Only Strict Saddles in the Energy Landscape of Predictive Coding Networks?



Francesco Innocenti



El Mehdi Achour



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Ryan Singh



Christopher L. Buckley

OF SUSSEX





Predictive coding inference seems to make the loss landscape of feedforward neural networks more benign and robust to vanishing gradients.



- 1. Introduction
- 2. Preliminaries
- 3. Theoretical results
- 4. Experiments
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Introduction: predictive coding

- **Predictive coding** (PC) is a brain-inspired learning algorithm that can train deep neural networks (DNNs) as an alternative to backpropagation (BP)
- In contrast to BP, PC **iteratively infers network activities** before updating weights
- This incurs an extra compute cost, but it has been argued to provide many benefits such as faster learning convergence [Song et al. '22]
- However, these speed-ups are not always observed, and the impact of PC inference on learning is not theoretically well understood



ospective configuration Network structure Feature maps: Feature maps: 0.32 128@8 × 8 Inputs: 64@16 × 16 -200 3@32 × 32 Output neurons: 0.31 10 Ъ -300 Rule 0.30 Prospective configuration Backpropagation 400 **∑** 0.29 Convolution Convolution Flatter Kernel size: 3 Kernel size: 3 -500 Stride: 2 Stride: 2 10-5 10-4 Padding: 1 10³ 10³ Padding: 1 Training episode Training episode Learning rate



Introduction: approach

- To address this gap, we study the geometry of the effective landscape on which PC learns: *the weight landscape at the equilibrium of the* network activities
- We focus on **saddle points** of the equilibrated energy



Introduction: saddles & neural networks

- Saddles are ubiquitous in the loss landscape of DNNs [Dauphin et al. '14]
- They have been characterised as [e.g. Get et al. '15]:
 - i) "Strict", with negative curvature (indefinite Hessian), or
 - ii) "Non-strict", where an escape (negative) direction is found in higher-order (n>2) derivatives
- Stochastic gradient descent (SGD) can be exponentially slowed by strict saddles [Du et al. '17] and effectively get stuck in non-strict ones [e.g. Böttcher & Wheeler '24]
 - (This is vanishing gradients from a landscape perspective [Orvieto et al. '22].)



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Introduction: contributions

- For DLNs, we first show that, at the equilibrium of the network activities, the PC energy is equal to a rescaled mean squared error (MSE) loss with a weight-dependent rescaling
- We then prove that many highly degenerate (non-strict) saddles of the loss become much easier to escape (strict) in the equilibrated energy
- We empirically verify that our linear theory holds for non-linear networks
- We provide evidence that other non-strict saddles of the loss that we do not address theoretically also become strict in the equilibrated energy

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Preliminaries

• MSE loss for DLNs:

- PC energy for DLNs:
- Minimised in 2 phases: Inference: $\Delta \mathbf{z}_{\ell} \propto -\frac{\partial \mathcal{F}}{\partial \mathbf{z}_{\ell}}$ Learn
- equilibrium $\mathcal{F}|_{\partial \mathcal{F}/\partial \mathbf{z}=0}(\boldsymbol{\theta})$ which we will abbreviate as $\mathcal{F}^*(\boldsymbol{\theta})$

$$\begin{split} \mathcal{L} &= \frac{1}{2N} \sum_{i=1}^{N} ||\mathbf{y}_{i} - \mathbf{W}_{L:1} \mathbf{x}_{i}||^{2} \\ \mathcal{F} &= \frac{1}{2N} \sum_{i=1}^{N} \sum_{\ell=1}^{L} ||\mathbf{z}_{\ell,i} - \mathbf{W}_{\ell} \mathbf{z}_{\ell-1,i}||^{2} \\ \frac{\mathcal{F}}{\partial_{\ell}} \qquad \text{Learning:} \quad \Delta \mathbf{W}_{\ell} \propto -\frac{\partial \mathcal{F}}{\partial \mathbf{W}_{\ell}} \end{split}$$

• In practice, inference is run to convergence until $\Delta z_{\ell} \approx 0$ before updating the weights

• Importantly, the **effective landscape** on which PC learns is the energy at the inference

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Theoretical results: equilibrated energy as rescaled MSE

• At the inference equilibrium, the PC energy turns out to be equal to a rescaled MSE loss

Theorem 1 (Equilibrated energy for DLNs). For any DLN parameterised by $\theta := (\mathbf{W}_1, \dots, \mathbf{W}_L)$ with input and output $(\mathbf{x}_i, \mathbf{y}_i)$, the PC energy (Eq. 2) at the exact inference equilibrium $\partial \mathcal{F}/\partial \mathbf{z} = \mathbf{0}$ is the following rescaled MSE loss (see §A.3.2 for derivation)

$$\mathcal{F}^* = \frac{1}{2N} \sum_{i=1}^{N} (\mathbf{y}_i - \mathbf{v}_i)$$

where the rescaling is $\mathbf{S} = \mathbf{I}_{d_y} + \sum_{\ell=2}^{L} (\mathbf{W}_{L:\ell}) (\mathbf{W}_{L:\ell})^T$.

$$\mathbf{W}_{L:1}\mathbf{x}_i)^T \mathbf{S}^{-1} (\mathbf{y}_i - \mathbf{W}_{L:1}\mathbf{x}_i)$$
(5)

Theoretical results: equilibrated energy as rescaled MSE



Theoretical results: saddle analysis

escape (strict) in the equilibrated energy

Theorem 3 (Strictness of zero-rank saddles of the equilibrated energy). Consider the set of critical points of the equilibrated energy (Eq. 5) $\theta^*(\mathbf{W}_L = \mathbf{0}, \mathbf{W}_{L-1:1} = \mathbf{0})$ where $\mathbf{g}_{\mathcal{F}^*}(\boldsymbol{\theta}^*) = \mathbf{0}$. The Hessian at these points has at least one negative eigenvalue (see §A.3.6) *for proof*)

• Many highly degenerate (non-strict) saddles of the MSE loss become much easier to

 $\exists \lambda(\mathbf{H}_{\mathcal{F}^*}(\boldsymbol{\theta}^*)) < 0 \quad [strict saddles, Def.]$ (10)

• These saddles include the origin, effectively making PC more robust to vanishing gradients

Theoretical results: saddle analysis

• Toy examples illustrating the result for the origin saddle



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Experiments: what about non-linear networks?

TSINM

Fashion-M

CIFAR-10

 \smile

- To test the theory, we train various network the considered saddles (e.g. origin)
- We find that, for the same learning rate, SGD on the equilibrated energy (PC) escapes much faster than on the loss (BP)

• To test the theory, we train various networks on standard datasets by initialising close to









Experiments: what about other saddles?

goes through these other saddles



• To test other non-strict saddles of the loss that we do not address theoretically, we train networks on a matrix completion task, where we know that starting near origin GD

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Conclusion

- **Conjecture**: all the saddles of the equilibrated energy are strict
- **Conclusion**: our work suggests that PC inference makes the loss landscape of feedforward neural networks more benign or easier to navigate
- remains a key challenge for scaling PC to large tasks

• **Summary:** we provided theoretical and empirical evidence that the effective landscape on which PC learns has only strict saddles and is more robust to vanishing gradients

• Limitation: inference convergence significantly slows down with network depth and

El Mehdi Achour

Thank you for your attention!

Ryan Singh

Christopher L. Buckley

