



## Sample Efficient Bayesian Learning of Causal Graphs from Interventions

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- Experimental design methods usually assume access to infinite intervention data
- Bayesian causal discovery methods have parametric assumptions on the SCM and noise
- The only non-parametric Bayesian approach assume that the causal graph is a tree



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- Task:

 $\odot$  Given the UCCG G and N interventional samples, return a DAG D

#### • Separating System:

**Lemma 5** ([Shanmugam et al., 2015]). There exists a labeling procedure that gives distinct labels of length l for all elements in [n] using letter from the integer alphabet  $\{0, 1, ..., a\}$ , where  $l = \lceil \log_a n \rceil$ . Furthermore, in every position, any integer letter is used at most  $\lceil \frac{n}{a} \rceil$  times.

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• Cutting edge configuration and interventional distributions:

**Lemma 1.** [Elahi et al., 2024] Assume that the faithfulness assumption holds and  $\mathcal{D}^*$  is the true DAG. For any DAG  $\mathcal{D}_1 \neq \mathcal{D}^*$ , if  $P_{\mathbf{s}}^{\mathcal{D}_1} = P_{\mathbf{s}}^{\mathcal{D}^*}$  for some  $\mathbf{S} \subseteq \mathbf{V}$ , they must share the same cutting edge orientation  $C(\mathbf{S})$ .

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Shanmugam, Karthikeyan, Murat Kocaoglu, Alexandros G. Dimakis, and Sriram Vishwanath. "Learning causal graphs with small interventions." Advances in Neural Information Processing Systems 28 (2015). Elahi, Muhammad Qasim, Lai Wei, Murat Kocaoglu, and Mahsa Ghasemi. "Adaptive Online Experimental Design for Causal Discovery." arXiv preprint arXiv:2405.11548 (2024).







#### **Our Approach** $C_1$ $X_1$ $X_3$ $X_1$ $C_2$ (X<sub>1</sub>) Update posteriors Intervene on $X_1$ $X_3$ $(X_2)$ $(X_3)$ $X_2$ $C_3$ $\Lambda_1$ (X3)



## **Theoretical Analysis**

#### • Asymptotic results:

**Lemma 2.** (Posterior Consistency) Consider an intervention target  $\mathbf{S}_i \in S$  and the corresponding true cutting-edge configuration  $C^*(\mathbf{S}_i)$ . As the number of samples  $m_{\mathbf{s}_i} \to \infty$  in  $\mathsf{Data}_{do(\mathbf{s}_i)} = \{\mathbf{v}_1, \mathbf{v}_2, \ldots, \mathbf{v}_{m_{\mathbf{s}_i}}\}$ , the posterior of the true cutting-edge configuration  $P(C^*(\mathbf{S}_i) \mid \mathsf{Data}_{do(\mathbf{s}_i)})$  converges to 1 with high probability. More precisely, we have the following high probability lower bound on the posterior probability of the true cutting-edge configuration.

$$P(\mathsf{C}^*(\mathbf{S}_i) \mid \mathsf{Data}_{do(\mathbf{s}_i)}) \ge 1 - \frac{1}{1 + \alpha_1 \exp\left(\mathcal{O}(m_{\mathbf{s}_i}) - \alpha_2 \mathcal{O}\left(\sqrt{m_{\mathbf{s}_i} \ln \frac{1}{\delta}}\right)\right)} w.p. \ at \ least \ 1 - \delta$$

Where  $\alpha_1$  and  $\alpha_2$  are constants depending on the prior and the problem instance. Thus, for any small choice of the probability  $\delta$ , with a sufficiently large number of samples  $m_{\mathbf{s}_i}$ , the posterior of the true cutting-edge configuration  $P(C^*(\mathbf{S}_i) \mid \mathsf{Data}_{do(\mathbf{s}_i)})$ , converges to 1 with a probability at least  $1 - \delta$ .

### **Theoretical Analysis**

#### • Non-asymptotic results:

**Theorem 3.** Given that the Assumption 1 hold, consider an intervention target  $\mathbf{S}_i \in S$  such that  $|\mathbf{S}_i| \leq k$  and the corresponding true cutting edge configuration  $C^*(\mathbf{S}_i)$ . If the number of samples  $m_{\mathbf{s}i}$  in  $\mathsf{Data}_{do(\mathbf{s}_i)} = {\mathbf{v}_1, \mathbf{v}_2, ..., \mathbf{v}_{m_{\mathbf{s}_i}}}$  satisfies the following:

$$m_{\mathbf{s}_{i}} = \frac{2\beta^{2}}{(D^{\mathbf{s}_{i}})^{2}} \ln \frac{2^{(k+1)d_{m}}}{\delta} + \frac{2}{D^{\mathbf{s}_{i}}} \ln \frac{2^{kd_{m}}(1-\gamma)(1-p^{*})}{p^{*}\gamma}$$

where  $p^*$  is the prior assigned to the true cutting-edge configuration  $C^*(\mathbf{S}_i)$ , then we have  $P(C^*(\mathbf{S}_i) \mid \mathsf{Data}_{do(\mathbf{s}_i)}) \geq 1 - \gamma$  with a probability at least  $1 - \delta$ .

# **Experimental Results**

- Baselines:
  - $\circ$  Random
  - o DCT
  - Adaptivity-sensitive search



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- We show in theory that our proposed algorithm will learn the true causal graph with a high probability given enough interventional samples and the convergence rate
- We demonstrate the performance of our algorithm with simulated experiments and show how to modify the algorithm to answer general causal queries with case study