

#### **Elucidating the Design Space of Dataset Condensation**

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#### **What is Dataset Distillation/Condensation?**



Source: Dataset Distillation: A Comprehensive Reviewhttps://arxiv.org/pdf/2301.07014





# **Motivation**

■ *Some datasetcondensation (DC) methods incur high computational costs, which*

*limit scalability to larger datasets*

■ *Others are restricted to less optimal design spaces, which could hinder potential*

*improvements*



# **Definition**

**Preliminary.** Dataset condensation involves generating a synthetic dataset  $\mathcal{D}^{\mathcal{S}} := {\{\mathbf{x}_{i}^{\mathcal{S}}, \mathbf{y}_{i}^{\mathcal{S}}\}}_{i=1}^{|\mathcal{D}^{\mathcal{S}}|}$ consisting of images  $\mathcal{X}^S$  and labels  $\mathcal{Y}^S$ , designed to be as informative as the original dataset  $\mathcal{D}^{\mathcal{T}} := {\{\mathbf{x}_i^{\mathcal{T}}, \mathbf{y}_i^{\mathcal{T}}\}}_{i=1}^{|\mathcal{D}^{\mathcal{T}}|}$ , which includes images  $\mathcal{X}^{\mathcal{T}}$  and labels  $\mathcal{Y}^{\mathcal{T}}$ . The synthetic dataset  $\mathcal{D}^{\mathcal{S}}$  is substantially smaller in size than  $\mathcal{D}^{\mathcal{T}}(|\mathcal{D}^{\mathcal{S}}| \ll |\mathcal{D}^{\mathcal{T}}|)$ . The goal of this process is to maintain the critical attributes of  $\mathcal{D}^{\mathcal{T}}$  to ensure robust or comparable performance during evaluations on test protocol  $\mathcal{P}_{\mathcal{D}}$ .

 $\arg \min \mathbb{E}_{(\mathbf{x}, \mathbf{y}) \sim \mathcal{P}_{\mathcal{D}}}[\ell_{eval}(\mathbf{x}, \mathbf{y}, \phi^*)], \text{ where } \phi^* = \arg \min_{\phi} \mathbb{E}_{(\mathbf{x}_i^{\mathcal{S}}, \mathbf{y}_i^{\mathcal{S}}) \sim \mathcal{D}^{\mathcal{S}}}[\ell(\phi(\mathbf{x}_i^{\mathcal{S}}), \mathbf{y}_i^{\mathcal{S}})].$  $(1)$ 



# Definition

 $\mathcal{L}_{syn} = ||p(\mu|\mathcal{X}^{\mathcal{S}}) - p(\mu|\mathcal{X}^{\mathcal{T}})||_2 + ||p(\sigma^2|\mathcal{X}^{\mathcal{S}}) - p(\sigma^2|\mathcal{X}^{\mathcal{T}})||_2, \ s.t. \ \mathcal{L}_{syn} \sim \mathbb{S}_{match},$  $\mathcal{X}^{\mathcal{S}*} = \arg \min \mathbb{E}_{\mathcal{L}_{syn}\sim \mathbb{S}_{match}} [\mathcal{L}_{syn}(\mathcal{X}^{\mathcal{S}}, \mathcal{X}^{\mathcal{T}})],$ 

> $\mathcal{X}^{\mathcal{S}} = \bigcup_{i}^{\infty} \mathcal{X}_{i}^{\mathcal{S}}, \ \mathcal{X}_{i}^{\mathcal{S}} = \{\mathbf{x}_{j}^{i} = \text{concat}(\{\tilde{\mathbf{x}}_{k}\}_{k=1}^{N} \subset \mathcal{X}_{i}^{\mathcal{T}})\}_{j=1}^{IPC},$  $(3)$

 $(2)$ 

 $(4)$ 

where C denotes the number of classes, concat( $\cdot$ ) represents the concatenation operator,  $\mathcal{X}_i^{\mathcal{S}}$  signifies the set of condensed images belonging to the *i*-th class, and  $\mathcal{X}_i^{\mathcal{T}}$  corresponds to the set of original images of the *i*-th class. It is important to note that the default settings for N are 1 and 4, as specified in the works (Zhou et al., 2023) and (Sun et al., 2024), respectively. Using one or more observer models, denoted as  $\{\phi_i\}_{i=1}^N$ , we then derive the soft labels  $\mathcal{Y}^S$  from the condensed image set  $\mathcal{X}^S$ .

$$
\mathcal{Y}^{\mathcal{S}} = \bigcup_{\mathbf{x}_i^{\mathcal{S}} \subset \mathcal{X}^{\mathcal{S}}} \frac{1}{N} \sum_{i=1}^N \phi_i(\mathbf{x}_i^{\mathcal{S}}).
$$

## **Design Choice**

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#### **Observation**





---- w/o reducing sharpness

w/ reducing sharpness

original dataset distilled dataset

128 256 512 1024

 $\overline{32}$  $64$ 

 $(c)$ 

Figure 2: (a): Illustration of soft category-aware matching (2) using a Gaussian distribution in  $\mathbb{R}^2$ . (b): The effect of employing smoothing LR schedule  $\left(\bigcirc\right)$  on loss landscape sharpness reduction. (c) top: The role of flatness regularization  $(6)$  in reducing the Frobenius norm of the Hessian matrix driven by data synthesis iteration. (c) bottom: Cosine similarity comparison between local gradients (obtained from original and distilled datasets via random batch selection) and the global gradient (obtained from gradient accumulation).



## **Real Data Initialization**



#### **Soft Category-aware Matching**

**Sketch Definition 3.1.** (formal definition in Appendix B.2) Given N random samples  $\{x_i\}_{i=1}^N$  with an unknown distribution  $p_{mix}(x)$ , we define two forms to statistical matching. Form (1): involves synthesizing M distilled samples  $\{y_i\}_{i=1}^M$ , where  $M \ll N$ , ensuring that the variances and means of both  $\{x_i\}_{i=1}^N$  and  $\{y_i\}_{i=1}^M$  are consistent. Form (2): treats  $p_{mix}(x)$  as a GMM with C components. For random samples  $\{x_i^j\}_{i=1}^{N_j}$  ( $\sum_j N_j = N$ ) within each component  $c_j$ , we synthesize  $M_j$  ( $\sum_j M_j = M$ ) distilled samples  $\{y_i^j\}_{i=1}^{M_j}$ , where  $M_j \ll N_j$ , to maintain the consistency of variances and means between  $\{x_i^j\}_{i=1}^{N_j}$  and  $\{y_i^j\}_{i=1}^{M_j}$ .

e.g., soft category-aware matching More details of proofs and theorems can be found in our paper  $\mathcal{L}_{\text{syn}}' = \alpha ||p(\mu|\mathcal{X}^{\mathcal{S}}) - p(\mu|\mathcal{X}^{\mathcal{T}})||_2 + ||p(\sigma^2|\mathcal{X}^{\mathcal{S}}) - p(\sigma^2|\mathcal{X}^{\mathcal{T}})||_2$  #Form (1)  $+\left(1-\alpha\right)\sum p(c_i)\left[||p(\mu|{\cal X}^{\cal S},c_i)-p(\mu|{\cal X}^{\cal T},c_i)||_2+||p(\sigma^2|{\cal X}^{\cal S},c_i)-p(\sigma^2|{\cal X}^{\cal T},c_i)||_2\right],$  $#Form(2)$ 

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#### **Soft Category-aware Matching**

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> **Theorem 3.2.** (proofs in Theorems B.5, B.7, B.8 and Corollary B.6) Given the original data distribution  $p_{mix}(x)$ , and define condensed samples as x and y in **Form (1)** and **Form (2)** with their distributions characterized by P and Q. Subsequently, it follows that (i)  $\mathbb{E}[x] \equiv \mathbb{E}[y]$ , (ii)  $\mathbb{D}[x] \equiv \mathbb{D}[y]$ , (iii)  $\mathcal{H}(P) - \frac{1}{2} [\log(\mathbb{E}[\mathbb{D}[y^j]] + \mathbb{D}[\mathbb{E}[y^j]]) - \mathbb{E}[\log(\mathbb{D}[y^j])]] \leq \mathcal{H}(Q) \leq \mathcal{H}(P) +$  $\frac{1}{4}\mathbb{E}_{(i,j)\sim\prod[\mathbf{C},\mathbf{C}]} \left[ \frac{(\mathbb{E}[y^i]-\mathbb{E}[y^j])^2(\mathbb{D}[y^i]+\mathbb{D}[y^j])}{\mathbb{D}[y^i]\mathbb{D}[y^j]} \right]$  and (iv)  $D_{KL}[p_{mix}||P] \leq \mathbb{E}_{i\sim\mathcal{U}[1,...,\mathbf{C}]} \mathbb{E}_{j\sim\mathcal{U}[1,...,\mathbf{C}]} \frac{\mathbb{E}[y^j]^2}{\mathbb{D}[y^i]}$ and  $D_{KL}[p_{mix}||Q] = 0$ .



#### **Flatness Regularization**

 $\mathcal{L}_{FR} = \mathbb{E}_{\mathcal{L}_{syn}\sim\mathbb{S}_{match}}[\mathcal{L}_{syn}(\mathcal{X}^{\mathcal{S}}, \mathcal{X}_{EMA}^{\mathcal{S}})], \ \mathcal{X}_{EMA}^{\mathcal{S}} = \beta \mathcal{X}_{EMA}^{\mathcal{S}} + (1-\beta)\mathcal{X}^{\mathcal{S}},$ 

**Theorem 3.3.** (proof in Appendix E) The optimization objective  $\mathcal{L}_{FR}$  can ensure sharpness-aware minimization within a  $\rho$ -ball for each point along a straight path between  $\mathcal{X}^S$  and  $\mathcal{X}^S$  and  $\mathcal{X}^S$ 

 $\mathcal{L}'_{FR} = D_{KL}(\text{softmax}(\phi(\mathcal{X}^S)/\tau)||\text{softmax}(\phi(\mathcal{X}^S_{EMA})/\tau)), \ \mathcal{X}^S_{EMA} = \beta \mathcal{X}^S_{EMA} + (1 - \beta)\mathcal{X}^S,$ 







Table 1: Comparison with the SOTA baseline dataset condensation methods. SRe<sup>2</sup>L and RDED utilize ResNet-18 for data synthesis, whereas G-VBSM and EDC leverage various backbones for this purpose.

#### **Experiment**

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Table 2: Cross-architecture generalization comparison with different IPCs on ImageNet-1k. RDED refers to the latest SOTA method on ImageNet-1k and  $+\Delta$  stands for the improvement for each architecture.

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#### **Experiment**



Table 3: Ablation studies on ImageNet-1k with IPC 10. Left: Explore the influence of the slowdown coefficient  $\zeta$  with CONFIG C. Right: Evaluate the effectiveness of real image initialization ( $\odot$ ), smoothing LR schedule ( $\odot$ ) and smaller batch size ( $\odot$  $\odot$ ) with  $\zeta = 2$ .



Table 4: Ablation studies on ImageNet-1k with IPC 10. Investigate the potential effects of several factors, including loss type, loss weight,  $\beta$ , and  $\tau$ , amid flatness regularization ( $\odot$ ).

## **Experiment**

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Table 5: Ablation studies on ImageNet-1k with IPC 10. Evaluate the effectiveness of several design choices, including soft category-aware matching  $(\bigcircled{e})$ , weak augmentation  $(\bigcircled{e})$  and EMA-based evaluation  $(\bigcircled{e})$ .







Figure 4: Application on ImageNet-1k. We evaluate the effectiveness of data-free network slimming and continual learning using VGG11-BN and ResNet-18, respectively.



Table 22: Comparison of Different Methods on ImageNet-21k.

# THANK YOU!