

Marrying Causal Representation Learning and Dynamical Systems for Science

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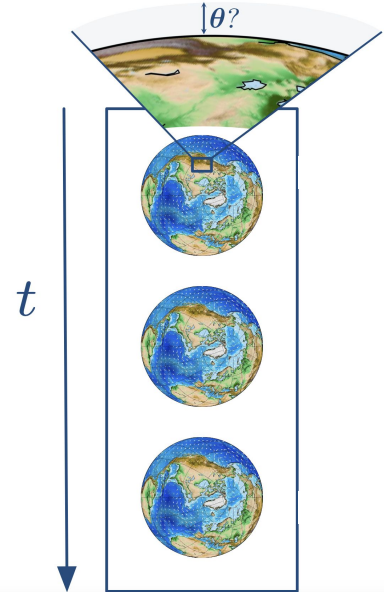
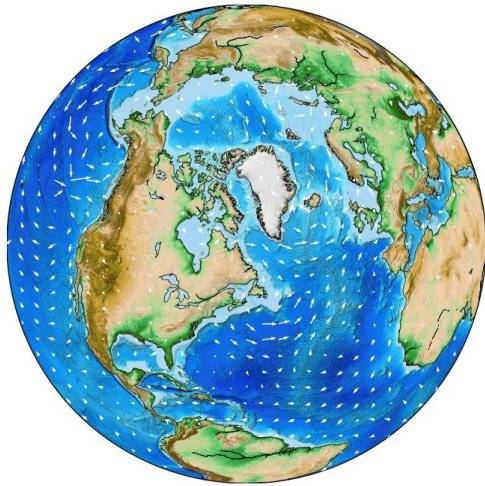
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Science and
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Causal
Learning and 

The text 'Causal Learning and' is in a light green, sans-serif font. To the right of the word 'and' is a small icon representing artificial intelligence, consisting of a central node connected to three other nodes in a triangular arrangement, with lines representing connections.

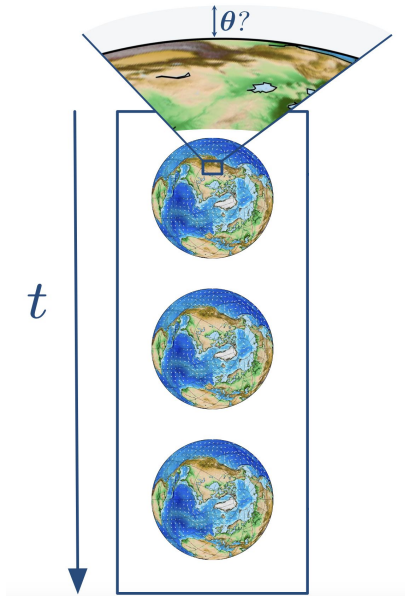
Motivation

Goal: Answer scientific questions that are related to underlying physical parameters from complex dynamical systems



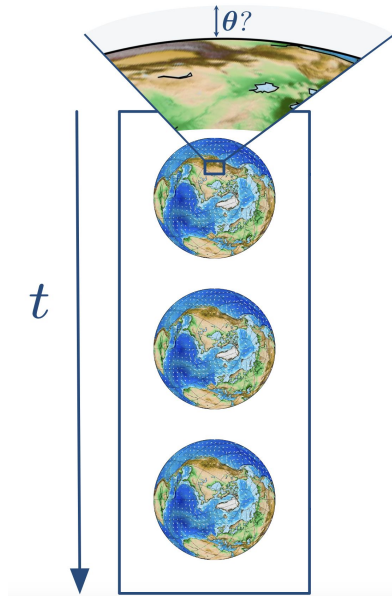
Problem Formulation

ODE System: $\dot{\mathbf{x}}(t) = f_{\theta}(\mathbf{x}(t))$



How much do we know about the system?

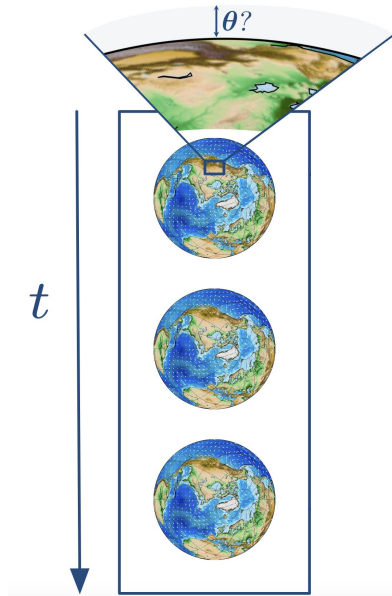
ODE System: $\dot{\mathbf{x}}(t) = f_{\theta}(\mathbf{x}(t))$



System f_{θ} given by field experts

If the functional form of the system is known

$$\text{ODE System: } \dot{\mathbf{x}}(t) = f_{\theta}(\mathbf{x}(t))$$



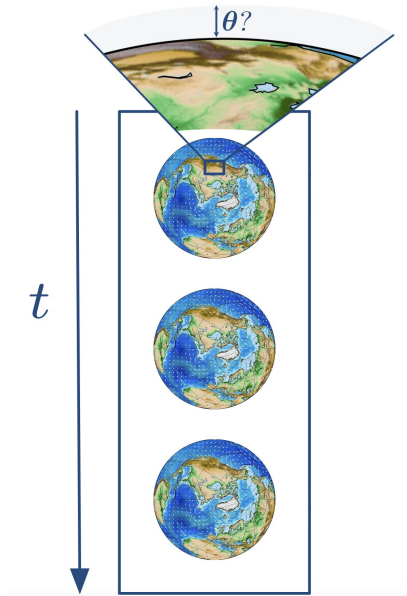
Corollary 1 (Full identifiability with known f)

$$\hat{\theta} \in \operatorname{argmin} \|F(\hat{\theta}) - \mathbf{x}\|_2^2 \quad (1)$$

fully-identifies the ground truth parameter θ .

If the functional form of the system is unknown

ODE System: $\dot{\mathbf{x}}(t) = f_{\theta}(\mathbf{x}(t))$



System f_{θ} unknown



CRL approaches

Why can we use CRL for system identification?

The ground assumptions between these two fields align

param. estimation assumption	CRL assumption
<i>existence & uniqueness</i>	<i>determ. gen.</i>
	<i>supp(θ) = Θ</i>
<i>structural identifiability</i>	<i>injectivity</i>

Edward L Ince. *Ordinary differential equations*. Courier Corporation, 1956.

Ror Bellman and Karl Johan Åström. *On structural identifiability*. *Mathematical biosciences*, 7(3-4): 329–339, 1970.

Identifiability for Unknown Systems

(e.g. with Multiview CRL)

Corollary 2 (Identifiability without known f)

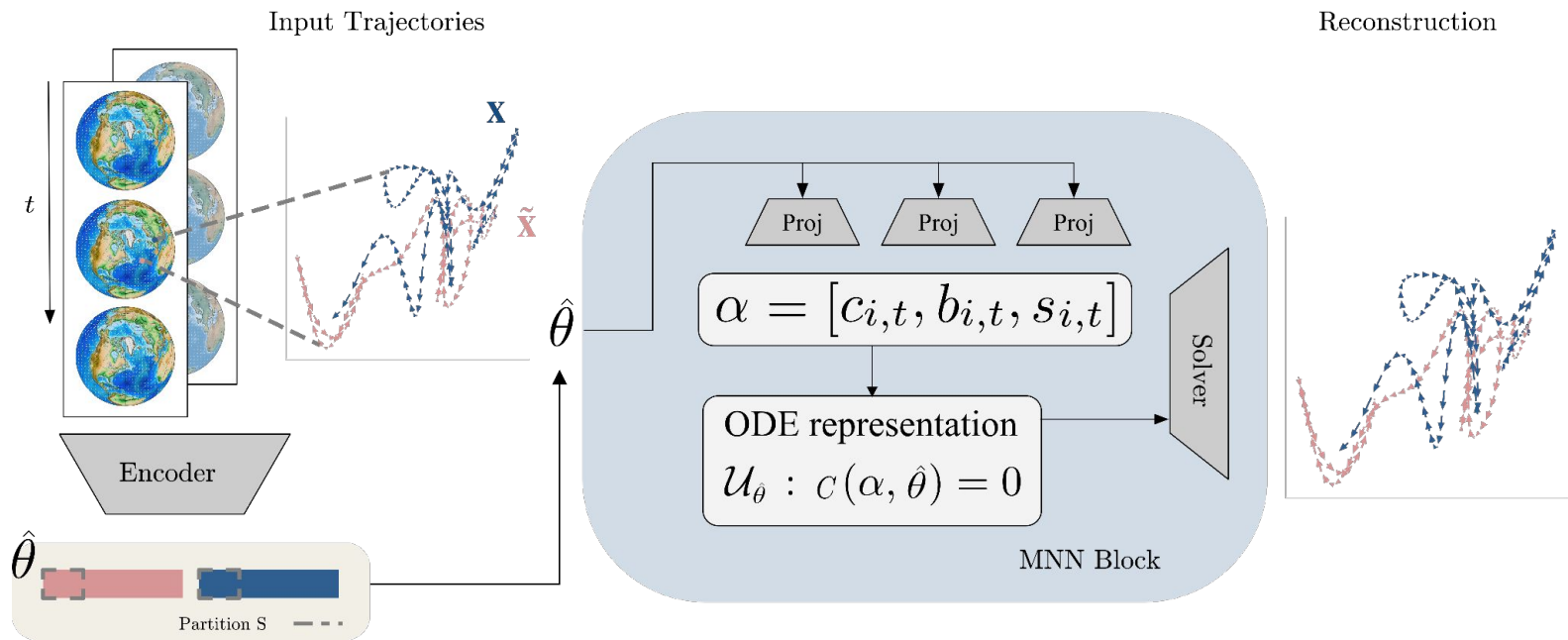
$$g, \hat{F} \in \operatorname{argmin} \mathbb{E}_{\mathbf{x}, \tilde{\mathbf{x}}} \underbrace{\|g(\mathbf{x})_S - g(\tilde{\mathbf{x}})_S\|_2^2}_{\text{Alignment}} + \underbrace{\|\hat{F}(g(\mathbf{x})) - \mathbf{x}\|_2^2 + \|\hat{F}(g(\tilde{\mathbf{x}})) - \tilde{\mathbf{x}}\|_2^2}_{\text{Sufficiency}}, \quad (2)$$

then the parameter θ is partially identified by g up to a diffeomorphism in the statistical setting.

*The choice of *alignment* can be generalized -- "Unifying Causal Representation Learning with the Invariance Principle" Yao et al. 2024

Model Architecture

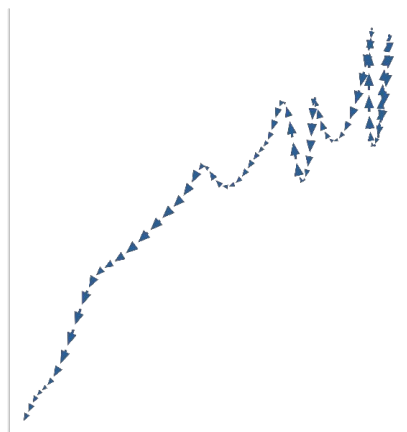
A general recipe for CRL-integrated system identifier



Wind Simulation: Efficiently Extracting Downstream Features

Goal: Discriminating air layer thickness by wind observations

Test Trajectory



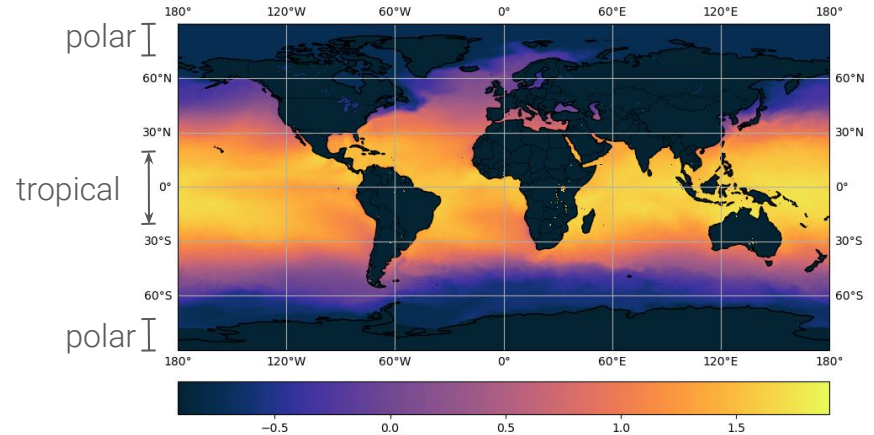
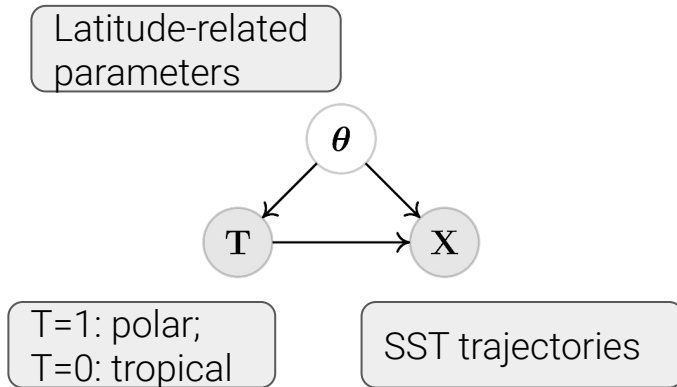
$\theta?$

	S_1	S_2	S_3	
Ada-GVAE	0.6	0.6	0.6	Accuracy 1.0 0.9 0.8 0.7 0.6 0.5
TI-MNN	0.6	0.6	0.6	
Contr. Id.	1.0	0.5	0.6	
Mech. Id. (Ours)	1.0	0.5	0.5	

Sea Surface Temperature: Estimating Pre-treatment Covariates

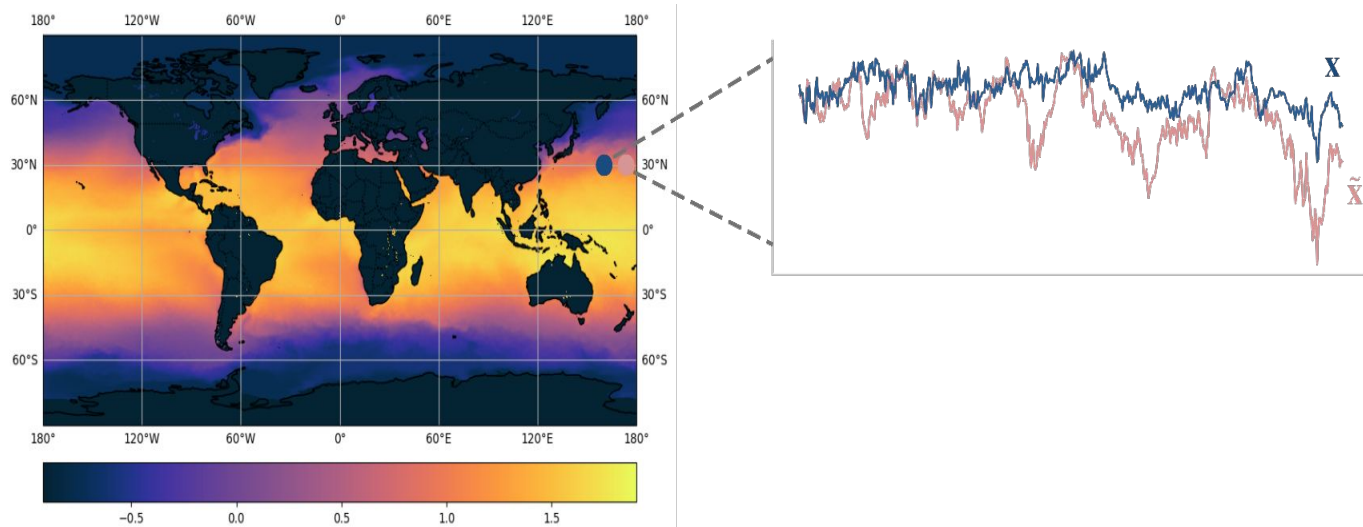
Goal: Isolating latitude-related parameters for reliable ATE estimation

$$\text{ATE} = \mathbb{E}[\mathbf{X}_1 - \mathbf{X}_0 \mid \theta]$$



Sea Surface Temperature: Estimating Pre-treatment Covariates

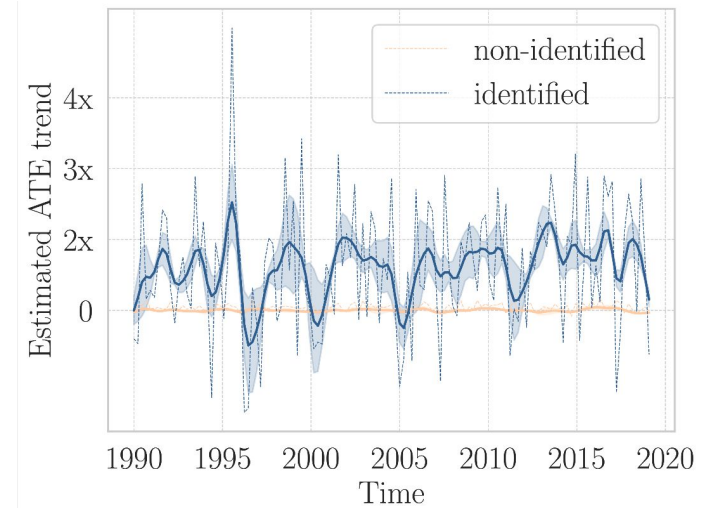
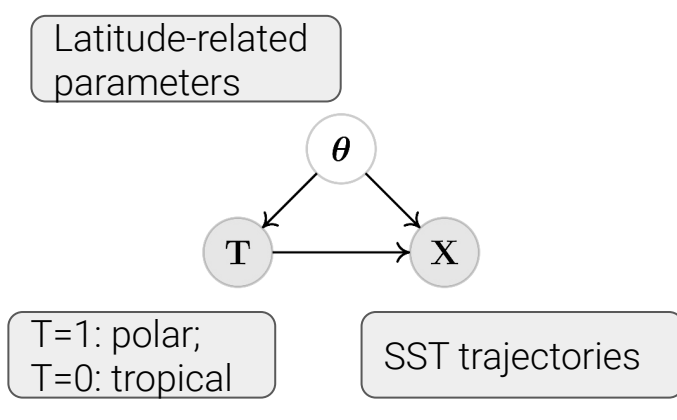
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Sea Surface Temperature: Estimating Pre-treatment Covariates

Goal: Isolating latitude-related parameters for reliable ATE estimation

$$\text{ATE} = \mathbb{E}[\mathbf{X}_1 - \mathbf{X}_0 \mid \theta]$$



Conclusion

CRL Identifiability approaches can be applied beyond traditional causal models and facilitate scientific discoveries.

Thank you!

