Only Strict Saddles in the Energy Landscape of Predictive Coding Networks?

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Predictive coding inference seems to make the loss landscape of feedforward neural networks more benign and robust to vanishing gradients.

- 1. Introduction
- 2. Preliminaries
- 3. Theoretical results
- 4. Experiments
- 5. Conclusion

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Introduction: **predictive coding**

- **Predictive coding** (PC) is a brain-inspired learning algorithm that can train deep neural networks (DNNs) as an alternative to backpropagation (BP)
- In contrast to BP, PC **iteratively infers network activities** before updating weights
- This incurs an extra compute cost, but it has been argued to provide many benefits such as **faster learning convergence** [Song et al. '22]
- However, these speed-ups are not always observed, and the impact of PC inference on learning is not theoretically well understood

Network structur Feature maps: Feature maps: 0.32 Inputs: $128@8 × 8$ $64@16 \times 16$ -200 $3@32 \times 32$ Output neurons: 0.31 ঁত -300 Rule 200 $\frac{1}{2}$ 0.30 Prospective configuration Backpropagation -400 $\sum 0.29$ Convolution Convolution Flatter Kernel size: 3 Kernel size: 3 -500 Stride: 2 Stride: 2 10^{-5} 10^{-4} Padding: 1 $10³$ $10³$ Padding: 1 Training episode Learning rate Training episode

Introduction: **approach**

- To address this gap, we study the geometry of the effective landscape on which PC learns: *the weight landscape at the equilibrium of the network activities*
- We focus on **saddle points** of the equilibrated energy

Introduction: **saddles & neural networks**

- Saddles are ubiquitous in the loss landscape of DNNs [Dauphin et al. '14]
- They have been characterised as [e.g. Get et al. '15]:
	- i) "**Strict**", with negative curvature (indefinite Hessian), or
	- ii) "**Non-strict**", where an escape (negative) direction is found in higher-order (n>2) derivatives
- Stochastic gradient descent (SGD) can be exponentially slowed by strict saddles [Du et al. '17] and effectively get stuck in non-strict ones [e.g. Böttcher & Wheeler '24]
	- (This is vanishing gradients from a landscape perspective [Orvieto et al. '22].)

Introduction: **contributions**

- For DLNs, we first show that, at the equilibrium of the network activities, the PC energy is equal to a rescaled mean squared error (MSE) loss with a weight-dependent rescaling
- We then prove that many highly degenerate (non-strict) saddles of the loss become much easier to escape (strict) in the equilibrated energy
- We empirically verify that our linear theory holds for non-linear networks
- We provide evidence that other non-strict saddles of the loss that we do not address theoretically also become strict in the equilibrated energy

- 1. Introduction
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Preliminaries

- PC energy for DLNs:
- Minimised in 2 phases: Inference: $\Delta \mathbf{z}_{\ell} \propto -\frac{\partial \mathcal{F}}{\partial \mathbf{z}_{\ell}}$ Learr
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- equilibrium $\mathcal{F}|_{\partial \mathcal{F}/\partial z=0}(\theta)$ which we will abbreviate as $\mathcal{F}^*(\theta)$

$$
\mathcal{L} = \frac{1}{2N} \sum_{i=1}^{N} ||\mathbf{y}_i - \mathbf{W}_{L:1} \mathbf{x}_i||^2
$$

$$
\mathcal{F} = \frac{1}{2N} \sum_{i=1}^{N} \sum_{\ell=1}^{L} ||\mathbf{z}_{\ell,i} - \mathbf{W}_{\ell} \mathbf{z}_{\ell-1,i}||^2
$$

$$
\frac{1}{\sum_{i \in \ell}} \text{ Learning:} \quad \Delta \mathbf{W}_{\ell} \propto -\frac{\partial \mathcal{F}}{\partial \mathbf{W}_{\ell}}
$$

• In practice, inference is run to convergence until $\Delta z_{\ell} \approx 0$ before updating the weights

• Importantly, the **effective landscape** on which PC learns is the energy at the inference

• MSE loss for DLNs:

- 1. Introduction
- 2. Preliminaries
- **3. Theoretical results**
- 4. Experiments
- 5. Conclusion

Theoretical results: **equilibrated energy as rescaled MSE**

• At the inference equilibrium, the PC energy turns out to be equal to a rescaled MSE loss

Theorem 1 (Equilibrated energy for DLNs). For any DLN parameterised by θ = $(\mathbf{W}_1,\ldots,\mathbf{W}_L)$ with input and output $(\mathbf{x}_i,\mathbf{y}_i)$, the PC energy (Eq. 2) at the exact inference equilibrium $\partial \mathcal{F}/\partial \mathbf{z} = \mathbf{0}$ is the following rescaled MSE loss (see §A.3.2 for derivation)

$$
\mathcal{F}^* = \frac{1}{2N} \sum_{i=1}^N (\mathbf{y}_i - \mathbf{V})
$$

where the rescaling is $S = I_{d_y} + \sum_{\ell=2}^{L} (\mathbf{W}_{L:\ell})(\mathbf{W}_{L:\ell})^T$.

$$
\mathbf{V}_{L:1}\mathbf{x}_i)^T\mathbf{S}^{-1}(\mathbf{y}_i - \mathbf{W}_{L:1}\mathbf{x}_i)
$$
 (5)

Theoretical results: **equilibrated energy as rescaled MSE** Ω \dot{e} *⁄max* \blacksquare Ò *L***m** *◊* = $\overline{\mathbf{a}}$ *|| |* \overline{r} peute partitibrated preray as rescaled *... e || |* \mathbf{r} |
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Theoretical results: **saddle analysis**

escape (strict) in the equilibrated energy

Theorem 3 (Strictness of zero-rank saddles of the equilibrated energy). Consider the set of critical points of the equilibrated energy (Eq. 5) $\theta^*(W_L = 0, W_{L-1:1} = 0)$ where $g_{\mathcal{F}^*}(\theta^*) = 0$. The Hessian at these points has at least one negative eigenvalue (see §A.3.6) for proof)

• Many highly degenerate (non-strict) saddles of the MSE loss become much easier to

 $\exists \lambda(\mathbf{H}_{\mathcal{F}^*}(\boldsymbol{\theta}^*))$ < 0 [strict saddles, Def. 1] (10)

• These saddles include the origin, effectively making PC more robust to vanishing gradients

Theoretical results: **saddle analysis**

• Toy examples illustrating the result for the origin saddle

- 1. Introduction
- 2. Preliminaries
- 3. Theoretical results
- **4. Experiments**
- 5. Conclusion

Experiments: **what about non-linear networks?** lear networ ú)) *>* 0 and

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 C MNIST MNIST-1D Fashion-MNIST CIFAR-10 • To test the theory, we train various networks on standard datasets by initialising close to the considered saddles (e.g. origin)
- We find that, for the same learning rate, SGD on the equilibrated energy (PC) escapes much faster than on the loss (BP)

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Experiments: **what about other saddles?**

• To test other non-strict saddles of the loss that we do not address theoretically, we train networks on a matrix completion task, where we know that starting near origin GD

goes through these other saddles

- 1. Introduction
- 2. Preliminaries
- 3. Theoretical results
- 4. Experiments
- **5. Conclusion**

Conclusion

• **Summary:** we provided theoretical and empirical evidence that the effective landscape on which PC learns has only strict saddles and is more robust to vanishing gradients

• **Limitation**: inference convergence significantly slows down with network depth and

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- **Conjecture**: all the saddles of the equilibrated energy are strict
- **Conclusion**: our work suggests that PC inference makes the loss landscape of feedforward neural networks more benign or easier to navigate
- remains a key challenge for scaling PC to large tasks

Thank you for your attention!

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