

Advancing Spiking Neural Networks for Sequential Modeling with Central Pattern Generators

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- Spiking Neural Networks
- Central Pattern Generators

➢ **Methods**

- Relationship between PE and CPGs
- Implementations

- Main Results
- Analysis

2

Time (ms)

3

"Training Spiking Neural Networks Using Lessons From Deep Learning."

0

Eshraghian, Jason Kamran et al. 2021

Threshold Potential

• Floating-point Numbers

• Binary Value

Soma

Dendrites

 $70 -$

50

30 10 $-10 +$ $-30 -50 -70$

Membrane Po<mark>ț</mark>ential (mV)
Membrane Po**ț**ential (mV)

Spiking Neural Networks

SNN version of Transformer

- In Transformer models, positional encoding:
	- $PE_{(pos, 2i)} = \sin\left(\frac{pos}{10000^{2i/d}}\right),$ $PE_{(pos, 2i+1)} = \cos\left(\frac{pos}{10000^{2i/d}}\right)$
- However, in the SNN version of Transformer (Spikformer), there has not been a good mechanism for Positional Encoding (PE).
	- **Positional encoding neurons in Transformer outputs float numbers.**
	- The output of SNN neurons is 1 or 0

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Central Pattern Generators

Central Pattern Generators (CPG) is a group of neurons capable of producing rhythmic patterned outputs without requiring rhythmic inputs.

Muscle (motor) commands

These neural circuits are responsible for generating the rhythmic signals that control vital activities such as locomotion, respiration, and chewing

Marder, Eve; Bucher, Dirk (2001-11-27). "Central pattern generators and the control of rhythmic movements". Current Biology. 11 (23): R986–R996

Simple Model

Coupled

Nature Reviews | Neuroscier

Yuste, R., MacLean, J., Smith, J. et al. The cortex as a central pattern generator. Nat Rev Neurosci 6, 477–483 (2005). https://doi.org/10.1038/nrn1686

Fudan NLP Lab 7

Positional Encoding in Transformers

- Transformer plays a crucial role in the latest AI models (for example, GPT).
- Positional Encoding (PE) is an important technique within the Transformer architecture.

We find that the CPGs can be used as a PE for SNNs!

Fudan NLP Lab 9

• This also inspires us to consider a new role for CPGs in neuroscience—not just as rhythm generators.

CPG-PE

- Current SNN version of the Transformer model:
	- (1) Non-uniqueness of Each Position in Spike-form;
	- (2) Non-spike Output
- Our proposed CPG-PE:
	- (1) Both brain-inspired and hardware-friendly
	- (2) Uniqueness of Each Position in Spike-form

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Relationship between PE and CPGs

The general form of CPGs: $\dot{\mathbf{x}} = \mathbf{F}(\mathbf{x}) + \mathbf{G}(\mathbf{x}, \mathbf{y}), \quad \dot{\mathbf{y}} = \mathbf{H}(\mathbf{y}) + \mathbf{K}(\mathbf{x}, \mathbf{y})$

Consider one of the simplest CPGs with the following assumptions:

- 1. The CPG is a coupled nonlinear oscillator with 2 neurons whose states are represented as $\mathbf{x}(t)$ and $\mathbf{y}(t)$.
- 2. Both neurons are autonomic neurons and will gain membrane voltage with constant speed, i.e., $F(x) = b > 0$, $H(y) = d > 0$.
- 3. Neuron represented by x will inhibits y while y excites x. And the influence is proportional to the other neuron's state. Formally, $\mathbf{G}(\mathbf{x}, \mathbf{y}) = a\mathbf{y}, \mathbf{K}(\mathbf{x}, \mathbf{y}) = -c\mathbf{x}$ where $a > 0, c > 0$. $\dot{\mathbf{x}}(t) = a\mathbf{y}(t) + b, \quad \dot{\mathbf{y}}(t) = -c\mathbf{x}(t) + d$

General Solution:

$$
\mathbf{x}(t) = k_1 \cos(\sqrt{ac} t) + k_2 \sqrt{\frac{a}{c}} \sin(\sqrt{ac} t) + \frac{d}{c} \quad \text{re-parameterize} \quad \mathbf{x}(t') = \sqrt{k_1^2 + \frac{a}{c} k_2^2 \sin(\sqrt{ac} t') + \frac{d}{c}} = A_1 \sin(w_1 t') + b_1,
$$

$$
\mathbf{y}(t) = -k_1 \sqrt{\frac{c}{a}} \sin(\sqrt{ac} t) + k_2 \cos(\sqrt{ac} t) - \frac{b}{a} \quad \mathbf{y}(t') = \sqrt{\frac{c}{a} k_1^2 + k_2^2 \cos(\sqrt{ac} t') - \frac{b}{a}} = A_2 \cos(w_2 t') + b_2
$$

The PE in Transformers is a particular solution of the membrane potential variations in a specific type of CPG.

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Implementations

Consider a system with N pairs of CPG neurons, resulting in a total of 2N cells. Then for $i =$ $1, 2, ..., N$, the equations governing the CPG-PE are as follows:

$$
CPG\text{-}PE^{2i-1}(t) = H\left(\cos\left(\eta \frac{t}{\tau^{\frac{i}{N}}}\right) - v^{\text{thres}}\right),\tag{11}
$$

$$
\text{CPG-PE}^{2i}(t) = H\left(\sin\left(\eta \frac{t}{\tau^{\frac{i}{N}}}\right) - v^{\text{thres}}\right),\tag{12}
$$

where η is a constant to control the period, τ represents the base period, and v^{thres} denotes the membrane potential threshold.

Simply concatenate with SNN neurons

Illustration of applying CPG-PE to SNNs

We also prove that CPG-PE is hardware-friendly because:

- CPG-PE can be integrated into a linear layer;
- CPG-PE can be simply implemented with 2 LIF neurons. Refer to Appendix B and C

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Forecasting Tasks

Experimental results of time-series forecasting on 4 benchmarks with different prediction lengths.

Performance 0.719 -> 0.744 by just adding the CPG-PE (marginal computation cost increase)

Text Classification

Image Classification

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Sweeping CPG properties

Positional Encoding Analysis

An ideal PE method for SNNs:

- (1) Uniqueness of each position;
- (2) Ability to discern positional information;
- (3) Compatibility with neuromorphic hardware;
- (4) Formulation in spike-form.

Repetition rate 12.19%

THANKS!

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Fudan NLP Lab 19