



# Are High-Degree Representations Really Unnecessary in

Equivariant Graph Neural Networks?

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# Global Features in Geometric GNNs





**(c) Virtual Nodes** in FastEGNN (ICML'24)

**(d) Mesh** in Neural P3M (NeurIPS'24)



# Symmetric Graph









**C60 & Carbon Nanotube**



Dodecahedron Icosahedron

Figure 1: Common symmetric graphs. Equivariant GNNs on symmetric graphs will degenerate to a zero function if the degree of their representations is fixed as 1.

### **Symmetrical Structure**

**Coincides with itself under certain transformations**

 $\forall \mathfrak{h} \in \mathfrak{H}, \mathfrak{h} \cdot \mathcal{G} = \mathcal{G}$ 



# The Degeneration Phenomenon







Theoretical Results





**Symmetrical Structure**

**Coincides with itself under certain transformations**

 $\forall \mathfrak{h} \in \mathfrak{H}, \mathfrak{h} \cdot \mathcal{G} = \mathcal{G}$ 

Using the definition of **symmetric structure** and **equivariant function**, we can get the equation

$$
f^{(l)}(\mathcal{G}) = f^{(l)}(\mathfrak{h} \cdot \mathcal{G})
$$
  
=  $\rho^{(l)}(\mathfrak{h}) \cdot f^{(l)}(\mathcal{G})$   
=  $\left(\frac{1}{|\mathfrak{H}|} \sum_{\mathfrak{h} \in \mathfrak{H}} \rho^{(l)}(\mathfrak{h})\right) \cdot f^{(l)}(\mathcal{G})$   
 $\stackrel{\triangle}{=} \rho^{(l)}(\mathfrak{H}) f^{(l)}(\mathcal{G})$ 

Note that the types of point groups are **finite**, so we only need to **enumerate all the groups** to represent the average.







**Symmetrical Structure**

**Coincides with itself under certain transformations**

 $\overline{\forall} \overline{\mathfrak{h}} \in \mathfrak{H}, \mathfrak{h} \cdot \mathcal{G} = \mathcal{G}$ 

Using the definition of **symmetric structure** and **equivariant function**, we can get the equation  $(I_{2l+1} - \rho^{(l)}(\mathfrak{H})) f^{(l)}(\mathcal{G}) = 0$ **The Degeneration Left Matrix is full-rank Phenomenon** det  $(I_{2l+1} - \rho^{(l)}(\mathfrak{H}) \rvert \neq 0$  $f^{(l)}(\mathcal{G})\equiv 0$ 

Note that the types of point groups are **finite**, so we only need to **enumerate all the groups** to represent the average.



Motivation for HEGNN



#### **Trace of point group average representation**



#### **Prediction of degenerate results for various symmetric graphs**



#### **Difficulties**

 Previous models generate **all representations of**   $|l_1 - l_2|$  ~  $l_1 + l_2$  through CG tensor product, and cannot extract representations of special orders for verification

### **Additional requirements**

- Can the model used for verification have **good application value**? For example, use it on **actual datasets**?
- $\triangleright$  Traditional high-order models use CG tensor products, with a complexity of up to  $O(L^6)$ , Can we design a model with **lower complexity**?
- Can you explain the **theoretical basis** for using high-order representations other than distinguishing symmetric structures?





**HEGNN**: Use the scalarization-trick to introduce high-order representations, which reduce the time complexity to  $O(L^2)$  from  $O(L^6)$  of CG tensor-product

- $\triangleright$  Initialization: Use spherical harmonics and calculate coefficients for different orders
- Expression ability: Use the relationship between spherical harmonics and Legendre polynomials to prove that **HEGNN can fully express all inner product information of geometric graphs**





Architecture of HEGNN



**Initialization of high-degree steerable feature**

$$
\tilde{\bm{v}}_{i,\mathtt{init}}^{(l)} = \frac{1}{|\mathcal{N}(i)|}\sum_{j \in \mathcal{N}(i)} \varphi_{\tilde{\bm{v}},\mathtt{init}}^{(l)}(\bm{m}_{ij,\mathtt{init}}) \cdot Y^{(l)} \Big( \tfrac{\vec{x}_i}{\|\vec{x}_i\|}
$$

**Calculation of cross-degree invariant messages**

$$
d_{ij} = \|\vec{x}_i - \vec{x}_j\|, \quad z_{ij}^{(l)} = \left\langle \tilde{v}_i^{(l)}, \tilde{v}_j^{(l)} \right\rangle, \quad \boldsymbol{m}_{ij} = \varphi_{\boldsymbol{m}} \left( \boldsymbol{h}_i, \boldsymbol{h}_j, \boldsymbol{e}_{ij}, d_{ij}^2, \oplus_{l=0}^L z_{ij}^{(l)} \right)
$$

**Aggregation of neighbor messages**

$$
\Delta \bm{h}_i = \varphi_{\bm{h}} \left( \bm{h}_i, \frac{1}{|\mathcal{N}(i)|} \sum_{j \in \mathcal{N}(i)} \bm{m}_{ij} \right), \ \Delta \vec{\bm{x}}_i = \frac{1}{|\mathcal{N}(i)|} \sum_{j \in \mathcal{N}(i)} \varphi_{\vec{\bm{x}}}(\bm{m}_{ij}) \cdot (\bm{\vec{x}}_i - \vec{\bm{x}}_j), \\ \Delta \tilde{\bm{v}}_i^{(l)} = \sqrt{\mathcal{N}(i)} \sum_{j \in \mathcal{N}(i)} \varphi_{\tilde{\bm{v}}}^{(l)}(\bm{m}_{ij}) \cdot \left( \tilde{\bm{v}}_i^{(l)} - \tilde{\bm{v}}_j^{(l)} \right)
$$

**Aggregation of neighbor messages**

$$
\displaystyle \mathbb{B}_{l=0}^{L} \Delta \tilde{\bm{v}}_i^{(l)} = \frac{1}{|\mathcal{N}(i)|} \sum_{j \in \mathcal{N}(i)} 1 \otimes_{\text{cg}}^{\varphi_{\tilde{\bm{v}}}(\bm{m}_{ij})} \left( \oplus_{l=0}^{L} \left( \tilde{\bm{v}}_i^{(l)} - \tilde{\bm{v}}_j^{(l)} \right) \right)
$$





Architecture of HEGNN





Theorem 4.1. For any geometric graph, there exists a bijection between the set of inner products  $\{z_{ij}^{(l)}\}_{l=1}^{|\mathbb{A}_{ij}|}$  given by Eq. (10) and the set of edge angles  $\mathbb{A}_{ij} = \{\theta_{is,jt} \coloneqq \langle \vec{x}_{is}, \vec{x}_{jt} \rangle\}_{s \in \mathcal{N}(i), t \in \mathcal{N}(j)}$ .  $\left\langle \sum_{s \in \mathcal{N}(i)} Y^{(l)}(\vec{x}_{is}) \, , \sum_{t \in \mathcal{N}(j)} Y^{(l)}(\vec{x}_{jt}) \right\rangle = \frac{4\pi}{2l+1} \sum_{s \in \mathcal{N}(i)} \sum_{t \in \mathcal{N}(j)} P^{(l)}(\langle \vec{x}_{is}, \vec{x}_{jt} \rangle) \, ,$ 



## Experiments



 $0.91 \pm 0.06$   $10.56 \pm 0.05$   $0.55 \pm 0.01$ 

 $0.94 \pm 0.10$   $10.55 \pm 0.16$   $0.52 \pm 0.01$ 

 $0.88 \pm 0.02$  10.56 $\pm$ 0.33 0.54 $\pm$ 0.01

## **Symmetric polyhedron experiment: Theoretical and experimental results are completely consistent**









 $k$ -fold (odd)  $k$ -fold (even) Tetrahedron Cube(Hexahedron) Octahedron

Dodecahedron **Icosahedron** 



# **N-body (N=5, 20, 50, 100): consistently outperforms other models**

HEGNN<sub> $l \leq 2$ </sub> 10.04 $\pm$ 0.45 61.80 $\pm$ 5.92 4.63 $\pm$ 0.01

HEGNN<sub> $l \leq 3$ </sub> 10.20 $\pm$ 0.23 62.82 $\pm$ 4.25 4.63 $\pm$ 0.01

HEGNN<sub> $l \leq 6$ </sub> 9.94 $\pm$ 0.07 59.93 $\pm$ 5.21 4.62 $\pm$ 0.01

## **MD-17: outperforms most molecules (6/8)**



 $12.85 \pm 0.01$ 

 $12.85 \pm 0.02$ 

 $12.85 \pm 0.01$ 

 $0.39 + 0.01$ 

 $0.37_{\pm 0.01}$ 

 $0.37\scriptstyle\pm 0.02$ 





Most molecules may **not be symmetrical**, and even affected by molecular vibration, the structural changes are enough to **eliminate the original symmetry**.

So what are the **advantages of HEGNN** at this time? The answer is **better robustness**!

Table 5: Take the tetrahedron as an example and compare the cases of EGNN,  $\text{HEGNN}_{l=3}$ , and HEGNN<sub> $l < 3$ </sub> when adding noise perturbations. Here,  $\varepsilon$  represents the ratio of noise, and the modulus of the noise obeys  $\mathcal{N}(0, \varepsilon \cdot \mathbb{E}[\|\vec{x} - \vec{x}_c\|] \cdot I)$ . It can be observed that the performance of EGNN is slightly improved in the presence of noise (from 50% when  $\varepsilon = 0.01$  to 60% when  $\varepsilon = 0.5$ ), while **HEGNN** demonstrates better robustness.





## Reference



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