Achievable distributional robustness when the robust risk is only partially identified

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Out-of-domain generalization





Training distribution \mathbb{P}_{train}





Test distribution \mathbb{P}_{test}

Out-of-domain generalization





Low training risk

Training distribution \mathbb{P}_{train}



 $\beta_{\text{train}} = \arg\min_{\beta} \mathcal{R}(\beta; \mathbb{P}_{\text{train}}) \quad \mathcal{R}(\beta_{\text{train}}; \mathbb{P}_{\text{test}}) \gg \min_{\beta} \mathcal{R}(\beta; \mathbb{P}_{\text{test}})$ High test risk





Distributional robustness

Goal: given training data, generalize to a set of feasible test distributions, called robustness set, by computing a minimiser of the robust risk

$$\beta_{\text{rob}} = \arg\min_{\beta} \left[\mathscr{R}_{\text{rob}}(\beta; \mathscr{P}_{\text{rob}}(\theta_{\star})) := \sup_{\mathbb{P} \in \mathscr{P}_{\text{rob}}(\theta_{\star})} \mathscr{R}(\beta; \mathbb{P}) \right]$$

In previously considered robustness scenarios, the parameters θ_{\star} and/or the robustness set $\mathscr{P}_{rob}(\theta_{\star})$ are considered to be **known**:

Distributionally robust optimization

$\mathcal{P}_{rob}(\mathbb{P}_{train})$
Ptrain

δ

$\begin{aligned} \theta_{\star} &= \mathbb{P}_{\text{train}}; \\ \mathscr{P}_{\text{rob}}(\theta_{\star}) &= \{\mathbb{P}: D(\mathbb{P}, \mathbb{P}_{\text{train}}) \leq \delta\} \end{aligned}$

Often, θ_{\star} and/or $\mathscr{P}_{rob}(\theta_{\star})$ are neither known nor computable from training data



Set of possible model parameters

Instead, they can be merely set identified.

Set of possible robust risks

We propose to minimise a new objective called the identifiable robust risk:

Best achievable distributional robustness:

 $\mathcal{R}_{\text{rob,ID}}(\beta; \Theta_{\text{eq}}) := \sup_{\substack{\theta \in \Theta_{\text{eq}}}} \sup_{\mathbb{P} \in \mathscr{P}_{\text{rob}}(\theta)} \mathcal{R}(\beta, \mathbb{P})$

 $\mathfrak{M}(\Theta_{eq}) = \inf_{\beta \in \mathbb{R}^d} \mathscr{R}_{rob,ID}(\beta; \Theta_{eq})$

Setting of structural causal models

Data model: linear structural causal model (SCM) with unobserved confounding, environments differ via additive shifts A^e :



$$A^e + \eta;$$

 $X^e =$

 $Y^e = \beta_{\downarrow}^{\top} X^e + \xi,$

Setting of structural causal models

Some structural knowledge about the strength and direction of the test shift:

 $\mathbb{E}[A^{\text{test}}A^{\text{test}}]^{\top}$





$$] \leq M_{\text{test}} = \gamma \Pi_{\mathscr{M}}.$$

- Infinite robustness to arbitrary shifts only possible if β_{\star} known (requires $\mathcal{O}(d)$ env's)
- •However, β_{\star} only identified on



Identifiable robustness for the SCM setting

We compute the identifiable robust risk explicitly:

$$\mathscr{R}_{rob,ID}(\beta;\Theta_{eq},\gamma\Pi_{\mathscr{M}}) = \mathscr{R}(\beta;\theta_{\star}) - \mathcal{R}(\beta;\theta_{\star}) - \mathcal{R}(\beta;\theta_{\star}) = \mathscr{R}(\beta;\theta_{\star}) - \mathcal{R}(\beta;\theta_{\star}) - \mathcal{R}(\beta;\theta$$

where:

- S: test shift directions along which the causal model can be identified
- R: test shift directions along which the model is non-identifiable
- $C_{\rm ker}$: max. norm of the model along non-identified directions

 $+ \gamma \|S^{\top}(\beta^{\mathscr{S}} - \beta)\|_{2}^{2} + \gamma (C_{ker} + \|R^{\top}\beta\|_{2})^{2},$ Invariance term **Non-identifiability term**

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Identifiable robustness for the SCM setting

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- We prove a **lower bound** for the id. robust risk which is tight for large γ ;
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Invariance term

Non-identifiability term

• For large γ , we prove suboptimality of existing robustness methods such as anchor regression [Rothenhäusler et al. 2021] and DRIG [Shen et al.

Simulations on Gaussian SCM data:



Experiments on real-world gene expression dataset [Replogle et al. 2022]:



Methods: \rightarrow Rob-ID \rightarrow Anchor \rightarrow DRIG \rightarrow ICP \rightarrow OLS

Outlook

- Extension to classification
- Nonlinear models
- Use for active intervention selection
- Partially identifiable framework beyond causality



