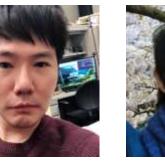




Meta-DiffuB: A Contextualized Sequence-to-Sequence Text Diffusion Model with Meta-Exploration Neurips 2024



Yun-Yen $Chuang^{1,2}$ Hung-Min Hsu³



 ${f Kevin}\,{f Lin}^4$







Hung-Yi Lee 2



Diffusion Models:

• A generative framework successful in image, audio, video, and text generation



Diffusion Models:

- A generative framework successful in image, audio, video, and text generation
- Works by adding (Foward process) and removing (Reverse process) noise to generate data



Diffusion Models:

- A generative framework successful in image, audio, video, and text generation
- Works by adding (Foward process) and removing (Reverse process) noise to generate data
- Seq2Seq Text Generation (S2S-Diffusion models): Generate target sentence from an input sentence



Diffusion Models:

- A generative framework successful in image, audio, video, and text generation
- Works by adding (Foward process) and removing (Reverse process) noise to generate data
- Seq2Seq Text Generation (S2S-Diffusion models): Generate target sentence from an input sentence
- Current Limitations (Non-contextualized noise scheduling):
 - Fixed noise scheduling in existing models (e.g., DiffuSeq, Dinoiser, SeqDiffuSeq, LD4LG, RDM)
 - Fails to adapt to sentence semantic



Diffusion Models:

- A generative framework successful in image, audio, video, and text generation
- Works by adding (Foward process) and removing (Reverse process) noise to generate data
- Seq2Seq Text Generation (S2S-Diffusion models): Generate target sentence from an input sentence
- Current Limitations (Non-contextualized noise scheduling):
 - Fixed noise scheduling in existing models (e.g., DiffuSeq, Dinoiser, SeqDiffuSeq, LD4LG, RDM)
 - Fails to adapt to sentence semantic

• Key Contributions:

• Introduce Meta-DiffuB to dynamically schedule noise



Diffusion Models:

- A generative framework successful in image, audio, video, and text generation
- Works by adding (Foward process) and removing (Reverse process) noise to generate data
- Seq2Seq Text Generation (S2S-Diffusion models): Generate target sentence from an input sentence
- Current Limitations (Non-contextualized noise scheduling):
 - Fixed noise scheduling in existing models (e.g., DiffuSeq, Dinoiser, SeqDiffuSeq, LD4LG, RDM)
 - Fails to adapt to sentence semantic

• Key Contributions:

- Introduce Meta-DiffuB to dynamically schedule noise
- Contextualized noise scheduling for better sentence generation



Diffusion Models:

- A generative framework successful in image, audio, video, and text generation
- Works by adding (Foward process) and removing (Reverse process) noise to generate data
- Seq2Seq Text Generation (S2S-Diffusion models): Generate target sentence from an input sentence
- Current Limitations (Non-contextualized noise scheduling):
 - Fixed noise scheduling in existing models (e.g., DiffuSeq, Dinoiser, SeqDiffuSeq, LD4LG, RDM)
 - Fails to adapt to sentence semantic

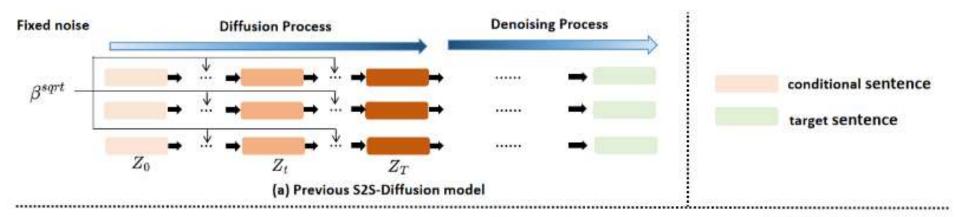
• Key Contributions:

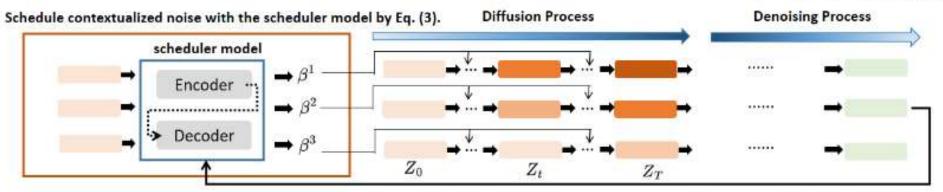
- Introduce Meta-DiffuB to dynamically schedule noise
- Contextualized noise scheduling for better sentence generation
- Plug-and-play scheduler model: Enhances existing models without fine-tuning



Meta-DiffuB: Framework

Scheduler-Exploiter Framework:





Update the scheduler model with the rewards of target sentences using Policy Gradient as shown in Eq. (6).

(b) Meta-DiffuB

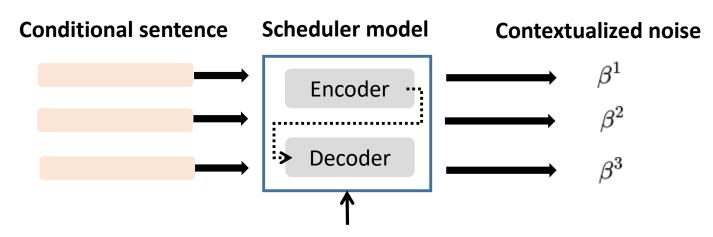


Methodology

- Noise Scheduling (Scheduler Model):
 - Generates Meta-Instructions for noise adjustment

 $\iota^{x} = B_{\psi}(\mathbf{w}^{x})$ $\boldsymbol{\beta}^{x} = skipping(\iota^{x}, \boldsymbol{\beta}^{sqrt}).$

- Customizes noise schedule based on sentence complexity
- Scheduler adapts noise levels based on exploiter's learning by Policy Gradient



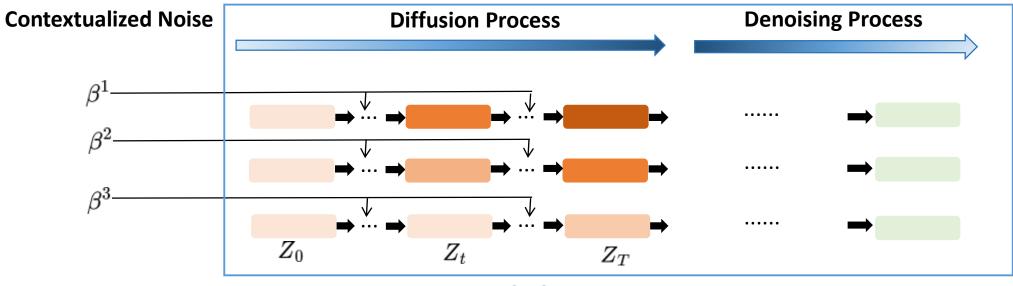
Update with the rewards of target sentences using Policy Gradient as shown in Eq. (6).



Methodology

• Training the Exploiter (S2S-Diffusion model):

• S2S-Diffusion model uses scheduled noise for generation



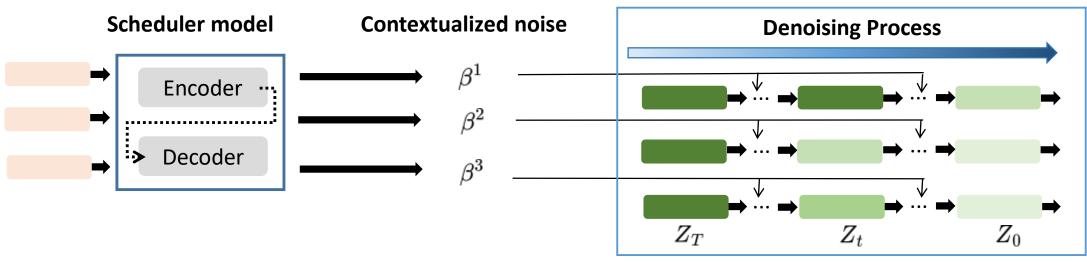
S2S-Diffusion model



Methodology

Contextualized Inference:

- Dynamic noise scheduling during inference for better text generation
- Adapts to sentence difficulty, improving quality and diversity



S2S-Diffusion model



Benchmark dataset experiment

Tasks	Methods	BLEU (†)	ROUGH-L (↑)	BERTScore (†)	Dist-1 (†)	Self-BLEU (↓)	M-R (↓)
	* GPT2-base	0.1980	0.5212	0.8246	0.9798	0.5480	5.20
	★ GPT2-large	0.2059	0.5415	0.8363	0.9819	0.7325	3.80
	* LevT	0.2268	0.5795	0.8344	0.9790	0.9995	4.80
QQP	* DiffuSeq	0.2413	0.5880	0.8365	0.9807	0.2732	2.60
	* SeqDiffuSeq	0.2434	1. King and 1. King an	0.8400	0.9807	-	2.33
	† Dinoiser	0.1949	0.5316	0.8036	0.9723	0.8643	6.20
	Meta-DiffuB	0.2632	0.5933	0.8519	0.9902	0.2595	1.00
	* GPT2-base	0.3083	0.5461	0.8021	0.9439	0.5444	3.40
	* GPT2-large	0.2693	0.5111	0.7882	0.9464	0.6042	4.00
	* LevT	0.2052	0.4402	0.7254	0.9715	0.9907	5.00
WA	* DiffuSeq	0.3622	0.5849	0.8126	0.9264	0.4642	3.00
	* SeqDiffuSeq	0.3712		0.8214	0.9077	H	3.33
	† Dinoiser	0.2388	0.4821	0.6787	0.8421	0.9132	6.20
	Meta-DiffuB	0.3877	0.6047	0.8233	0.9355	0.3888	1.60
	★ GPT2-base	0.0741	0.2714	0.6052	0.9602	0.1403	3.80
	* GPT2-large	0.1110	0.3215	0.6346	0.9670	0.2910	2.60
1992	* LevT	0.0930	0.2893	0.5491	0.8914	0.9830	5.40
QT	* DiffuSeq	0.1731	0.3665	0.6123	0.9056	0.2789	3.20
	* SeqDiffuSeq	0.1746	155	0.6174	0.9248		3.33
	† Dinoiser	0.0477	0.1872	0.4690	0.8191	0.5273	6.40
	Meta-DiffuB	0.1820	0.3870	0.6286	0.9323	0.2527	1.80
	* GPT2-base	0.0108	0.1508	0.5279	0.9194	0.0182	4.00
	★ GPT2-large	0.0125	0.1002	0.5293	0.9244	0.0213	4.00
10100	* LevT	0.0158	0.0550	0.4760	0.9726	0.7103	3.80
CC	* DiffuSeq	0.0139	0.1056	0.5131	0.9467	0.0144	3.40
	* SeqDiffuSeq	0.0112		0.4425	0.9608		2.80
	† Dinoiser	0.0096	0.1166	0.3545	0.2485	0.9994	6.00
	Meta-DiffuB	0.0220	0.1528	0.5316	0.9670	0.0133	1.20







Benchmark dataset experiment

Tasks	Methods	BLEU (†)	ROUGH-L (†)	BERTScore ([†])	Dist-1 (†)	Self-BLEU (↓)	M-R (\downarrow)
	* GPT2-base	0.1980	0.5212	0.8246	0.9798	0.5480	5.20
	* GPT2-large	0.2059	0.5415	0.8363	0.9819	0.7325	3.80
	* LevT	0.2268	0.5795	0.8344	0.9790	0.9995	4.80
QQP	* DiffuSeq	0.2413	0.5880	0.8365	0.9807	0.2732	2.60
	* SeqDiffuSeq	0.2434	12	0.8400	0.9807	-	2.33
	† Dinoiser	0.1949	0.5316	0.8036	0.9723	0.8643	6.20
	Meta-DiffuB	0.2632	0.5933	0.8519	0.9902	0.2595	1.00
	* GPT2-base	0.3083	0.5461	0.8021	0.9439	0.5444	3.40
	* GPT2-large	0.2693	0.5111	0.7882	0.9464	0.6042	4.00
	* LevT	0.2052	0.4402	0.7254	0.9715	0.9907	5.00
WA	* DiffuSeq	0.3622	0.5849	0.8126	0.9264	0.4642	3.00
	* SeqDiffuSeq	0.3712		0.8214	0.9077	H	3.33
	† Dinoiser	0.2388	0.4821	0.6787	0.8421	0.9132	6.20
	Meta-DiffuB	0.3877	0.6047	0.8233	0.9355	0.3888	1.60
	★ GPT2-base	0.0741	0.2714	0.6052	0.9602	0.1403	3.80
	* GPT2-large	0.1110	0.3215	0.6346	0.9670	0.2910	2.60
823	* LevT	0.0930	0.2893	0.5491	0.8914	0.9830	5.40
QT	* DiffuSeq	0.1731	0.3665	0.6123	0.9056	0.2789	3.20
	* SeqDiffuSeq	0.1746	100	0.6174	0.9248		3.33
	† Dinoiser	0.0477	0.1872	0.4690	0.8191	0.5273	6.40
	Meta-DiffuB	0.1820	0.3870	0.6286	0.9323	0.2527	1.80
	* GPT2-base	0.0108	0.1508	0.5279	0.9194	0.0182	4.00
	* GPT2-large	0.0125	0.1002	0.5293	0.9244	0.0213	4.00
1000	* LevT	0.0158	0.0550	0.4760	0.9726	0.7103	3.80
CC	* DiffuSeq	0.0139	0.1056	0.5131	0.9467	0.0144	3.40
	* SeqDiffuSeq	0.0112		0.4425	0.9608	2	2.80
	† Dinoiser	0.0096	0.1166	0.3545	0.2485	0.9994	6.00
	Meta-DiffuB	0.0220	0.1528	0.5316	0.9670	0.0133	1.20

Model agnostic experiment

Tasks	Methods	BLEU (†)	BERTScore (†)	Dist-1 (†)
	* DiffuSeq	0.2413	0.8365	0.9807
	Meta-Diffu B (D_{θ} = DiffuSeq)	0.2552	0.8821	0.9922
QQP	* SeqDiffuSeq	0.2434	0,8400	0.9807
	Meta-Diffu B ($D_{\theta} = \text{SeqDiffuSeq}$)	0.2632	0.8919	0.9902
	† Dinoiser	0.1949	0.8036	0.9723
	Meta-Diffu B (D_{θ} = Dinoiser)	0.2271	0.8525	0.9752
	* DiffuSeq	0.3622	0.8126	0.9264
	Meta-Diffu B (D_{θ} = DiffuSeq)	0.3877	0.8233	0.9355
WA	* SeqDiffuSeq	0.3712	0.8214	0.9077
	Meta-Diffu B (D_0 = SeqDiffuSeq)	0.3957	0.8451	0.9412
	† Dinoiser	0.2388	0.6787	0.8421
	Meta-Diffu B (D_{θ} = Dinoiser)	0.2471	0.7285	0.8694





Benchmark dataset experiment

Tasks	Methods	BLEU (↑)	ROUGH-L (†)	BERTScore ([†])	Dist-1 (†)	Self-BLEU (↓)	M-R (↓)
	* GPT2-base	0.1980	0.5212	0.8246	0.9798	0.5480	5.20
	★ GPT2-large	0.2059	0.5415	0.8363	0.9819	0.7325	3.80
1010121	* LevT	0.2268	0.5795	0.8344	0.9790	0.9995	4.80
QQP	* DiffuSeq	0.2413	0.5880	0.8365	0.9807	0.2732	2.60
	* SeqDiffuSeq	0.2434		0.8400	0.9807	_	2.33
	† Dinoiser	0.1949	0.5316	0.8036	0.9723	0.8643	6.20
	Meta-DiffuB	0.2632	0.5933	0.8519	0.9902	0.2595	1.00
	* GPT2-base	0.3083	0.5461	0.8021	0.9439	0.5444	3.40
	* GPT2-large	0.2693	0.5111	0.7882	0.9464	0.6042	4.00
	* LevT	0.2052	0.4402	0.7254	0.9715	0.9907	5.00
WA	* DiffuSeq	0.3622	0.5849	0.8126	0.9264	0.4642	3.00
	* SeqDiffuSeq	0.3712	-	0.8214	0.9077	<i></i>	3.33
	† Dinoiser	0.2388	0.4821	0.6787	0.8421	0.9132	6.20
	Meta-DiffuB	0.3877	0.6047	0.8233	0.9355	0.3888	1.60
	* GPT2-base	0.0741	0.2714	0.6052	0.9602	0.1403	3.80
	* GPT2-large	0.1110	0.3215	0.6346	0.9670	0.2910	2.60
19975	* LevT	0.0930	0.2893	0.5491	0.8914	0.9830	5.40
QT	* DiffuSeq	0.1731	0.3665	0.6123	0.9056	0.2789	3.20
	* SeqDiffuSeq	0.1746	100	0.6174	0.9248		3.33
	† Dinoiser	0.0477	0.1872	0.4690	0.8191	0.5273	6.40
	Meta-DiffuB	0.1820	0.3870	0.6286	0.9323	0.2527	1.80
	* GPT2-base	0.0108	0.1508	0.5279	0.9194	0.0182	4.00
	* GPT2-large	0.0125	0.1002	0.5293	0.9244	0.0213	4.00
61054.00×	* LevT	0.0158	0.0550	0.4760	0.9726	0.7103	3.80
CC	* DiffuSeq	0.0139	0.1056	0.5131	0.9467	0.0144	3.40
	* SeqDiffuSeq	0.0112		0.4425	0.9608	2	2.80
	† Dinoiser	0.0096	0.1166	0.3545	0.2485	0.9994	6.00
	Meta-DiffuB	0.0220	0.1528	0.5316	0.9670	0.0133	1.20

Model agnostic experiment

Tasks	Methods	BLEU (†)	BERTScore (†)	Dist-1 (†
	* DiffuSeq	0.2413	0.8365	0.9807
	Meta-Diffu $B (D_{\theta} = \text{DiffuSeq})$	0.2552	0.8821	0.9922
QQP	* SeqDiffuSeq	0.2434	0,8400	0.9807
	Meta-Diffu B ($D_{\theta} = \text{SeqDiffuSeq}$)	0.2632	0.8919	0.9902
	† Dinoiser	0.1949	0.8036	0.9723
	Meta-Diffu B (D_{θ} = Dinoiser)	0.2271	0.8525	0.9752
	* DiffuSeq	0.3622	0.8126	0.9264
	Meta-Diffu B (D_{θ} = DiffuSeq)	0.3877	0.8233	0.9355
WA	* SeqDiffuSeq	0.3712	0.8214	0.9077
	Meta-Diffu B (D_0 = SeqDiffuSeq)	0.3957	0.8451	0.9412
	† Dinoiser	0.2388	0.6787	0.8421
	Meta-Diffu B (D_{θ} = Dinoiser)	0.2471	0.7285	0.8694

MBR decoding experiment

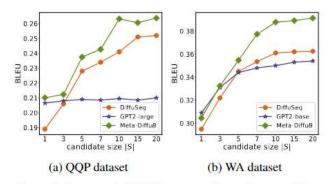
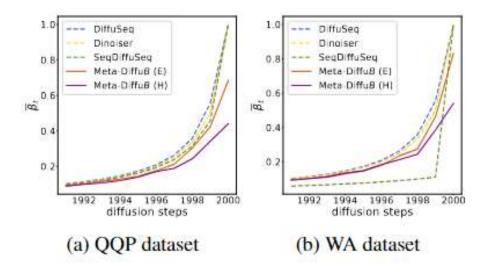


Figure 2: Increase in BLEU score with varying candidate sizes |S| on the QQP and WA datasets.



Contextualized Noise Scheduling

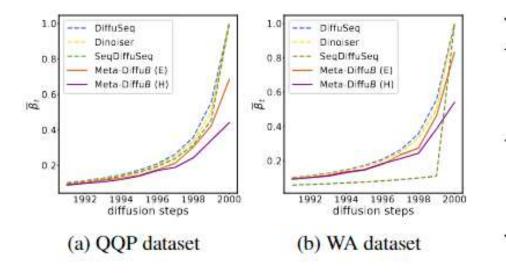
- Noise adjustment based on sentence complexity:
 - More noise for simpler sentences to enhance diversity
 - Less noise for complex sentences to improve accuracy
- Significant improvement in generation performance:
 - Noticeable enhancement in both quality and diversity for sentences of varying difficulty





Contextualized Noise Scheduling

- Noise adjustment based on sentence complexity:
 - More noise for simpler sentences to enhance diversity
 - Less noise for complex sentences to improve accuracy
- Significant improvement in generation performance:
 - Noticeable enhancement in both quality and diversity for sentences of varying difficulty



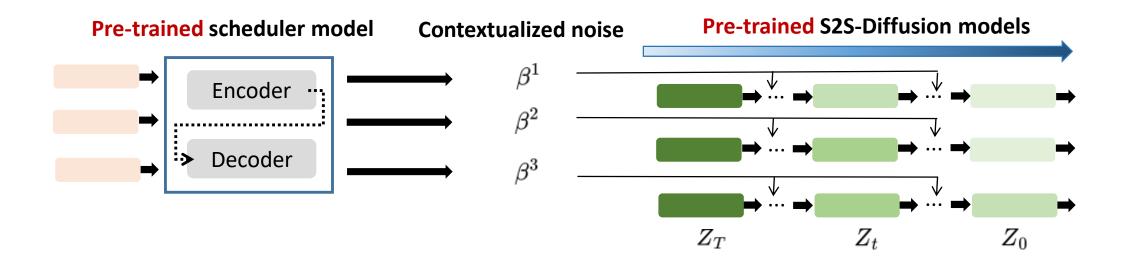
Methods	BLEU (†)	Self-BLEU (\downarrow)
DiffuSeq (E)	0.3721	0.4345
SeqDiffuSeq (E)	0.3752	0.4652
Dinoiser (E)	0.2892	0.8852
Meta-DiffuB (E)	0.3997	0.3688
DiffuSeq (H)	0.3216	0.5085
SeqDiffuSeq (H)	0.3282	0.6251
Dinoiser (H)	0.2092	0.9528
Meta-DiffuB (H)	0.3724	0.4056

Plug-and-Play experiment



- Pre-trained scheduler integrated into other models:
 - Applied Meta-DiffuB's pre-trained scheduler to DiffuSeq and other S2S-Diffusion models
 - No fine-tuning required
 - Improved performance without additional training

Scheduler	DiffuSeq	BLEU (†)	ROUGH-L (↑)	BERTScore (↑)	Dist-1 (†)	Self-BLEU (\downarrow)
WA		0.2594	0.5912	0.8459	0.9834	0.2653
QT	QQP	0.2603	0.5947	0.8503	0.9812	0.2649
Null		0.2413	0.5880	0.8365	0.9807	0.2732



Conclusion & Applications

• Conclusion & Applications

- Superior performance compared with previous S2S-Diffusion models in Seq2Seq tasks
- Dynamic noise scheduling for better quality and diversity
- Plug-and-play scheduler for easy integration

Conclusion & Applications

• Conclusion & Applications

- Superior performance compared with previous S2S-Diffusion models in Seq2Seq tasks
- Dynamic noise scheduling for better quality and diversity
- Plug-and-play scheduler for easy integration
- Applications:
 - Language Translation
 - Text Summarization
 - Dialogue Systems

Conclusion & Applications

• Conclusion & Applications

- Superior performance compared with previous S2S-Diffusion models in Seq2Seq tasks
- Dynamic noise scheduling for better quality and diversity
- Plug-and-play scheduler for easy integration
- Applications:
 - Language Translation
 - Text Summarization
 - Dialogue Systems
- Future Impact:
 - It is a valuable asset in the field of Seq2Seq Diffusion models.