Identifiability Guarantees for Causal Disentanglement from Purely Observational Data

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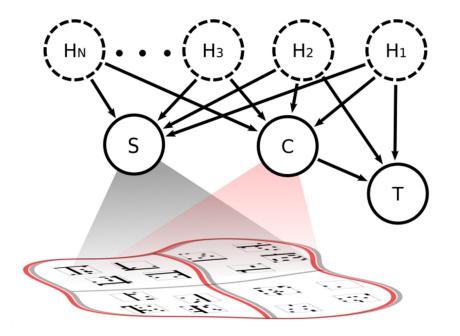


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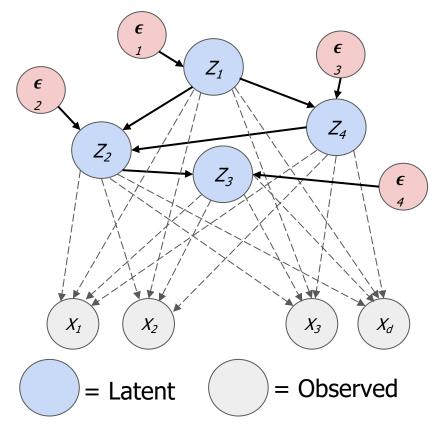
### Motivation

<u>Causal disentanglement</u> aims to uncover the underlying causal mechanisms present in complex, unobserved systems.



Particularly useful in learning complicated gene regularly networks

#### Nonlinear Additive Gaussian Equation Models



$$Z_i = f_i(Z_{pa(i)}) + \mathcal{E}_i, \qquad \forall i \in [n]$$

• 
$$\mathcal{E}_i \sim \mathcal{N}(0, \sigma_i^2)$$
 ,  $f_i$  is nonlinear

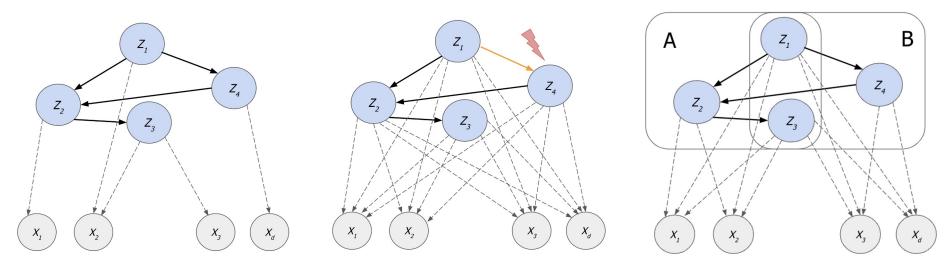
• Observed 
$$X = g(Z)$$

• 
$$g = H \in \mathbb{R}^{n \times d}$$
 is linear

## Latent factors are identifiable with...

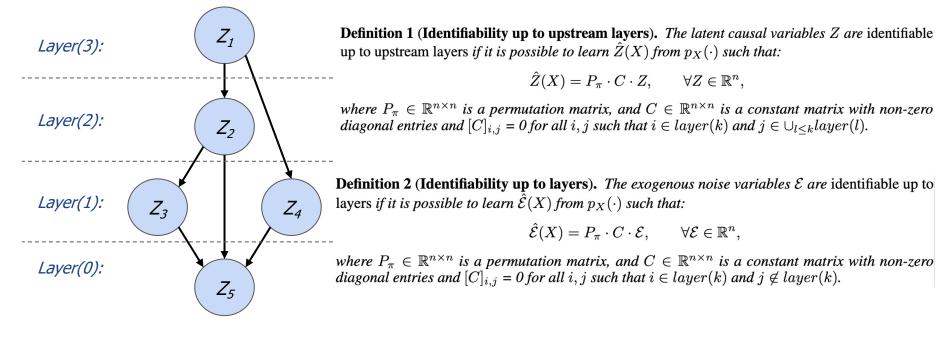
<u>Graphical constraints</u> on the mixing process Access to atomic interventions

#### *Data from m<u>ultiple</u> <u>modalities</u>*



#### What is identifiable without any of the above assumptions?

## Layer-wise Identifiability



**Layers of a causal DAG**. A latent variable is contained in layer(k) if its longest path to a lead node is is length k.

### **Preview of Main Results**

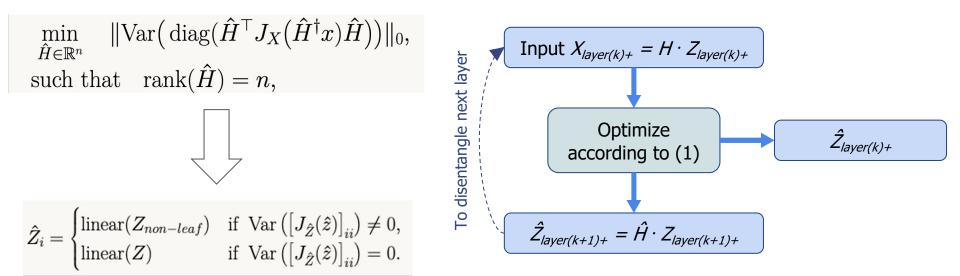
**Theorem 1.** Under Assumptions 1 and 2, the latent variables Z are identifiable up to their upstream layers from purely observational data.

**Theorem 2.** Under Assumptions 1 and 2, the exogenous noise variables  $\mathcal{E}$  are identifiable up to their layers from purely observational data.

**Proposition 1.** Under Assumptions 1 and 2, the exogenous noise variables  $\mathcal{E}$  are generally unidentifiable beyond layer-wise transformation from observational data.

Assumption 1: Linear mixing Assumption 2: Nonlinear additive Gaussian noise model

#### Learning Latent Variable Representations



## Quadratic Programming on Estimated Scores

Can solve as a <u>rank-constrained</u> optimization problem:

 $\hat{H} = \arg \min_{\hat{H} \in \mathbb{R}^n} \quad \left\| Var \left( diag(J_{\hat{Z}}(\hat{H}^{\dagger}x)) \right) \right\|_0,$  such that  $\operatorname{rank}(\hat{H}) = n$ 

Can solve iteratively by column as a <u>QCQP</u>:

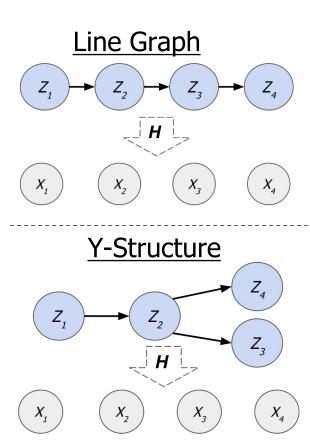
$$\begin{split} [\hat{H}]_i &= \arg\min_{h\in\mathbb{R}^n} \quad 0\\ &\text{such that} \quad h^{\top}\tilde{J}_X(x^{(m)})h = 0, \quad \forall m \in [N],\\ &h^{\top}h = 1,\\ &h^{\top}[\hat{H}]_j = 0, \quad \forall j \in [i-1], \end{split}$$
where  $\tilde{J}_X(x^{(m)}) \triangleq \hat{J}_X(x^{(m)}) - \left(\frac{1}{N}\sum_{m=1}^N \hat{J}_X(x^{(m)})\right)$ 

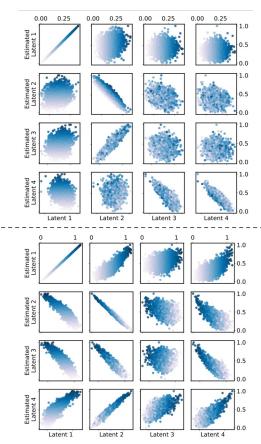
**Discontinuous and Non-convex** 

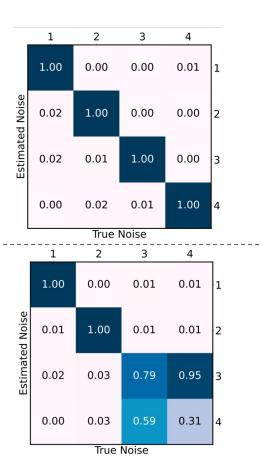
d x n dimensions

Continuous

#### **Results on Synthetic Data**







# Summary

• Prove that latent causal variables can be disentangled up to their upstream layer representations

• Present practical algorithm to perform such disentanglement

• Validate our theory and algorithm with experiments on synthetic data

