FedAvP: Augment Local Data via Shared Policy in Federated Learning

Minui Hong

Seoul National University

Junhyeog Yun

Seoul National University

Insu Jeon

Seoul National University

Gunhee Kim

Seoul National University

Motivation

- Federated Data Augmentation Aim to increase **the diversity and volume of data** available at each client, thereby improving overall performance of the federated models.
- Sharing input-level or feature-level information can **raise privacy concerns**.

Background : Reconstruction Attack

• Assume we have a given gradient $\mathcal{V}W(x, y)$, then we can optimize **for a dummy data** and label pair (x', y') by minimizing the following objective[1]:

[1] Zhu, L., et al. "Deep leakage from gradients", NeurlPS 2019 [Fig] Federated learning training process, https://ai.sony/blog/blog-032/

Motivation

You can set all, ICLR'21

\n
$$
x^*, y^* = \operatorname*{argmin}_{x', y'} \frac{[(1-\alpha) \cdot (1 - \ell(\nabla W(x, y), \nabla W(x', y')))}{+\alpha \cdot ||x' - x_{mean}||}
$$
\nMean Image

$$
\text{Zhu, Z., et al., PMLR'}21 \qquad \qquad x^*, y^* = \underset{x', y'}{\text{argmin}} \quad \frac{[(1 - \alpha - \beta) \cdot (1 - \ell(\nabla W(x, y), \nabla W(x', y')))}{x', y' + \alpha \cdot |c - y'| + \beta \cdot (1 - \ell(W^p(z|z \sim G(y')), W(x'))]} \quad \text{Label & Generation}
$$

Zhou & Konukoglu, ICLR'23
$$
x^*, y^* = \underset{x',y'}{\operatorname{argmin}} \frac{[(1-\alpha-\beta)\cdot(1-\ell(\nabla W(x,y),\nabla W(x',y')))}{+\alpha \cdot \mathbb{E}_k ||\bar{\mu}^k - \mu^{k'}|| + \beta \cdot \mathbb{E}_k ||\bar{\sigma}^k - \sigma^{k'}||]}
$$

Feature Statistics

[1] Yoon, Tehrim, et al. "FedMix: Approximation of Mixup under Mean Augmented Federated Learning.", ICLR 2021 [3] Zhou & Konukoglu. "FedFA: Federated Feature Augmentation.", ICLR 2024 [2] Zhuangdi Zhu, Junyuan Hong, and Jiayu Zhou. "Data-free knowledge distillation for heterogeneous federated learning.", PMLR 2021

Our Idea

- Instead of directly sharing raw data between clients, we share Data **Augmentation Policies**.
- Augmentation Policies include the types and intensities of image transformations such as translation, shear, and flipping.

- One round of local training and aggregation is considered an **inner step**.
- Validation on clients after each global model update servers as the **outer step**.

(a) Our Federated Meta Policy Loss(FMPL)

Meta Policy Loss can be computed locally

(b) First-order Approximation of FMPL

- Accessing other clients' gradients raises **privacy and communication** concerns.
- To address this, we apply **a firstorder approximation.**

• We apply a first-order approximation via Taylor expansion, **reducing both privacy risks and communication overhead.**

Consider the federated meta-policy loss derived from the updated weight w_n^k for client k at step n *using a first-order Taylor expansion:*

$$
\ell_{D_k^{val}}(w_{g_{r+1}}) \approx \ell_{D_k^{val}}(w_n^k) + \nabla \ell_{D_k^{val}}(w_n^k)^T (w_{g_r} - w_n^k).
$$

When computing the policy gradient of the loss with respect to θ_{n-1}^k , the first-order gradient *approximation is*

$$
-\alpha_k \cdot lr\frac{\partial (\nabla \ell_{p^{val}_{k}}(w^{k}_{n})^{T} \nabla \ell_{tp_{\frac{\theta^{k}_{n-1}}{\theta^{k}_{n-1}}}(p^{train}_{k,n-1})^{(w^{k}_{n-1}))}}}{\partial \theta^{k}_{n-1}},
$$

where $w_n^k = w_{g_r} - lr \cdot g_{w_0^k}^{au}$ \boldsymbol{k} $\frac{aug}{w_0^k} - \cdots - lr \cdot g^{aug}_{w_{n-1}^k}$ $\lim_{\mu,k}$ and α_k is a coefficient proportional to the client's *data size.*

• We update our policy as done in Reptile[1]. Our algorithm **allows for** rapid adaptation of a personalized policy by each client.

We train the policy neural network by increasing the dot-product between policy gradients on each client as follows:

$$
\theta_{g_{r+1}} \approx \theta_{g_r} - \eta \lambda \frac{\partial}{\partial \theta_0^k} \mathbb{E} \left[\sum_{j=1}^n L_{k,j} - \frac{\lambda}{2} \sum_{j=0}^n \sum_{s=0}^{j-1} \langle \nabla L_{k,j} \cdot \nabla L_{k,s} \rangle \right],
$$

where $L_{k,j} = \ell_{D_{k,j}^{va}}^{FMl}$ $_{D_r^{val}}^{FMLPL}(\theta_0^k)$ is the federated meta-policy loss computed on the client k's j-th *validation data batch using the global policy parameters* θ_0^k *.*

[1] Nichol, Alex, Joshua Achiam, and John Schulman. "On first-order meta-learning algorithms." arXiv 2018.

Experiments

• Non-IID Classification Results. • Results with a larger model.

• Visualization of global policies.

Experiments

• Reconstruction attack results. • Computation and comm. cost.

Thank you

Code: https://github.com/alsdml/FedAvP