The Prevalence of Neural Collapse in Neural Multivariate Regression

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Motivation





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Motivation

Neural Collapse (NC): observed during TPT of large overparameterized models for classification.

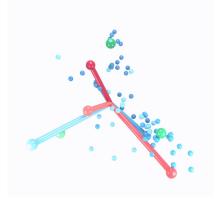
TPT: The post zero-error training phase

Papyan et al. (2020) outlined properties that describe the emergence of a geometric structure that induces maximally separated clustering between last-layer features and linear classifiers:

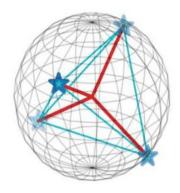
- NC1 Variability Collapse
- NC2 Convergence to Simplex ETF
- NC3 Convergence to Self-Duality
- NC4 Nearest Class-Mean Decision Rule

Empirical observations of NC were coupled by theoretical frameworks such as the unconstrained feature model (UFM).

The **UFM** helps explain why NC occurs in classification by allowing the optimization to freely adjust last-layer features along with classifier weights.



Papyan et al., 2020



Kim et al., 2024

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Recently,

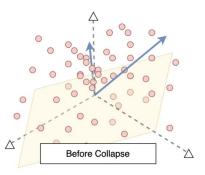
- NC has been investigated under different *loss functions and regularization techniques*.
- NC properties have been examined within *intermediate layers of DNNs*.
- NC phenomena have been studied for both *balanced/imbalanced data scenarios*.
- Under the NC framework, criteria have been devised for the *detection of OOD data*.
- NC provided a theoretical framework, which explained the **bias-variance alignment** in modern deep models.

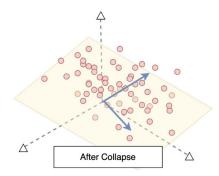
The prevalence and implications of NC in regression remained unexplored.

Regression serves numerous applications across diverse domains such as:

- Imitation learning for autonomous driving.
- Robotics.
- Forecasting stock prices, estimating risk, and predicting market trends.
- Meteorology.
- RL algorithms, where regression is employed to predict value functions, with the targets being Monte Carlo or bootstrapped returns.

Our work introduces Neural Regression Collapse (NRC) as a new form of NC for neural multivariate regression.





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Neural Regression Collapse (NRC)

Notations and Definitions





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Notations

- Multivariate regression: $\{(\mathbf{x}_i, \mathbf{y}_i), i = 1, ..., M\}$
- Targets: n-dim with sample cov matrix Σ and min eigenvalue λ_{\min}
- DNN: $f_{\theta, \mathbf{W}, \mathbf{b}}(\mathbf{x}) = \mathbf{W} \mathbf{h}_{\theta}(\mathbf{x}) + \mathbf{b}$
- Non-linear feature extractor: $\mathbf{h}_{\theta}(): \mathbb{R}^{D} \to \mathbb{R}^{d}, \mathbf{h}_{i} := \mathbf{h}_{\theta}(\mathbf{x}_{i}), \widetilde{\mathbf{h}}_{i} := \mathbf{h}_{i} \cdot ||\mathbf{h}_{i}||^{-1}$
- Feature matrix: $\mathbf{H} := [\mathbf{h}_1 \cdots \mathbf{h}_M]$
- Final linear layer: W
- For most neural regression tasks: **n << d**
- Train the DNN using GD to minimize the regularized L2 loss:

$$\min_{\theta, \mathbf{W}, \mathbf{b}} \frac{1}{2M} \sum_{i=1}^M ||f_{\theta, \mathbf{W}, \mathbf{b}}(\mathbf{x}_i) - \mathbf{y}_i||_2^2 + \frac{\lambda_\theta}{2} ||\theta||_2^2 + \frac{\lambda_\mathbf{W}}{2} ||\mathbf{W}||_F^2$$





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Definitions

Additional notation:

- $\operatorname{proj}(\mathbf{v}|\mathbf{C})$: projection of v to the column space of C.
- \mathbf{H}_{PCA_n} : columns consisting of the first **n** principal components of the features.

NRC1:

NRC2:

- Feature vector collapse
- The d-dim feature vectors collapse to a n-dim subspace spanned by their n principal components:

$$\operatorname{NRC1} = \frac{1}{M} \sum_{i=1}^{M} \left| \left| \widetilde{\mathbf{h}}_{i} - proj(\widetilde{\mathbf{h}}_{i} | \mathbf{H}_{PCA_{n}}) \right| \right|_{2}^{2} \to 0.$$

- Self duality
- The feature vectors also collapse to the n-dim space spanned by the rows of the last-layer weight matrix:

NRC2 =
$$\frac{1}{M} \sum_{i=1}^{M} \left\| \widetilde{\mathbf{h}}_{i} - proj(\widetilde{\mathbf{h}}_{i} | \mathbf{W}^{T}) \right\|_{2}^{2} \to 0.$$

NRC3:

• The Gram matrix of the last-layer weights converges to a specific functional form that depends on the square root of the covariance matrix of the targets. There exists a constant $\gamma \in (0, \lambda_{\min})$, such that:

$$\operatorname{NRC3} = \left\| \frac{\mathbf{W}\mathbf{W}^T}{||\mathbf{W}\mathbf{W}^T||_F} - \frac{\mathbf{\Sigma}^{1/2} - \gamma^{1/2}\mathbf{I}_n}{||\mathbf{\Sigma}^{1/2} - \gamma^{1/2}\mathbf{I}_n||_F} \right\|_F^2 \to 0.$$



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Main Experiments

Prevalence of NRC in Practice





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Experiment Setup

- MuJoCo Locomotion Datasets (Reacher, Swimmer, Hopper) [Brockman et al., 2016]:
 - Simulated robotic locomotion tasks with continuous control environments.
 - Input: State observations of the robot
 - Target: Optimal actions to achieve a task
 - Model: Multi-Layer Perceptron with 3 hidden layers of dimension 256.

• CARLA Dataset [Dosovitskiy et al., 2017]:

- Autonomous driving simulation with diverse traffic and environmental conditions.
- Input: RGB images from vehicle-mounted cameras.
- Target: Steering commands for navigation, e.g. speed and angle
- Model: ResNet18

• UTK Face Dataset [Zhang et al., 2017]:

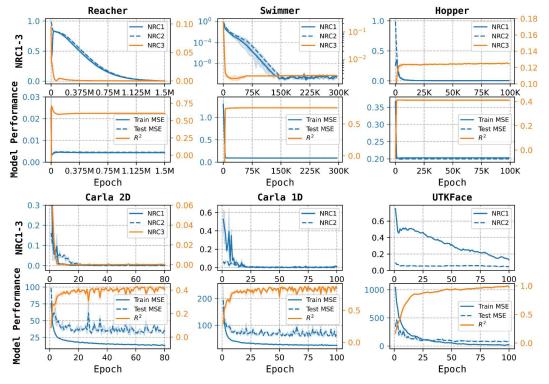
- Large-scale facial dataset labeled with age, gender, and ethnicity.
- Input: Facial images
- Target: Predicted attributes, e.g. age
- Model: ResNet 34







Results: Prevalence of NRC1-3



- Converging model performance metrics indicate training becomes stable.
- The presence of NRC1-NRC3 across six datasets indicates that neural collapse is not only prevalent in classification but also often occurs in multivariate regression.

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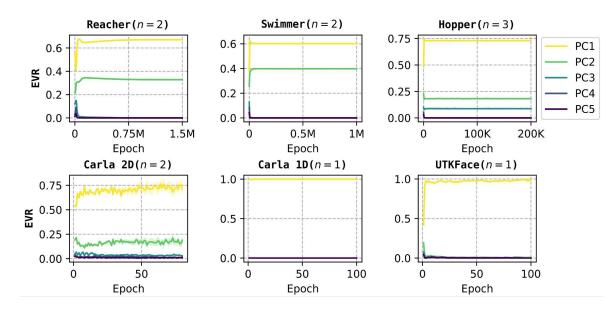
Figure 1: Prevalence of NRC1-NRC3 in the six datasets. Model performances are also shown.







Results (Cont.): Explained Variance Ratio



- Significant variance for all of the **first** *n* **components** after a short period of training;
- Very low or even no variance for other components;
- A perfect collapse occurs in the subspace spanned by the first *n* principal components.

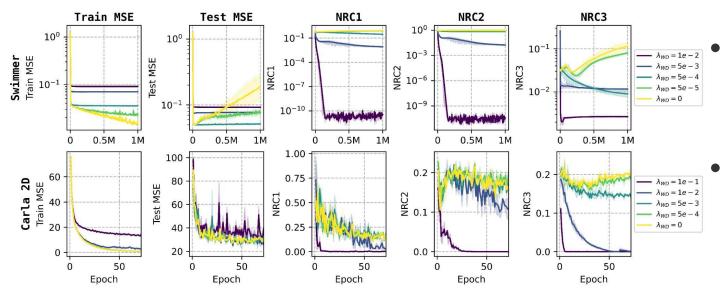
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Figure 2: Explained Variance Ratio (EVR) for the first 5 principal components (PC) of **H** during training. Target dimension is denoted as *n*.



Results (Cont.): Small Weight Decays



- As weight decay decreases, NRC1-3 become less:
 - NRC1-3 that emerges during training is **due to regularization**

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Figure 3: Examine NRC1-NRC3 with different weight decay values.





Theoretic Results

Prevalence of NRC in Theory





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Theoretic results

NRC1-3 emerge as solutions in the regularized UFM:

$$rac{1}{2M}||\mathbf{W}\mathbf{H}+\mathbf{b}\mathbf{1}_M^T-\mathbf{Y}||_F^2+rac{\lambda_{\mathbf{H}}}{2M}||\mathbf{H}||_F^2+rac{\lambda_{\mathbf{W}}}{2}||\mathbf{W}||_F^2$$

• All of the d-dim feature vectors lie in the n-dim space spanned by the n rows of W: $\sqrt{\lambda_{W}}$

$$\mathbf{H} = \sqrt{\frac{\lambda_{\mathbf{W}}}{\lambda_{\mathbf{H}}}} \mathbf{W}^{T} [\mathbf{\Sigma}^{1/2}]^{-1} (\mathbf{Y} - \bar{\mathbf{Y}})$$

• The theoretical result matches the definition of **NRC3** for $c = \lambda_W \lambda_H$:

$$\mathbf{W}\mathbf{W}^T = \sqrt{rac{\lambda_{\mathbf{H}}}{\lambda_{\mathbf{W}}}} \left[\mathbf{\Sigma}^{1/2} - \sqrt{c} \mathbf{I}_n
ight]$$

• At optimality, the **residual errors** are **uncorrelated** across the n target dimensions and each has **variance equal to c**:

$$\mathbf{W}\mathbf{H} + \mathbf{b}\mathbf{1}_M^T - \mathbf{Y} = -\sqrt{c}[\mathbf{\Sigma}^{1/2}]^{-1}(\mathbf{Y} - \bar{\mathbf{Y}})$$

No regularization implies **no collapse**: the emergence of NRC is due to inclusion of regularization in the loss function.



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