Sirine Ayadi $*^{1,2}$

Fabian Theis $1,2,3$

Reference

Unconditional Samples

Leon Hetzel* $1,2,3$

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Stephan Günnemann $1,2$

Guided Samples

https://www.cs.cit.tum.de/daml/uniguide/

Diffusion models for drug design Equivariant (unconditional) diffusion model for 3D molecule generation

- coordinates: X
- atom types: $\mathbf h$
- configuration: **Z**

Hoogeboom, E., Satorras, V. G., Vignac, C., & Welling, M. (2022, June). Equivariant diffusion for molecule generation in 3D.

Diffusion models for drug design

Extending unconditional diffusion models for molecules to various conditioning tasks

Controlling diffusion models

Previous diffusion-based methods are limited to a single drug design task

Conditional Diffusion Models

- ◆ Does not require extra training
- **X** Requires external model for guidance
- **X** External model has to be trained on noisy states of the diffusion process

- Require conditional training per task
- **X** Require task-specific data
- **X** Extra training might be required to find a suitable condition representation

Previous Work

Previous

Work

Guiding Diffusion Models

Self-guiding diffusion models

5

πп

Incorporating the condition c to the unconditional model $\epsilon_{\theta}(\mathbf{z}_t, t)$ during inference

$$
= \frac{p_{\theta}(\mathbf{z}_t) p_{\theta}(\mathbf{c} | \mathbf{z}_t)}{p(\mathbf{c})}
$$

$$
\frac{\log p_{\theta}(\mathbf{z}_t) + S \nabla_{\mathbf{z}_t} \log p_{\theta}(\mathbf{c} \,|\, \mathbf{z}_t)}{\sqrt{1 - \bar{\alpha}_t}}
$$

$$
{t},t)-\sqrt{1-\bar{\alpha}{t}}S\,\nabla_{\mathbf{z}_{t}}\mathrm{log}\,p_{\theta}(\boldsymbol{c}\,|\,\mathbf{z}_{t})
$$

Self-guiding diffusion models

Incorporating the condition c to the unconditional model $\epsilon_{\theta}(\mathbf{z}_t, t)$ during inference

Self-guided diffusion model $\hat{\boldsymbol{\epsilon}}_{\theta}(\mathbf{z}_t, t, \boldsymbol{c}) = \boldsymbol{\epsilon}_{\theta}(\mathbf{z}_t)$

$$
z_t) = \mathcal{N}\big(\boldsymbol{c} \,|\, \boldsymbol{f}_\theta(\mathbf{z}_t, t), \boldsymbol{I}\big)
$$

$$
\frac{\mathbf{z}_t - \sqrt{1 - \bar{\alpha}_t} \,\boldsymbol{\epsilon}_{\theta}(\mathbf{z}_t, t)}{\sqrt{\bar{\alpha}_t}} = \hat{\mathbf{z}}_0
$$

$$
,t)+\lambda _{t}\,S\,\nabla _{\mathbf{z}_{t}}\big\Vert \hat{\mathbf{z}}_{0}-\boldsymbol{c}\big\Vert _{2}^{2}
$$

Assumption

 $p_{\theta}(\boldsymbol{c} | \mathbf{z})$

Use clean data point approximation

$$
\bm{f}_{\theta}(\mathbf{z}_t, t) =
$$

Guiding signal reduces to squared error

$$
\nabla_{\mathbf{z}_t} \log p_{\theta}(\mathbf{c} \,|\, \mathbf{z}_t) = -\frac{1}{2} \nabla_{\mathbf{z}_t} \left\| \mathbf{z}_t \right\| \mathbf{z}_t
$$
\nThe condition must lie in the configuration space

UniGuide: A unified guidance framework

The condition map transforms arbitrary source conditions to suitable guidance targets

UniGuide: A unified guidance framework

Compute projection on surface from closest neighbours

$$
\bar{\boldsymbol{y}}_i = \frac{1}{k} \sum_{j \in \mathcal{N}_{\hat{\boldsymbol{x}}}_i} R_{\hat{\mathbf{x}}_0} \boldsymbol{y}_j \quad ,
$$

with $\mathcal{N}_{\hat{x}_i} = \arg \min_{I \subset \{1, ..., K\}, |I| = k} \sum_{i \in I} ||R_{\hat{x}_0} y_j - \hat{x}_i||_2$

Compute the (point-wise) target condition

$$
c_{\mathbf{x},i} = \begin{cases} \bar{y}_i + \frac{\alpha}{d}(\bar{y}_i - \hat{x}_i), & \text{if } \hat{x}_i \text{ outside } V \\ \bar{y}_i - \frac{\alpha}{d}(\bar{y}_i - \hat{x}_i), & \text{if } \hat{x}_i \text{ inside } V \wedge d < \alpha \\ \hat{x}_i, & \text{otherwise}, \end{cases}
$$

Surface Condition Map (LBDD)

Sample points y from the surface

$$
C_{\partial V} : \mathbb{R}^{K \times 3} \times \mathbb{R}^{N \times 3} \to \mathbb{R}^{N \times 3}
$$

$$
\mathbf{y} \times \hat{\mathbf{x}}_0 \quad \mapsto \mathbf{c}_{\mathbf{x}} \quad ,
$$

Figure: Surface Condition Map $C_{\partial V}$: For every atom x_i , the closest surface points y_j are computed.

The condition map transforms arbitrary source conditions to suitable guidance targets

UniGuide: A unified guidance framework

Special Case $S = Z$
Ensure equivalent update
$C_Z: \mathbb{R}^{m \times (3+d)} \times \mathbb{R}^{m \times (3+d)} \rightarrow \mathbb{R}^{m \times (3+d)}$
$\tilde{z} \times \hat{z}_0^{\mathcal{A}} \rightarrow T_{\hat{z}_0^{\mathcal{A}}}\tilde{z}$
SBDD
$C_Z(\tilde{z}^{\mathcal{P}}, \hat{z}_t^{\mathcal{P}}) = T_{\hat{z}_t^{\mathcal{P}}}\tilde{z}^{\mathcal{P}}$

\nFBDD

\n
$$
C_Z(\tilde{z}^{\mathcal{A}}, \hat{z}_t^{\mathcal{A}}) = T_{\hat{z}_t^{\mathcal{A}}}\tilde{z}^{\mathcal{A}}
$$
\n
$$
\mathcal{A} = \mathcal{P} \cup \mathcal{F}
$$

Compute projection on surface from closest neighbours

$$
\bar{\boldsymbol{y}}_i = \frac{1}{k} \sum_{j \in \mathcal{N}_{\hat{\boldsymbol{x}}}_i} R_{\hat{\mathbf{x}}_0} \boldsymbol{y}_j \quad ,
$$

with $\mathcal{N}_{\hat{\boldsymbol{x}}_i} = \arg \min_{I \subset \{1, ..., K\}, |I| = k} \sum_{i \in I} \|R_{\hat{\mathbf{x}}_0} \boldsymbol{y}_j - \hat{\boldsymbol{x}}_i\|_2$

Compute the (point-wise) target condition

$$
c_{\mathbf{x},i} = \begin{cases} \bar{y}_i + \frac{\alpha}{d}(\bar{y}_i - \hat{x}_i), & \text{if } \hat{x}_i \text{ outside } V \\ \bar{y}_i - \frac{\alpha}{d}(\bar{y}_i - \hat{x}_i), & \text{if } \hat{x}_i \text{ inside } V \wedge d < \alpha \\ \hat{x}_i, & \text{otherwise}, \end{cases}
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$$

Figure: Surface Condition Map $C_{\partial V}$: For every atom x_i , the closest surface points y_j are computed.

The condition map transforms arbitrary source conditions to suitable guidance targets

Guiding an off-the-shelf EDM model for LBDD shows superior performance, even to Virtual Screening.

Results: Ligand-Based Drug Design

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Results: Structure-Based Drug Design UniGuide outperforms different diffusion-based conditioning approaches.

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Quantitative Comparison on CrossDocked. We highlight in **bold** the best approach given the same backbone and underline the best approach overall.

Generated

VINA Dock: -10.2

Results: Fragment-Based Drug Design UniGuide is readily applicable to various FBDD settings in a unified fashion

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