **Task:** Sample from data distribution p_0 *accurately* and *efficiently*
- › **Forward SDE:**

$$d\mathbf{x}_s = \boldsymbol{\beta}_s(\mathbf{x}_s)ds + \boldsymbol{\sigma}_s d\mathbf{w}_s, \quad \text{with } \mathbf{x}_0 \sim p_0$$

Introduction

Problem Setting

- › **Task:** Sample from data distribution p_0 *accurately* and *efficiently*
- › **Forward SDE:**

$$d\mathbf{x}_s = \boldsymbol{\beta}_s(\mathbf{x}_s)ds + \boldsymbol{\sigma}_s d\mathbf{w}_s, \quad \text{with } \mathbf{x}_0 \sim p_0$$

- › **Backward SDE:**

$$d\tilde{\mathbf{x}}_t = \left[-\tilde{\boldsymbol{\beta}}_t(\tilde{\mathbf{x}}_t) + \frac{\tilde{\boldsymbol{\sigma}}_t \tilde{\boldsymbol{\sigma}}_t^\top + \tilde{\mathbf{v}}_t \tilde{\mathbf{v}}_t^\top}{2} \nabla \log \tilde{p}_t(\tilde{\mathbf{x}}_t) \right] dt + \tilde{\mathbf{v}}_t d\mathbf{w}_t$$

with $\tilde{p}_0 = p_T \approx \mathcal{N}(\mathbf{0}, \mathbf{I})$ and $\tilde{p}_T = p_0$

Introduction

Problem Setting

- › **Task:** Sample from data distribution p_0 *accurately* and *efficiently*
- › **Forward SDE:**

$$d\mathbf{x}_s = \boldsymbol{\beta}_s(\mathbf{x}_s)ds + \boldsymbol{\sigma}_s d\mathbf{w}_s, \quad \text{with } \mathbf{x}_0 \sim p_0$$

- › **Backward SDE:**

$$d\tilde{\mathbf{x}}_t = \left[-\tilde{\boldsymbol{\beta}}_t(\tilde{\mathbf{x}}_t) + \frac{\tilde{\boldsymbol{\sigma}}_t \tilde{\boldsymbol{\sigma}}_t^\top + \tilde{\mathbf{v}}_t \tilde{\mathbf{v}}_t^\top}{2} \nabla \log \tilde{p}_t(\tilde{\mathbf{x}}_t) \right] dt + \tilde{\mathbf{v}}_t d\mathbf{w}_t$$

with $\tilde{p}_0 = p_T \approx \mathcal{N}(\mathbf{0}, \mathbf{I})$ and $\tilde{p}_T = p_0$

- › **Score Function:** $\mathbf{s}_t^\theta(\mathbf{x}_t) \approx \nabla \log p_t(\mathbf{x}_t)$ by optimizing

$$\mathcal{L}(\theta) = \int_0^T \psi_t \mathbb{E}_{\mathbf{x}_t \sim p_t} \left[\|\nabla \log p_t(\mathbf{x}_t) - \mathbf{s}_t^\theta(\mathbf{x}_t)\|^2 \right] dt$$

Introduction

Problem Setting

- › **Task:** Sample from data distribution p_0 *accurately* and *efficiently*
- › **Forward SDE:**

$$d\mathbf{x}_s = \boldsymbol{\beta}_s(\mathbf{x}_s)ds + \boldsymbol{\sigma}_s d\mathbf{w}_s, \quad \text{with } \mathbf{x}_0 \sim p_0$$

- › **Backward SDE:**

$$d\tilde{\mathbf{x}}_t = \left[-\tilde{\boldsymbol{\beta}}_t(\tilde{\mathbf{x}}_t) + \frac{\tilde{\boldsymbol{\sigma}}_t \tilde{\boldsymbol{\sigma}}_t^\top + \tilde{\mathbf{v}}_t \tilde{\mathbf{v}}_t^\top}{2} \nabla \log \tilde{p}_t(\tilde{\mathbf{x}}_t) \right] dt + \tilde{\mathbf{v}}_t d\mathbf{w}_t$$

with $\tilde{p}_0 = p_T \approx \mathcal{N}(\mathbf{0}, \mathbf{I})$ and $\tilde{p}_T = p_0$

- › **Score Function:** $\mathbf{s}_t^\theta(\mathbf{x}_t) \approx \nabla \log p_t(\mathbf{x}_t)$ by optimizing

$$\mathcal{L}(\theta) = \int_0^T \psi_t \mathbb{E}_{\mathbf{x}_t \sim p_t} \left[\|\nabla \log p_t(\mathbf{x}_t) - \mathbf{s}_t^\theta(\mathbf{x}_t)\|^2 \right] dt$$

- › **Implementations:** SDE ($\mathbf{v}_t = \boldsymbol{\sigma}_t$), Probability Flow ODE (PF-ODE, $\mathbf{v}_t \equiv \mathbf{0}$)

Introduction

Error Analysis

Take $\beta_s(\mathbf{x}_s) = -\frac{1}{2}\mathbf{x}_s$ and $\sigma_s = \mathbf{I}$:

- Forward SDE: $d\mathbf{x}_s = -\frac{1}{2}\mathbf{x}_s ds + d\mathbf{w}_s$ with $\mathbf{x}_0 \sim p_0$

Introduction

Error Analysis

Take $\beta_s(\mathbf{x}_s) = -\frac{1}{2}\mathbf{x}_s$ and $\sigma_s = \mathbf{I}$:

- Forward SDE: $d\mathbf{x}_s = -\frac{1}{2}\mathbf{x}_s ds + d\mathbf{w}_s$ with $\mathbf{x}_0 \sim p_0$
- Backward SDE: $d\tilde{\mathbf{x}}_t = \left[\frac{1}{2}\tilde{\mathbf{x}}_t + \frac{1+v^2}{2}\nabla \log \tilde{p}_t(\tilde{\mathbf{x}}_t) \right] dt + v d\mathbf{w}_t$, with $\tilde{p}_0 = p_T \approx \mathcal{N}(\mathbf{0}, \mathbf{I})$ and $\tilde{p}_T = p_0$

Introduction

Error Analysis

Take $\beta_s(\mathbf{x}_s) = -\frac{1}{2}\mathbf{x}_s$ and $\sigma_s = \mathbf{I}$:

- ▶ Forward SDE: $d\mathbf{x}_s = -\frac{1}{2}\mathbf{x}_s ds + d\mathbf{w}_s$ with $\mathbf{x}_0 \sim p_0$
- ▶ Backward SDE: $d\tilde{\mathbf{x}}_t = \left[\frac{1}{2}\tilde{\mathbf{x}}_t + \frac{1+v^2}{2}\nabla \log \tilde{p}_t(\tilde{\mathbf{x}}_t) \right] dt + v d\mathbf{w}_t$, with $\tilde{p}_0 = p_T \approx \mathcal{N}(\mathbf{0}, \mathbf{I})$ and $\tilde{p}_T = p_0$

Theorem (Error Analysis of Continuous Diffusion Models [BDBDD23])

Suppose $t_0 = 0 \leq \dots \leq t_N = T - \delta$ satisfies $t_{k+1} - t_k \leq \kappa(T - t_{k+1})$ and

$$\sum_{k=0}^{N-1} (s_{k+1} - s_k) \mathbb{E}_{\tilde{\mathbf{x}}_{s_k} \sim \tilde{p}_{s_k}} \left[\left\| \nabla \log \tilde{p}_{s_k}(\tilde{\mathbf{x}}_{s_k}) - \tilde{\mathbf{s}}_{s_k}^{\theta}(\mathbf{x}_{s_k}) \right\|^2 \right] \leq \epsilon.$$

Then with

$$T = \mathcal{O}(\log(d\epsilon^{-1})), \quad \kappa = \mathcal{O}(d^{-1}\epsilon \log^{-1}(d\epsilon^{-1})), \quad N = \mathcal{O}(d\epsilon^{-1} \log^2(d\epsilon^{-1})),$$

we have

$$D_{\text{KL}}(p_{\delta} \parallel \hat{q}_{t_N}) \lesssim d\epsilon^{-T} + \epsilon + d\kappa T \lesssim \epsilon.$$

Introduction

Error Analysis

Theorem (Error Analysis of Continuous Diffusion Models [BDBDD23])

With

$$T = \mathcal{O}(\log(d\epsilon^{-1})), \quad \kappa = \mathcal{O}(d^{-1}\epsilon \log^{-1}(d\epsilon^{-1})), \quad N = \mathcal{O}(d\epsilon^{-1} \log^2(d\epsilon^{-1})),$$

we have

$$D_{\text{KL}}(p_\delta \| \hat{q}_{t_N}) \lesssim d\epsilon^{-T} + \epsilon + d\kappa T \lesssim \epsilon.$$

Introduction

Error Analysis

Theorem (Error Analysis of Continuous Diffusion Models [BDBDD23])

With

$$T = \mathcal{O}(\log(d\epsilon^{-1})), \quad \kappa = \mathcal{O}(d^{-1}\epsilon \log^{-1}(d\epsilon^{-1})), \quad N = \mathcal{O}(d\epsilon^{-1} \log^2(d\epsilon^{-1})),$$

we have

$$D_{\text{KL}}(p_\delta \| \hat{q}_{t_N}) \lesssim d e^{-T} + \epsilon + d\kappa T \lesssim \epsilon.$$

- ▶ **Truncation Error:** Error caused by approximating p_T by p_∞ , of the order $\mathcal{O}(d \exp(-T))$;

Introduction

Error Analysis

Theorem (Error Analysis of Continuous Diffusion Models [BDBDD23])

With

$$T = \mathcal{O}(\log(d\epsilon^{-1})), \quad \kappa = \mathcal{O}(d^{-1}\epsilon \log^{-1}(d\epsilon^{-1})), \quad N = \mathcal{O}(d\epsilon^{-1} \log^2(d\epsilon^{-1})),$$

we have

$$D_{\text{KL}}(p_\delta \|\hat{q}_{t_N}) \lesssim de^{-T} + \epsilon + d\kappa T \lesssim \epsilon.$$

- **Truncation Error:** Error caused by approximating p_T by p_∞ , of the order $\mathcal{O}(d \exp(-T))$;
- **Approximation Error:** Error caused by approximating $\nabla \log p_t(\mathbf{x}_t)$ by NN $\hat{\mathbf{s}}_t^\theta(\mathbf{x}_t)$, assumed to be of $\mathcal{O}(\epsilon)$;

Introduction

Error Analysis

Theorem (Error Analysis of Continuous Diffusion Models [BDBDD23])

With

$$T = \mathcal{O}(\log(d\epsilon^{-1})), \quad \kappa = \mathcal{O}(d^{-1}\epsilon \log^{-1}(d\epsilon^{-1})), \quad N = \mathcal{O}(d\epsilon^{-1} \log^2(d\epsilon^{-1})),$$

we have

$$D_{\text{KL}}(p_\delta \|\hat{q}_{t_N}) \lesssim de^{-T} + \epsilon + d\kappa T \lesssim \epsilon.$$

- **Truncation Error:** Error caused by approximating p_T by p_∞ , of the order $\mathcal{O}(d \exp(-T))$;
- **Approximation Error:** Error caused by approximating $\nabla \log p_t(\mathbf{x}_t)$ by NN $\hat{\mathbf{s}}_t^\theta(\mathbf{x}_t)$, assumed to be of $\mathcal{O}(\epsilon)$;
- **Discretization Error:** Error caused by numerically solving the backward SDE, e.g. exponential integrator [ZC22].

Introduction

Inference Cost

Inference Cost

- The evaluation of the score function \mathbf{s}_t^θ is expensive
- The inference process of continuous diffusion models requires $\tilde{\mathcal{O}}(d)$ times of score function evaluations

Possible Solutions

- DDIM [SME20]
- Higher-order schemes [DVK22, KAAL22, LHE⁺24]
- Operator learning [ZNV⁺23]
- Knowledge distillation [LL21, MRG⁺23]
- Consistency model [SDCS23, SD23, LS24]
- Parallel sampling [SBE⁺24, TTL⁺24]

Section 2: Algorithm

Algorithm

Parallel Sampling

Picard Iteration

For $k \in [0 : K - 1]$,

Algorithm

Parallel Sampling

Picard Iteration

For $k \in [0 : K - 1]$,

- › Solve ODE $d\mathbf{x}_t = \mathbf{f}_t(\mathbf{x}_t)dt$ in parallel

$$\mathbf{x}_t^{(0)} \equiv \mathbf{x}_0, \text{ and } \mathbf{x}_t^{(k+1)} := \mathbf{x}_0 + \int_0^t \mathbf{f}_s(\mathbf{x}_s^{(k)})ds$$

Algorithm

Parallel Sampling

Picard Iteration

For $k \in [0 : K - 1]$,

- Solve ODE $d\mathbf{x}_t = \mathbf{f}_t(\mathbf{x}_t)dt$ in parallel

$$\mathbf{x}_t^{(0)} \equiv \mathbf{x}_0, \text{ and } \mathbf{x}_t^{(k+1)} := \mathbf{x}_0 + \int_0^t \mathbf{f}_s(\mathbf{x}_s^{(k)})ds$$

- Simulate Langevin dynamics $d\mathbf{x}_t = -\nabla V(\mathbf{x}_t)dt + d\mathbf{w}_t$ in parallel [ACV24]

$$\mathbf{x}_t^{(0)} \equiv \mathbf{x}_0, \text{ and } \mathbf{x}_t^{(k+1)} := \mathbf{x}_0 - \int_0^t \nabla V(\mathbf{x}_s^{(k)})ds + \mathbf{w}_t$$

Algorithm

Parallel Sampling

Picard Iteration

For $k \in [0 : K - 1]$,

- Solve ODE $d\mathbf{x}_t = \mathbf{f}_t(\mathbf{x}_t)dt$ in parallel

$$\mathbf{x}_t^{(0)} \equiv \mathbf{x}_0, \text{ and } \mathbf{x}_t^{(k+1)} := \mathbf{x}_0 + \int_0^t \mathbf{f}_s(\mathbf{x}_s^{(k)})ds$$

- Simulate Langevin dynamics $d\mathbf{x}_t = -\nabla V(\mathbf{x}_t)dt + d\mathbf{w}_t$ in parallel [ACV24]

$$\mathbf{x}_t^{(0)} \equiv \mathbf{x}_0, \text{ and } \mathbf{x}_t^{(k+1)} := \mathbf{x}_0 - \int_0^t \nabla V(\mathbf{x}_s^{(k)})ds + \mathbf{w}_t$$

- Sample from diffusion models in parallel (This work)

$$d\hat{\mathbf{y}}_{t_n, \tau}^{(k+1)} = \left[\frac{1}{2} \hat{\mathbf{y}}_{t_n, \tau}^{(k+1)} + \mathbf{s}_{t_n + g_n(\tau)}^\theta \left(\hat{\mathbf{y}}_{t_n, g_n(\tau)}^{(k)} \right) \right] d\tau + d\mathbf{w}_{t_n + \tau}$$

Section 3:
Main Results



Main Results

Assumptions

- › **Regularity of data distribution:** p_0 has finite second moment and is normalized, i.e., $\text{cov}_{p_0}(\mathbf{x}_0) = \mathbf{I}_d$

Main Results

Assumptions

- **Regularity of data distribution:** p_0 has finite second moment and is normalized, i.e., $\text{cov}_{p_0}(\mathbf{x}_0) = \mathbf{I}_d$
- **Bounded learned score:** The learned score \mathbf{s}_t^θ has bounded C^1 norm with Lipschitz const L_s .

Main Results

Assumptions

- **Regularity of data distribution:** p_0 has finite second moment and is normalized, i.e., $\text{cov}_{p_0}(\mathbf{x}_0) = \mathbf{I}_d$
- **Bounded learned score:** The learned score \mathbf{s}_t^θ has bounded C^1 norm with Lipschitz const L_s .
- δ -accurate score estimation:

Main Results

Assumptions

- **Regularity of data distribution:** p_0 has finite second moment and is normalized, i.e., $\text{cov}_{p_0}(\mathbf{x}_0) = \mathbf{I}_d$
- **Bounded learned score:** The learned score \mathbf{s}_t^θ has bounded C^1 norm with Lipschitz const L_s .
- **δ -accurate score estimation:**
SDE The learned score \mathbf{s}_t^θ is $L^2([0, t_N])$ δ -accurate:

$$\mathbb{E}_{\tilde{p}} \left[\sum_{n=0}^{N-1} \sum_{m=0}^{M_n-1} \epsilon_{n,m} \left\| \mathbf{s}_{t_n+\tau_{n,m}}^\theta(\tilde{\mathbf{x}}_{t_n+\tau_{n,m}}) - \nabla \log \tilde{p}_{t_n+\tau_{n,m}}(\tilde{\mathbf{x}}_{t_n+\tau_{n,m}}) \right\|^2 \right] \leq \delta_2^2$$

Main Results

Assumptions

- ▶ **Regularity of data distribution:** p_0 has finite second moment and is normalized, i.e., $\text{cov}_{p_0}(\mathbf{x}_0) = \mathbf{I}_d$
- ▶ **Bounded learned score:** The learned score \mathbf{s}_t^θ has bounded C^1 norm with Lipschitz const L_s .
- ▶ **δ -accurate score estimation:**
SDE The learned score \mathbf{s}_t^θ is $L^2([0, t_N])$ δ -accurate:

$$\mathbb{E}_{\tilde{p}} \left[\sum_{n=0}^{N-1} \sum_{m=0}^{M_n-1} \epsilon_{n,m} \left\| \mathbf{s}_{t_n+\tau_{n,m}}^\theta(\tilde{\mathbf{x}}_{t_n+\tau_{n,m}}) - \nabla \log \tilde{p}_{t_n+\tau_{n,m}}(\tilde{\mathbf{x}}_{t_n+\tau_{n,m}}) \right\|^2 \right] \leq \delta_2^2$$

PF-ODE The learned score \mathbf{s}_t^θ is $L^\infty([0, t_N])$ δ -accurate:

$$\mathbb{E}_{\tilde{p}_{t_n+\tau_{n,m}}} \left[\left\| \mathbf{s}_{t_n+\tau_{n,m}}^\theta(\tilde{\mathbf{x}}_{t_n+\tau_{n,m}}) - \nabla \log \tilde{p}_{t_n+\tau_{n,m}}(\tilde{\mathbf{x}}_{t_n+\tau_{n,m}}) \right\|^2 \right] \leq \delta_\infty^2.$$

Main Results

Assumptions

- ▶ **Regularity of data distribution:** p_0 has finite second moment and is normalized, i.e., $\text{cov}_{p_0}(\mathbf{x}_0) = \mathbf{I}_d$
- ▶ **Bounded learned score:** The learned score \mathbf{s}_t^θ has bounded C^1 norm with Lipschitz const L_s .
- ▶ **δ -accurate score estimation:**
SDE The learned score \mathbf{s}_t^θ is $L^2([0, t_N])$ δ -accurate:

$$\mathbb{E}_{\tilde{p}} \left[\sum_{n=0}^{N-1} \sum_{m=0}^{M_n-1} \epsilon_{n,m} \left\| \mathbf{s}_{t_n+\tau_{n,m}}^\theta(\tilde{\mathbf{x}}_{t_n+\tau_{n,m}}) - \nabla \log \tilde{p}_{t_n+\tau_{n,m}}(\tilde{\mathbf{x}}_{t_n+\tau_{n,m}}) \right\|^2 \right] \leq \delta_2^2$$

PF-ODE The learned score \mathbf{s}_t^θ is $L^\infty([0, t_N])$ δ -accurate:

$$\mathbb{E}_{\tilde{p}_{t_n+\tau_{n,m}}} \left[\left\| \mathbf{s}_{t_n+\tau_{n,m}}^\theta(\tilde{\mathbf{x}}_{t_n+\tau_{n,m}}) - \nabla \log \tilde{p}_{t_n+\tau_{n,m}}(\tilde{\mathbf{x}}_{t_n+\tau_{n,m}}) \right\|^2 \right] \leq \delta_\infty^2.$$

- ▶ **Bounded true score (PF-ODE):** The true score $\nabla \log p_t$ has bounded C^1 norm with Lipschitz const L_p .

Main Results

SDE Implementation

Theorem (Parallel Acceleration for SDE Implementation)

Under assumptions aforementioned, given

$$T = \mathcal{O}(\log(d\delta^{-2})), \quad h = \Theta(1), \quad N = \mathcal{O}(\log(d\delta^{-2})), \\ \epsilon = \Theta(d^{-1}\delta^2 \log^{-1}(d\delta^{-2})), \quad M = \mathcal{O}(d\delta^{-2} \log(d\delta^{-2})), \quad K = \tilde{\mathcal{O}}(\log(d\delta^{-2})),$$

we have the following error bound

$$D_{\text{KL}}(p_\eta \| \hat{q}_{t_N}) \lesssim de^{-T} + d\epsilon T + \delta_2^2 + dTe^{-K} \lesssim \delta^2,$$

with a total of

- $KN = \tilde{\mathcal{O}}(\log^2(d\delta^{-2}))$ approximate time complexity
- $dM = \tilde{\mathcal{O}}(d^2\delta^{-2})$ space complexity

for parallelizable $L^2([0, t_N])$ δ -accurate score function evaluations.

Main Results

PF-ODE Implementation

PF-ODE with predictor-corrector [CCL⁺24] further improves space complexity:

Theorem (Parallel Acceleration for PF-ODE Implementation)

Under assumptions aforementioned, given proper parameter selections, we have

$$\mathrm{TV}(p_\eta, \hat{q}_{t_N})^2 \lesssim de^{-T} + d\epsilon^2 T^2 + (T^2 + N^2)\delta_\infty^2 + dN^2 e^{-K} \lesssim \delta^2,$$

with a total of

- $(K + K^\dagger N^\dagger)N = \tilde{O}(\log^2(d\delta^{-2}))$ approximate time complexity
- $d(M \vee M^\dagger) = \tilde{\Theta}(d^{3/2}\delta^{-1})$ space complexity

for parallelizable $L^\infty([0, t_N])$ δ -accurate score function evaluations.

Remark

$$\begin{aligned} \mathbb{E}[f(x_t) - f(x_0)]^2 &\lesssim \mathbb{E}\left[\int f'(x_t)b_t + f''(x_t)\sigma dt\right]^2 + \mathbb{E}\left[\int f'(x_t)\sqrt{2\sigma}dw_t\right]^2 \\ &\sim O(t^2) + \sigma O(t), \end{aligned}$$

Main Results

Proof Sketch

Theorem (Generalized Girsanov's Theorem)

Let $\alpha(t, \omega) \in \mathcal{V}^m$, $\Sigma(t, \omega) \in \mathcal{V}^{m \times n}$, and $(\mathbf{w}_t(\omega))_{t \geq 0}$ be a Wiener process on (Ω, \mathcal{F}, q) . For $t \in [0, T]$, suppose $\mathbf{z}_t(\omega)$ satisfies

$$d\mathbf{z}_t(\omega) = \alpha(t, \omega)dt + \Sigma(t, \omega)d\mathbf{w}_t(\omega),$$

where $\Sigma(t, \omega)\delta(t, \omega) = \alpha(t, \omega) - \beta(t, \omega)$, then there exists p on (Ω, \mathcal{F}) s.t.

- 1 $p \ll q$ with the Radon-Nikodym derivative $\frac{dp}{dq}(\omega) = M_T(\omega)$;
- 2 $\tilde{\mathbf{w}}_t(\omega) = \mathbf{w}_t(\omega) + \int_0^t \delta(s, \omega)ds$ is a Wiener process on (Ω, \mathcal{F}, p) ;
- 3 Any continuous path generated by the process \mathbf{z}_t satisfies the following SDE under p :

$$d\tilde{\mathbf{z}}_t(\omega) = \beta(t, \omega)dt + \Sigma(t, \omega)d\tilde{\mathbf{w}}_t(\omega).$$

Main Results

Proof Sketch

In n -th block, let $q|_{\mathcal{F}_{t_n}}$ be the measure shared by $\mathbf{w}_t(\omega)$ in the Picard iteration

1 Define $d\tilde{\mathbf{w}}_{t_n+\tau}(\omega) = d\mathbf{w}_{t_n+\tau}(\omega) + \boldsymbol{\delta}_{t_n}(\tau, \omega)d\tau$, where

$$\boldsymbol{\delta}_{t_n}(\tau, \omega) := \mathbf{s}_{t_n+g_n(\tau)}^\theta(\hat{\mathbf{y}}_{t_n, g_n(\tau)}^{(K-1)}(\omega)) - \nabla \log \tilde{p}_{t_n+\tau}(\hat{\mathbf{y}}_{t_n+\tau}^{(K)}(\omega));$$

Main Results

Proof Sketch

In n -th block, let $q|_{\mathcal{F}_{t_n}}$ be the measure shared by $\mathbf{w}_t(\omega)$ in the Picard iteration

- 1 Define $d\tilde{\mathbf{w}}_{t_n+\tau}(\omega) = d\mathbf{w}_{t_n+\tau}(\omega) + \boldsymbol{\delta}_{t_n}(\tau, \omega)d\tau$, where

$$\boldsymbol{\delta}_{t_n}(\tau, \omega) := \mathbf{s}_{t_n+g_n(\tau)}^\theta(\hat{\mathbf{y}}_{t_n, g_n(\tau)}^{(K-1)}(\omega)) - \nabla \log \tilde{p}_{t_n+\tau}(\hat{\mathbf{y}}_{t_n+\tau}^{(K)}(\omega));$$

- 2 Invoke Girsanov's theorem

$$\log \frac{d\tilde{p}|_{\mathcal{F}_{t_n}}}{dq|_{\mathcal{F}_{t_n}}}(\omega) = - \int_0^{h_n} \boldsymbol{\delta}_{t_n}(\tau, \omega)^\top d\mathbf{w}_{t_n+\tau}(\omega) - \frac{1}{2} \int_0^{h_n} \|\boldsymbol{\delta}_{t_n}(\tau, \omega)\|^2 d\tau;$$

Main Results

Proof Sketch

In n -th block, let $q|_{\mathcal{F}_{t_n}}$ be the measure shared by $\mathbf{w}_t(\omega)$ in the Picard iteration

- 1 Define $d\tilde{\mathbf{w}}_{t_n+\tau}(\omega) = d\mathbf{w}_{t_n+\tau}(\omega) + \boldsymbol{\delta}_{t_n}(\tau, \omega)d\tau$, where

$$\boldsymbol{\delta}_{t_n}(\tau, \omega) := \mathbf{s}_{t_n+g_n(\tau)}^\theta(\hat{\mathbf{y}}_{t_n, g_n(\tau)}^{(K-1)}(\omega)) - \nabla \log \tilde{p}_{t_n+\tau}(\hat{\mathbf{y}}_{t_n+\tau}^{(K)}(\omega));$$

- 2 Invoke Girsanov's theorem

$$\log \frac{d\tilde{p}|_{\mathcal{F}_{t_n}}(\omega)}{dq|_{\mathcal{F}_{t_n}}(\omega)} = - \int_0^{h_n} \boldsymbol{\delta}_{t_n}(\tau, \omega)^\top d\mathbf{w}_{t_n+\tau}(\omega) - \frac{1}{2} \int_0^{h_n} \|\boldsymbol{\delta}_{t_n}(\tau, \omega)\|^2 d\tau;$$

- 3 Conclude that $(\tilde{\mathbf{w}}_{t_n+\tau})_{\tau \geq 0}$ is a Wiener process under $\tilde{p}|_{\mathcal{F}_{t_n}}$ and thus:

$$d\hat{\mathbf{y}}_{t_n, \tau}^{(K)}(\omega) = \left[\frac{1}{2} \hat{\mathbf{y}}_{t_n, \tau}^{(K)}(\omega) + \nabla \log \tilde{p}_{t_n+\tau}(\hat{\mathbf{y}}_{t_n, \tau}^{(K)}(\omega)) \right] d\tau + d\tilde{\mathbf{w}}_{t_n+\tau}(\omega),$$

i.e. the true backward SDE with the true score function for $\tau \in [t_n, t_{n+1}]$.

Conclusion

Empirical Results

- › Picard iteration with adaptive window size [SBE⁺24]
- › Triangular Anderson acceleration [TTL⁺24]

Takeaways

- › **Parallelized inference algorithm** for both SDE and PF-ODE implementations

Conclusion

Empirical Results

- Picard iteration with adaptive window size [SBE⁺24]
- Triangular Anderson acceleration [TTL⁺24]

Takeaways

- **Parallelized inference algorithm** for both SDE and PF-ODE implementations
- Convergence analysis that achieves the **first poly-logarithmic error bound** for diffusion models with generalized Girsanov's theorem

Conclusion

Empirical Results

- › Picard iteration with adaptive window size [SBE⁺24]
- › Triangular Anderson acceleration [TTL⁺24]

Takeaways

- › **Parallelized inference algorithm** for both SDE and PF-ODE implementations
- › Convergence analysis that achieves the **first poly-logarithmic error bound** for diffusion models with generalized Girsanov's theorem
- › **Improved space complexity** for PF-ODE implementation with predictor-corrector from $\tilde{\mathcal{O}}(d^2)$ to $\tilde{\Theta}(d^{3/2})$








Thank you for your attention!

References I

-  Nima Anari, Sinho Chewi, and Thuy-Duong Vuong, *Fast parallel sampling under isoperimetry*, arXiv preprint arXiv:2401.09016 (2024).
-  Joe Benton, Valentin De Bortoli, Arnaud Doucet, and George Deligiannidis, *Linear convergence bounds for diffusion models via stochastic localization*, arXiv preprint arXiv:2308.03686 (2023).
-  Sitan Chen, Sinho Chewi, Holden Lee, Yuanzhi Li, Jianfeng Lu, and Adil Salim, *The probability flow ode is provably fast*, Advances in Neural Information Processing Systems **36** (2024).
-  Tim Dockhorn, Arash Vahdat, and Karsten Kreis, *Genie: Higher-order denoising diffusion solvers*, Advances in Neural Information Processing Systems **35** (2022), 30150–30166.
-  Tero Karras, Miika Aittala, Timo Aila, and Samuli Laine, *Elucidating the design space of diffusion-based generative models*, Advances in Neural Information Processing Systems **35** (2022), 26565–26577.

References II

-  Gen Li, Yu Huang, Timofey Efimov, Yuting Wei, Yuejie Chi, and Yuxin Chen, *Accelerating convergence of score-based diffusion models, provably*, arXiv preprint arXiv:2403.03852 (2024).
-  Eric Luhman and Troy Luhman, *Knowledge distillation in iterative generative models for improved sampling speed*, arXiv preprint arXiv:2101.02388 (2021).
-  Cheng Lu and Yang Song, *Simplifying, stabilizing and scaling continuous-time consistency models*, arXiv preprint arXiv:2410.11081 (2024).
-  Chenlin Meng, Robin Rombach, Ruiqi Gao, Diederik Kingma, Stefano Ermon, Jonathan Ho, and Tim Salimans, *On distillation of guided diffusion models*, Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition, 2023, pp. 14297–14306.
-  Andy Shih, Suneel Belkhale, Stefano Ermon, Dorsa Sadigh, and Nima Anari, *Parallel sampling of diffusion models*, Advances in Neural Information Processing Systems **36** (2024).

References III

-  Yang Song and Prafulla Dhariwal, *Improved techniques for training consistency models*, arXiv preprint arXiv:2310.14189 (2023).
-  Yang Song, Prafulla Dhariwal, Mark Chen, and Ilya Sutskever, *Consistency models*, arXiv preprint arXiv:2303.01469 (2023).
-  Jiaming Song, Chenlin Meng, and Stefano Ermon, *Denoising diffusion implicit models*, arXiv preprint arXiv:2010.02502 (2020).
-  Zhiwei Tang, Jiasheng Tang, Hao Luo, Fan Wang, and Tsung-Hui Chang, *Accelerating parallel sampling of diffusion models*, arXiv preprint arXiv:2402.09970 (2024).
-  Qinsheng Zhang and Yongxin Chen, *Fast sampling of diffusion models with exponential integrator*, arXiv preprint arXiv:2204.13902 (2022).
-  Hongkai Zheng, Weili Nie, Arash Vahdat, Kamyar Azizzadenesheli, and Anima Anandkumar, *Fast sampling of diffusion models via operator learning*, International Conference on Machine Learning, PMLR, 2023, pp. 42390–42402.