

Reinforcement Learning Guided Semi-Supervised Learning

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Introduction

- **Semi-Supervised Learning (SSL):** Uses a small labeled dataset with a large unlabeled pool.
- **Limitations**: Heuristics or predefined rules for pseudo-labeling methods are often suboptimal.
- **Challenge**: How can we better leverage unlabeled data to guide the learning process?

Reinforcement Learning Guided Semi-Supervised Learning (RLGSSL)

- Treats SSL as a **one-armed bandit problem**.
- **Dynamically** adapt and respond to the data.
- **Beyond standard norm** for SSL.
- Potential to **transform** SSL frameworks.

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- **Reward: Generalization** measured via label mixup between labeled and pseudo-labeled samples.

Reward Function

● Balanced utilization of labeled and unlabeled data by Inter-mixup:

$$
x_i^{\mathrm{m}} = \mu \, x_i^u + (1 - \mu) \, x_i^l, \qquad \mathbf{y}_i^{\mathrm{m}} = \mu \, \mathbf{y}_i^u + (1 - \mu) \, \mathbf{y}_i^l
$$

● Reward: Negative disagreement between model predictions and mixup labels:

$$
\mathcal{R}(s, a; \mathrm{sg}[\theta]) = \mathcal{R}(X^l, Y^l, X^u, Y^u; \mathrm{sg}[\theta]) = -\frac{1}{C \cdot N^{\mathrm{m}}} \sum_{i=1}^{N^{\mathrm{m}}} ||P_{\theta}(x_i^{\mathrm{m}}) - \mathbf{y}_i^{\mathrm{m}}||_2^2
$$

Reinforcement Learning Loss

- **One-Armed Bandit Principle:** Optimize one-time reward based on the policy output.
- **Exploits non-differentiable reward.**
- Enables policy gradient with a **deterministic policy**.
- **KL-Divergence Weighted Negative Reward:**

 $\mathcal{L}_{\rm rl}(\theta) = -\mathbb{E}_{\mathbf{y}^u_* \sim \pi_\theta} \text{KL}(\mathbf{e}, \mathbf{y}^u_i) \mathcal{R}(s, a; \text{sg}[\theta]) = -\mathbb{E}_{x^u_* \in \mathcal{D}_u} \text{KL}(\mathbf{e}, P_\theta(x^u_i)) \mathcal{R}(s, a; \text{sg}[\theta])$

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• Measures distance between label predictions and a uniform distribution vector *e=1/C*

Teacher Student Framework

● Teacher parameter update via WMA:

$$
\theta_T = \beta \, \theta_T + (1 - \beta) \, \theta_S
$$

● **Supervised Loss** on labeled data**:**

$$
\mathcal{L}_{\text{sup}}(\theta_S) = \mathbb{E}_{(x^l,\mathbf{y}^l) \in \mathcal{D}^l}\left[\ell_{CE}\left(P_{\theta_S}(x^l), \mathbf{y}^l\right)\right]
$$

• Consistency Loss between student and teacher on unlabeled data:

$$
\mathcal{L}^{\text{cons}} = \mathbb{E}_{x^u \in \mathcal{D}^u} \left[\ell_{\text{KL}} \left(P_{\theta_S}(x^u), P_{\theta_T}(x^u) \right) \right]
$$

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• Learning objective: $\mathcal{L}(\theta_S) = \mathcal{L}_{rl} + \lambda_1 \mathcal{L}_{\text{sup}} + \lambda_2 \mathcal{L}_{\text{cons}}$

Experimental Results

Table 1: Performance of RLGSSL and state-of-the-art SSL algorithms with the CNN-13 network. We report the average test errors and the standard deviations of 5 trials.

Thank You

