



# Geometric Exploitation for Infor Panoramic Semantic Segmentation

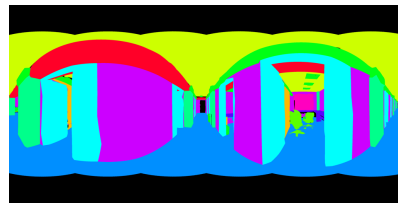
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# Approach for Indoor Panoramic Semantic Segmentation



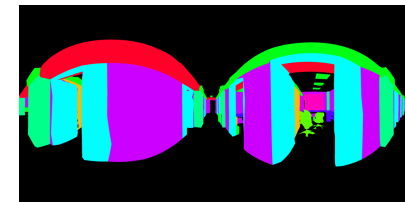
Deep Neural Network



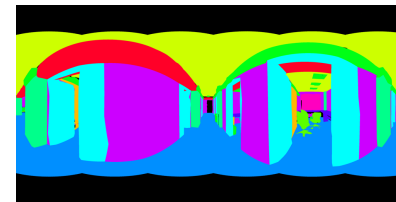
Traditional approach



Over-sampled segments



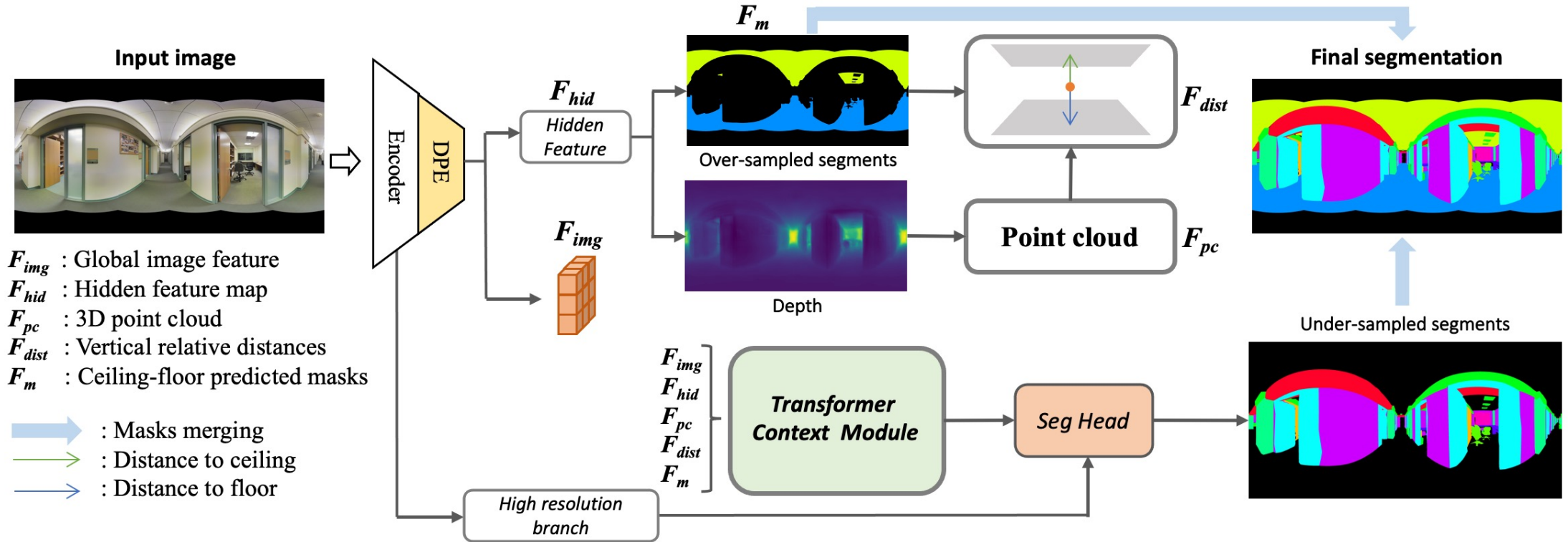
Under-sampled segments



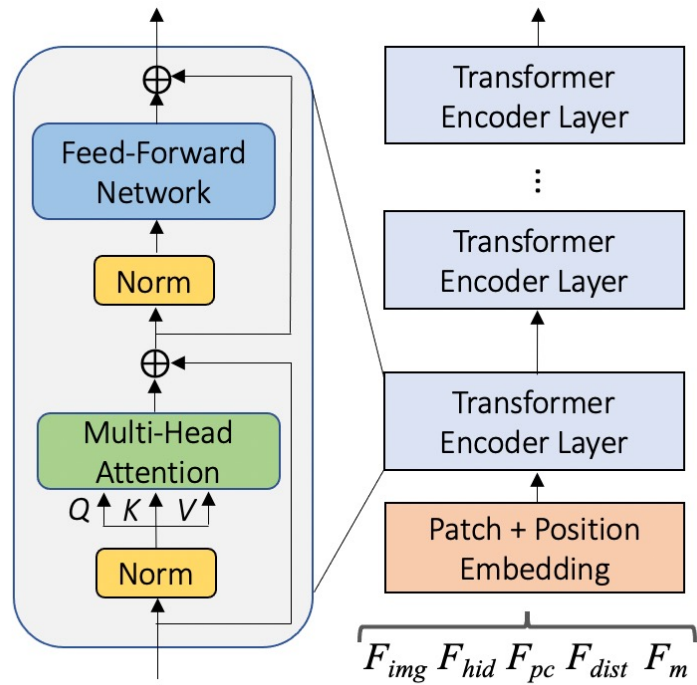
Our approach



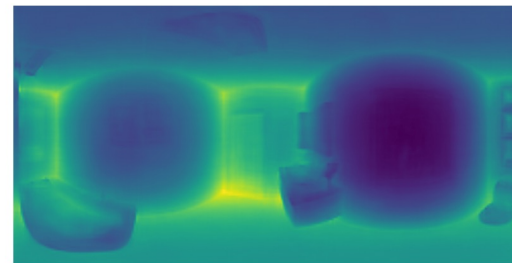
# Method



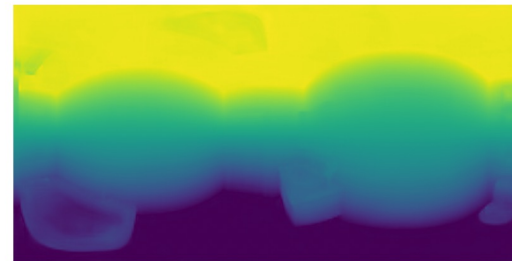
# Proposed Concepts



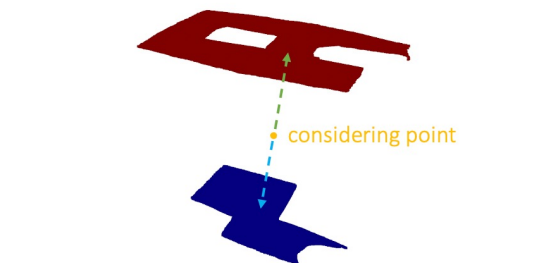
Transformer Based  
Context Module



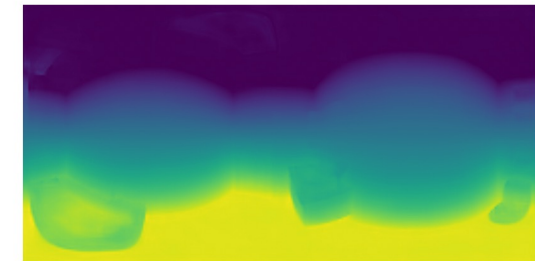
Estimated Depth



Distance to Floor



Fitting planes



Distance to Ceiling

Vertical Relative  
Distance

# Quantitative results

Quantitative comparison on the **Stanford2D3DS** dataset

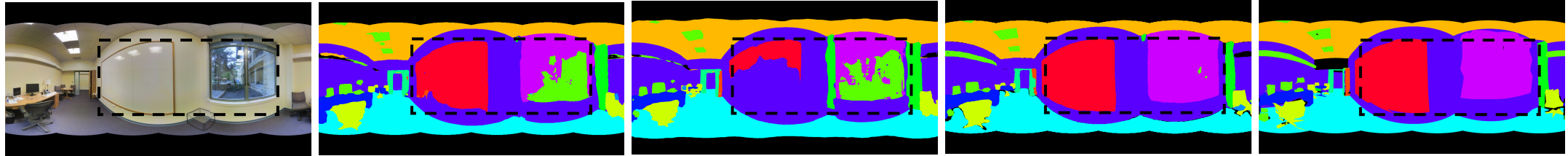
Method	Venue	Validation Avg mIoU (%)	Validation F1 mIoU (%)
Tangent [10]	CVPR 2019	45.6	-
FreDSNet [4]	ICRA 2022	-	46.1
PanoFormer [22]	ECCV 2022	48.9	-
SFSS-MMSI [12]	WACV 2024	-	52.9
HoHoNet [24]	CVPR 2021	52.0	53.9
Trans4PASS [34]	CVPR 2022	52.1	53.3
Trans4PASS+ [35]	Arxiv 2022	53.7	53.6
SGAT4PASS [18]	IJCAI 2023	55.3	56.4
<b>Ours</b>		<b>55.5</b>	<b>56.8</b>

Quantitative comparison on the **Structured3D** and **Matterport3D** datasets

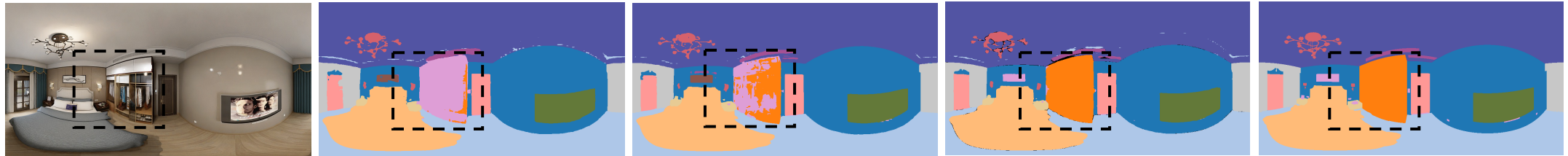
Methods	Modal	Structured3D		Matterport3D	
		Val mIoU (%)	Test mIoU (%)	Val mIoU (%)	Test mIoU (%)
PanoFormer [22]	RGB	55.57	54.87	30.04	26.87
Trans4PASS+ [35]	RGB	66.74	66.90	33.43	29.21
SFSS-MMSI [12]	RGB	71.94	68.34	35.15	31.30
PanoFormer [22]	RGBD	60.98	59.27	33.99	31.23
SFSS-MMSI [12]	RGBD	<b>73.78</b>	70.17	<b>39.19</b>	<b>35.92</b>
<b>Ours</b>	RGB	<b>72.86</b>	<b>71.66</b>	<b>36.42</b>	<b>33.06</b>

# Qualitative results

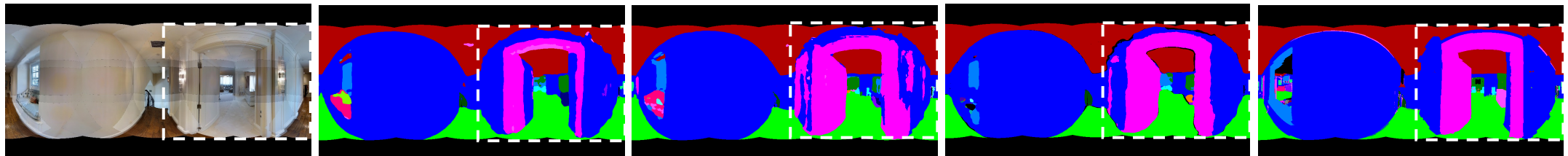
Stanford2D3DS dataset



Structured3D dataset



Matterport3D dataset



Image

Trans4PASS+

SFSS-MMSI

Ours

Ground Truth





Thank you!

