

# Typicalness-Aware Learning for Failure Detection

Yijun Liu<sup>1</sup> Jiequan Cui<sup>2</sup> Zhuotao Tian<sup>1 $\boxtimes$ </sup> Sengiao Yang<sup>3</sup> Oingdong He<sup>4</sup> Xiaoling Wang<sup>1</sup> Jingyong Su<sup>1 $\boxtimes$ </sup> {liuyijun}@stu.hit.edu.cn <sup>1</sup>Harbin Institute of Technology (Shenzhen)  $\frac{2 \text{Nanyang} \text{ Technology}}{2 \text{Nanyang} \text{D}}$ <sup>3</sup>The Chinese University of Hong Kong <sup>4</sup>Tencent Youtu Lab

















# **Key Insight & Motivation**



\* Whether this image is labeled as Human or Horse, neither label is accurate

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• Typical samples are those that exhibit similarity to a majority of other samples at the semantic level. These samples possess typical features that are easier for deep neural networks to learn and generalize.

• Atypical samples, on the other hand, differ significantly from other samples at the semantic level. They pose a challenge for the model to generalize due to their uniqueness. These samples are often located near the decision boundary.



[1] Beyond confidence: Reliable models should also consider atypicality. NeurIPS 2023 [2] Unleashing mask: Explore the intrinsic out-of-distribution detection capability. ICML2023.

#### **Measurement of typicalness**



The nearest neighbor distance between sample features and the training set feature collection

- High feature dimensionality of samples
- Large number of training samples
- Time and resource consuming

**Distinguishing typical samples from atypical samples**

• **using ID and OOD samples as examples**



- X-axis shows the sample index
- Y-axis shows the mean responses across channels.
- ID shows higher positive responses compared to OOD

#### **Typicalness-Aware Learning**



### **Calculate Typicalness**

 $Q = \{(\mu_i, \sigma_i^2) | \hat{y_i} = y\}$ Add mean and varience of correct prediction to Quene

$$
d = \min_{(\mu_j, \sigma_j^2) \in Q} W((\mu_{new}, \sigma_{new}^2), (\mu_j, \sigma_j^2)) \quad \text{Get minimal distance}
$$

$$
\tau=1-\frac{d-d_{min}}{d_{max}-d_{min}}.
$$

Distance normanlization

 $T(\tau) = T_{\rm min} + (1-\tau) \times (T_{\rm max} - T_{\rm min})$ 

Calculate dynaminc magnitude

#### **How to design the loss function?**

• **fully optimize in the direction of typical samples, while not approaching infinity for atypical samples**

$$
\mathcal{L}_{\text{TAL}}(\bm{f},y) = -\log \frac{e^{\hat{\bm{f}}_{\bm{y}}* \overline{\boldsymbol{\Gamma}}(\tau)}}{\sum_{i=1}^{k} e^{\hat{\bm{f}}_{i}* \overline{\boldsymbol{\Gamma}}(\tau)}} \qquad \qquad \text{Dynamic}
$$



# **Experimental Results**



### Table 1: Evaluation results of the proposed TAL on CIFAR100.

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### Table 2: Evaluation results of the proposed TAL on ImageNet.



