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Spiking Graph Neural Network on Riemannian Manifolds

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Source code: <https://github.com/ZhenhHuang/MSG>

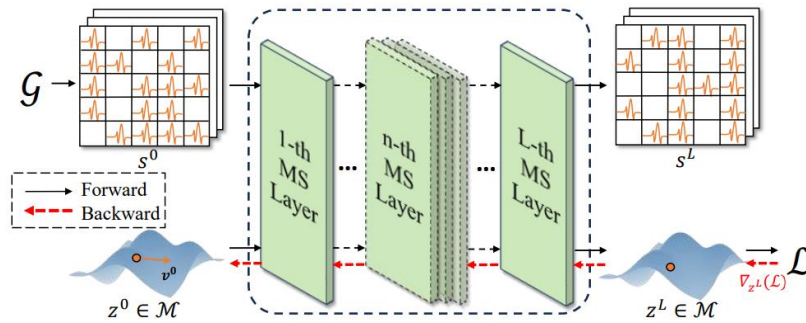
Motivations

- Graph data is non-Euclidean, and it's hard to represent its geometric properties by binary spike trains.
- BPTT training for SNN is non-differentiable and high time latency delay.
- Surrogate gradient with BPTT may cause gradient vanishing and explosion.
- Float operations on the Riemannian manifold contradict the binary property of SNN.

Contributions

- First Graph-SNN on the Riemannian manifolds (*MSG*) without manifold operations on forward phase.
- New training methods *DvM* builds relation to the manifold.
- Avoids high latency and gradient vanishing and explosion.
- Lower energy consumption and effective model performance.
- Theoretically show *MSG*'s connection to manifold ODEs.

Manifold-valued Spiking GNN



BPTT vs DvM

BPTT:

$$\nabla_{W^l} \mathcal{L} = \sum_t \left[\frac{\partial s^l[t]}{\partial W^l} \right]^* \nabla_{s^l[t]} \mathcal{L}$$

Differentiation via Manifold:

Theorem 4.1 (Backward Gradient). Let \mathcal{L} be the scalar-valued function, and \mathbf{z}^l is the output of l -th layer with parameter \mathbf{W}^l , which is delivered by tangent vector \mathbf{v}^l . Then, the gradient of function \mathcal{L} w.r.t \mathbf{W}^l is given as follows:

$$\nabla_{\mathbf{W}^l} \mathcal{L} = \left[\frac{\partial \mathbf{v}^{l-1}}{\partial \mathbf{W}^l} \right]^* [D_{\mathbf{v}^{l-1}} \phi^{l-1}]^* \nabla_{\mathbf{z}^l} \mathcal{L}, \quad \nabla_{\mathbf{z}^l} \mathcal{L} = [D_{\mathbf{z}^l} \psi^l]^* \nabla_{\mathbf{z}^{l+1}} \mathcal{L}, \quad (12)$$

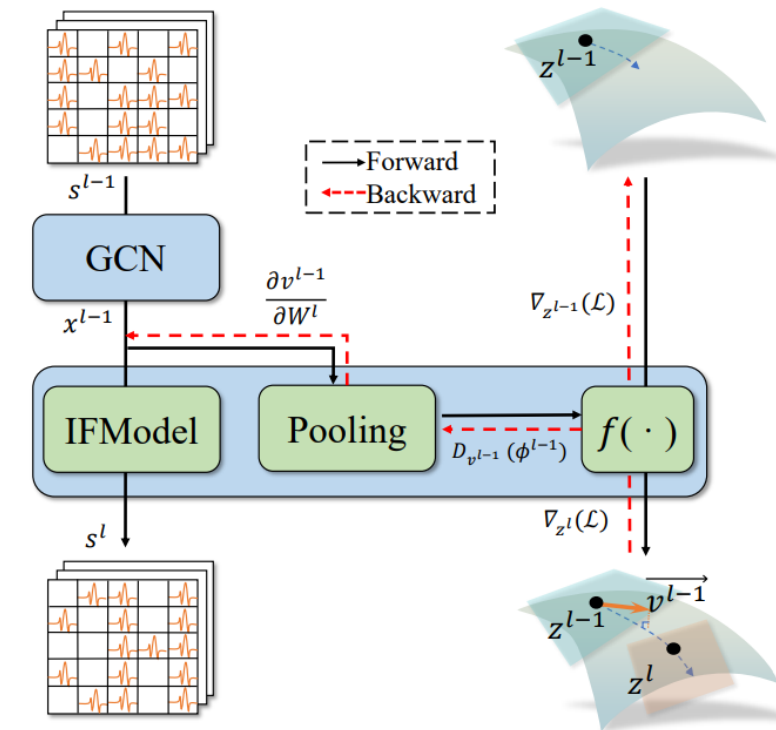
where $\phi^{l-1}(\cdot) = \text{Exp}_{\mathbf{z}^{l-1}}(\cdot)$, $\psi^l(\cdot) = \text{Exp}_{(\cdot)}(\mathbf{v}^l)$, and $[\cdot]^*$ means the matrix form of pullback.

BPTT via spikes:

1. High time steps latency delay
2. Non-differentiable
3. Gradient vanishing/explosion

Differentiation via Manifold:

1. Recurrence-free
2. Differentiable by smooth function
3. Avoid gradient vanishing/explosion



Algorithm 1 Training MSG by the proposed Differentiation via Manifold

Input: Graph $\mathcal{G}(\mathcal{V}, \mathcal{E}, \mathbf{F}, \mathbf{A})$, Manifold \mathcal{M} , Loss function over the manifold $\mathcal{L}(\cdot)$, Number of spiking layers L , Original points \mathbf{O} .

Output: Parameters $\{\mathbf{W}^l\}_{l=0, \dots, L}$

- 1: **while** not converging **do**
- 2: ▷ forward pass
- 3: Input current $\mathbf{X}^0 = \text{GCN}(\mathbf{A}, \mathbf{F}; \mathbf{W}^0)$;
- 4: Initialize $[\mathbf{S}^0, \mathbf{Z}^0] = \text{MSNeuron}(\mathbf{X}^0, \mathbf{O})$;
- 5: **for** each spiking layer $l = 1$ to L **do**
- 6: $\mathbf{X}^{(l-1)} = \text{GCN}(\mathbf{A}, \mathbf{S}^{(l-1)}; \mathbf{W}^l)$;
- 7: $[\mathbf{S}^l, \mathbf{Z}^l] = \text{MSNeuron}(\mathbf{X}^{(l-1)}, \mathbf{Z}^{(l-1)})$;
- 8: **end for**
- 9: ▷ backward pass
- 10: Compute $\nabla_{\mathbf{z}^L} \mathcal{L}$ from $\mathcal{L}(\mathbf{Z}^L)$.
- 11: **for** layer $l = L - 1$ to 1 **do**
- 12: Compute $D_{\mathbf{z}^l} \psi^l, D_{\mathbf{v}^{l-1}} \phi^{l-1}, \frac{\partial \mathbf{v}^{l-1}}{\partial \mathbf{W}^l}$.
- 13: Compute $\nabla_{\mathbf{z}^l} \mathcal{L}, \nabla_{\mathbf{W}^l} \mathcal{L}$ as Eq. 12.
- 14: Update \mathbf{W}^l .
- 15: **end for**
- 16: **end while**

Theory: MSG as Neural ODE Solver

Definition 5.1 (Dynamic Chart Solver [17]). *The manifold ODE in Eq. (13) with initial condition $\mathbf{z}(0) = \mathbf{z}$ can be solved with a finite collection of successive charts $\{(U_i, \phi_i)\}_{i=1, \dots, L}$. If ode_i is the numerical solver to Euclidean ODE corresponding to the i -th chart, $\mathbf{y}(t) = \text{ode}_i(t)$ on $[\tau_i, \tau_i + \epsilon_i]$, then $\mathbf{z}(t)$ in Eq. (13) is given as*

$$(\phi_L^{-1} \circ \text{ode}_L \circ (\phi_L \circ \phi_{L-1}^{-1}) \circ \dots \circ (\phi_2 \circ \phi_1^{-1}) \circ \text{ode}_1 \circ \phi_1)(t). \quad (15)$$

That is, a manifold ODE can be solved in Euclidean subspaces given by a series of successive charts.

Theorem 5.2 (MSG as Dynamic Chart Solver). *If $\mathbf{y}(t) : [\tau, \tau + \epsilon] \rightarrow \mathbb{R}^n$ is the solution of*

$$\frac{d\mathbf{y}(t)}{dt} = (D_{\text{Exp}_{\mathbf{z}}(\mathbf{y}(t))} \text{Log}_{\mathbf{z}})u(\text{Exp}_{\mathbf{z}}(\mathbf{y}(t)), t), \quad (16)$$

then $\mathbf{z}(t) = \text{Exp}_{\mathbf{z}}(\mathbf{y}(t))$ is a valid solution to the manifold ODE of Eq. (13) on $t \in [\tau, \tau + \epsilon]$, where $\mathbf{z} = \mathbf{z}(\tau)$. If $\mathbf{y}(t)$ is given by the first-order approximation with the ϵ small enough,

$$\mathbf{y}(\tau + \epsilon) = \epsilon \cdot (D_{\mathbf{z}} \text{Log}_{\mathbf{z}})u(\mathbf{z}(\tau), \tau), \quad (17)$$

then the update process of Eqs. (4) and (8) in MSG is equivalent to Dynamic Chart Solver in Eq. (13).

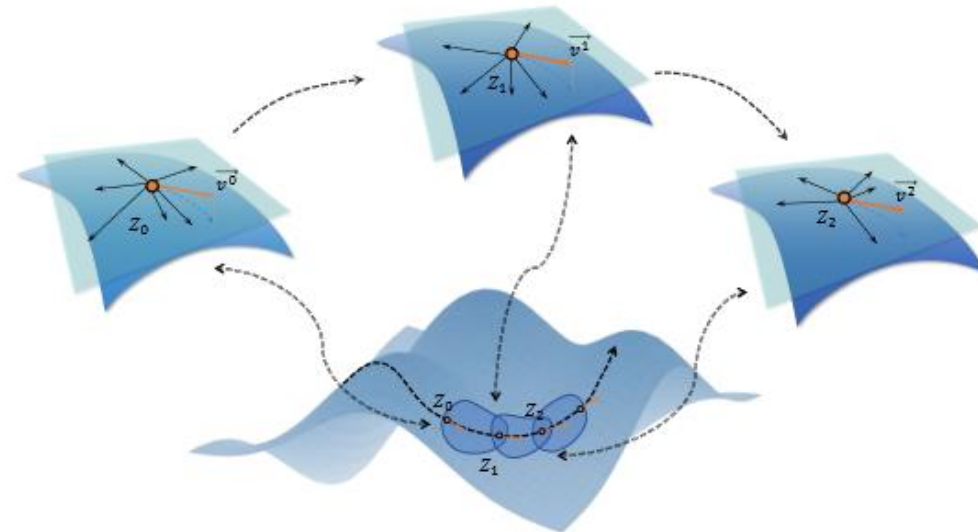


Figure 3: Charts given by the logarithmic map.

1. MSG approximates a solver of manifold Ordinary Differential Equations (ODEs).
2. Each layer solves the ODE of a smooth path, the endpoint is parameterized by a GNN related to the spikes.
3. Layer-by-layer forwarding solves the manifold ODE from the current chart to the successive chart.



Experiment Results

Table 1: Node Classification (NC) in terms of classification accuracy (%) and Link Prediction in terms of AUC (%) on Computers, Photo, CS and Physics datasets. The best results are **boldfaced**, and the runner-ups are underlined. The standard derivations are given in the subscripts.

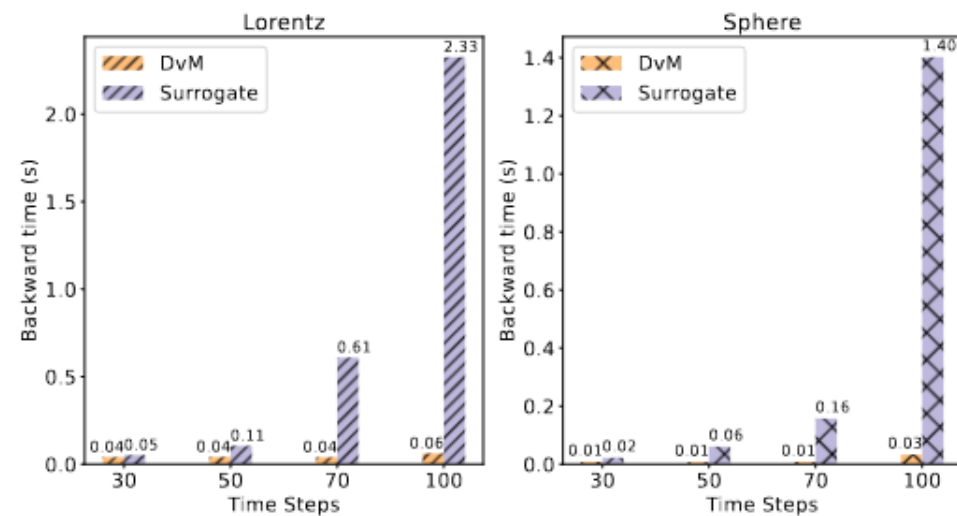
		Computers		Photo		CS		Physics	
		NC	LP	NC	LP	NC	LP	NC	LP
ANNE	GCN [19]	83.55±0.71	92.07±0.40	86.01±0.20	88.84±0.39	91.68±0.84	93.68±0.84	95.03±0.19	93.46±0.39
	GAT [2]	86.82±0.04	91.91±1.08	86.68±1.32	88.45±0.07	91.74±0.22	94.06±0.70	95.11±0.29	93.44±0.70
	SGC [19]	82.17±1.25	90.46±0.80	87.91±0.65	89.84±0.40	92.09±0.05	95.94±0.43	94.77±0.32	95.93±0.70
	SAGE [9]	81.69±0.86	90.56±0.48	89.41±1.28	89.86±0.90	92.71±0.73	95.22±0.14	95.62±0.26	95.75±0.37
ANN-R	HGCN [9]	88.71±0.24	<u>96.88±0.53</u>	89.18±0.50	94.54±0.20	90.72±0.16	93.02±0.26	94.46±0.20	94.10±0.64
	κ -GCN [13]	89.20±0.50	95.30±0.20	92.22±0.62	94.89±0.15	91.98±0.15	94.86±0.18	95.85±0.20	94.58±0.22
	Q-GCN [4]	85.94±0.93	96.98±0.05	92.50±0.95	<u>97.47±0.03</u>	91.18±0.28	93.39±0.20	94.84±0.25	OOM
	HyboNet [54]	86.29±2.30	96.80±0.05	92.67±0.09	97.70±0.07	92.34±0.03	95.65±0.26	95.56±0.18	98.46±0.49
SNN-E	SpikeNet [43]	88.00±0.70	-	<u>92.90±0.10</u>	-	92.15±0.18	-	92.66±0.30	-
	SpikeGCN [5]	86.90±0.30	91.12±1.79	92.60±0.70	93.84±0.03	90.86±0.11	95.07±1.22	94.53±0.18	92.88±0.80
	SpikeGCL [6]	89.04±0.08	92.72±0.03	92.50±0.17	95.58±0.11	91.77±0.11	95.13±0.24	95.21±0.10	94.15±0.29
	SpikeGT [55]	81.00±1.06	-	90.66±0.38	-	91.86±0.61	-	94.38±1.57	-
	MSG (Ours)	89.27±0.19	94.65±0.73	93.11±0.11	96.75±0.18	<u>92.65±0.04</u>	95.19±0.15	95.93±0.07	93.43±0.16

Table 3: Energy cost. The number of parameters at the running time (KB) and theoretical energy consumption (mJ) on Computers, Photo, CS and Physics datasets. The best results are **boldfaced**, and the runner ups are underlined.

		Computers		Photo		CS		Physics	
		#(para.)	energy	#(para.)	energy	#(para.)	energy	#(para.)	energy
ANNE	GCN [19]	24.91	1.671	24.14	0.893	218.29	18.444	269.48	42.842
	GAT [2]	24.99	2.477	24.22	1.273	218.38	28.782	269.55	81.466
	SGC [19]	7.68	0.508	5.97	0.219	102.09	8.621	42.08	6.688
	SAGE [9]	49.77	1.671	48.23	0.893	436.53	18.444	538.92	42.842
ANN-R	HGCN [9]	24.94	1.614	24.96	0.869	217.79	18.390	269.31	42.800
	κ -GCN [13]	25.89	1.647	25.12	0.889	218.24	18.440	269.44	42.836
	Q-GCN [4]	24.93	1.629	24.96	0.876	217.83	18.393	269.34	42.809
	HyboNet [54]	27.06	1.625	26.29	0.875	219.94	18.399	271.47	42.825
SNN-E	SpikeNet [43]	101.22	<u>0.070</u>	98.07	0.040	438.51	0.218	540.04	0.334
	SpikeGCN [5]	38.40	0.105	29.84	0.046	510.45	1.871	210.40	1.451
	SpikeGCL [6]	59.26	0.121	57.85	0.067	445.69	<u>0.128</u>	548.74	<u>0.214</u>
	SpikeGT [55]	77.07	1.090	74.46	0.584	365.28	6.985	355.77	12.524
	MSG(Ours)	26.95	0.047	25.68	<u>0.043</u>	226.15	0.026	143.72	0.029

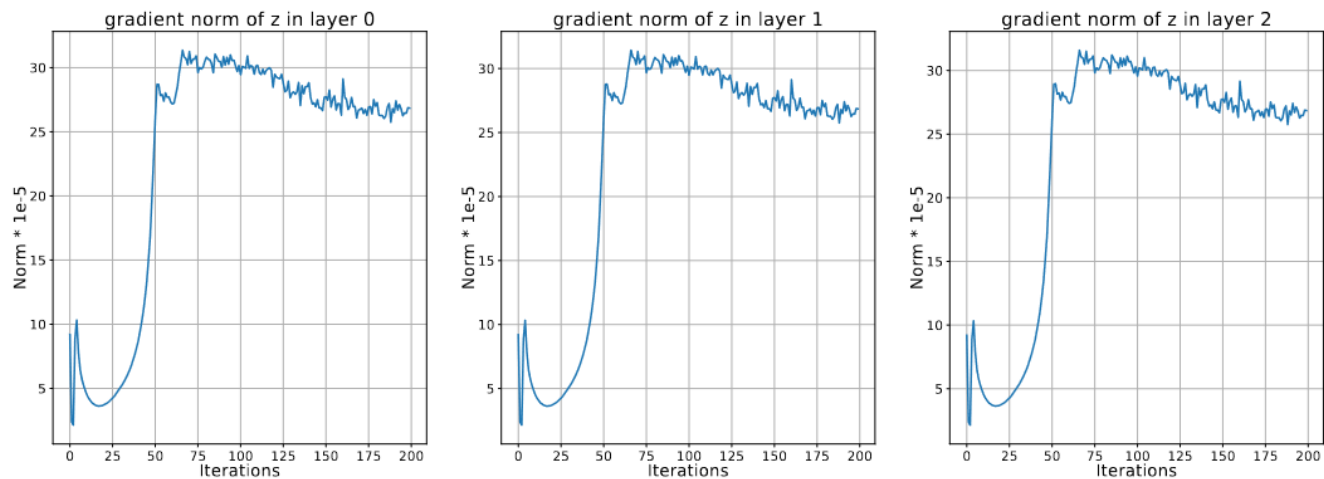
Table 2: Ablation study of geometric variants. Results of node classification in terms of ACC (%).

	Computers	Photo	CS	Physics
\mathbb{H}^{32}	89.27±0.19	93.11±0.11	92.65±0.04	95.93±0.07
\mathbb{S}^{32}	87.84±0.77	92.03±0.79	<u>92.72±0.06</u>	95.85±0.02
\mathbb{E}^{32}	88.94±0.24	92.93±0.21	92.82±0.04	95.81±0.04
$\mathbb{H}^{16} \times \mathbb{H}^{16}$	<u>89.18±0.25</u>	92.06±0.14	92.67±0.10	<u>95.90±0.04</u>
$\mathbb{H}^{16} \times \mathbb{S}^{16}$	88.00±1.05	91.97±0.08	92.33±0.21	95.73±0.11
$\mathbb{S}^{16} \times \mathbb{S}^{16}$	82.49±1.18	92.31±0.45	92.18±0.21	95.81±0.10

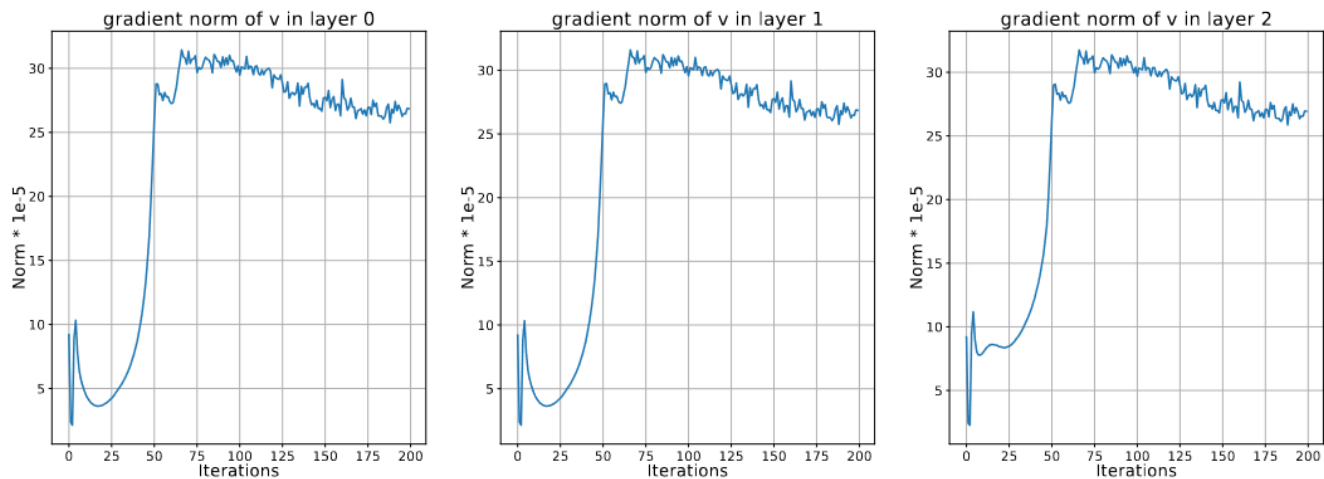


(a) Backward times in model training.

Visualizations



(a) The norm of backward gradient of L with respect to z in each spiking layers.



(b) The norm of backward gradient of L with respect to v in each spiking layers.

