LOGARITHMIC SMOOTHING FOR PESSIMISTIC OFF-POLICY EVALUATION, SELECTION & LEARNING

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[OFF-POLICY CONTEXUTAL BANDITS](#page-1-0)

• OFF-POLICY (OFFLINE) CONTEXTUAL BANDIT. A framework that optimizes decision-making by leveraging logged interactions.

- INTERACTIONS. For any *i ∈* [*n*]
	- Observe context *xⁱ ∼ ν*, where *xⁱ ∈ X*
	- Take action $a_i \sim \pi_0(\cdot | x_i)$, where $a_i \in \mathcal{A}$
	- Suffers a cost *cⁱ ∼ p*(*· | xⁱ , ai*). (*cⁱ ∈* [*−*1*,* 0], negative reward)
- Log $\mathcal{D}_n = \{x_i, a_i, c_i\}_{i \in [n]}$ and use it to improve the system.

PERFORMANCE METRIC. For $\pi \in \Pi$, the risk is defined as:

$$
R(\pi) = \mathbb{E}_{X \sim \nu, a \sim \pi(\cdot | X)} [c(X, a)],
$$

where *c*(*x, a*) = E*^c∼p*(*·|x,a*) [*c*] is the expected cost of *x* and *a*.

Tasks. Given logged data $\mathcal{D}_n = \{x_i, a_i, c_i\}_{i \in [n]}$ by π_0 :

- \cdot Evaluation (OPE). For a new π , estimate $R(\pi) \approx \hat{R}_n(\pi)$.
- \cdot Selection (OPS). Given $\{\pi_1, \cdots, \pi_m\}$, select arg min $_{i \in [m]}$ $R(\pi_i)$.
- Learning (OPL). Find $\pi_* = \arg \min_{\pi \in \Pi} R(\pi)$.

Pessimismis optimal for OPE, OPS & OPL. [[1,](#page-19-0) [2](#page-19-1), [3](#page-19-2)]

- OPE. [[4,](#page-20-0) [5](#page-20-1)] study concentration properties (beyond *MSE*).
- OPS. [[2](#page-19-1), [5\]](#page-20-1) use risk upper bounds (pessimism).
- OPL. [\[1](#page-19-0), [3](#page-19-2), [6](#page-20-2), [7](#page-21-0)] use risk generalization bounds (pessimism).

Instead of $\hat{R}_n(\pi)$, they use a high-probability bound $\hat{U}_n(\pi)$:

$$
R(\pi) \leq \hat{U}_n(\pi) = \hat{R}_n(\pi) + \hat{C}(\pi).
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What we do.

- Derive tight upper bounds for a broad family of estimators.
- Find the estimator (within that family) with the tightest bound.

[NOVEL CONCENTRATION BOUNDS](#page-6-0)

NOVEL CONCENTRATION BOUNDS

We focus on the family of regularized IPS estimators:

$$
\hat{R}_{n}^{h}(\pi) = \frac{1}{n} \sum_{i=1}^{n} h(\pi(a_{i}|x_{i}), \pi_{0}(a_{i}|x_{i}), c_{i}) = \frac{1}{n} \sum_{i=1}^{n} h_{i}, \qquad (1)
$$

with *h* is a transform satisfying (C1): $\frac{p}{q}c \le h(p, q, c) \le 0$.

$$
h(p, q, c) = \frac{p}{q}c, \implies \text{IPS [8],}
$$
\n
$$
h(p, q, c) = \min\left(\frac{p}{q}, M\right)c, M \in \mathbb{R}^+ \implies \text{Clipping [9],}
$$
\n
$$
h(p, q, c) = \left(\frac{p}{q}\right)^{\alpha}c, \alpha \in [0, 1] \implies \text{Exponential Smoothing [6],}
$$
\n
$$
h(p, q, c) = \frac{p}{q + \gamma}c, \gamma \ge 0 \implies \text{Implicit Exploration [5]...}
$$

NOVEL CONCENTRATION BOUNDS

Let $π ∈ Π$, define the empirical $ℓ$ -th moment of $\hat{R}_n^h(π)$ as

$$
\hat{\mathcal{M}}_n^{h,\ell}(\pi) = \frac{1}{n} \sum_{i=1}^n h_i^{\ell}.
$$
 (3)

For $\lambda > 0$, we define the function ψ_{λ} as $\psi_{\lambda}(x) = (1 - \exp(-\lambda x)) / \lambda$.

Let $\pi \in \Pi$, $L \geq 1$, *h* satisfying (C1), $\delta \in (0,1]$ and $\lambda > 0$. Then it holds with probability at least $1 - \delta$ that

$$
R(\pi) \leq \psi_{\lambda}\left(\hat{R}_{n}^{h}(\pi) + \sum_{\ell=2}^{2L} \frac{\lambda^{\ell-1}}{\ell} \hat{\mathcal{M}}_{n}^{h,\ell}(\pi) + \frac{\ln(1/\delta)}{\lambda n}\right), \qquad (4)
$$

- *L* controls the empirical moments, *L ↗* tightens the bound.
- Holds for all *h*, find the *h* that minimizes the bound!

INFINITELY MANY MOMENTS

Setting $L \rightarrow \infty$ and minimizing it w.r.t. *h* yields a bound:

$$
R(\pi) \leq \psi_{\lambda} \left(\hat{R}_{n}^{\lambda}(\pi) + \frac{\ln(1/\delta)}{\lambda n} \right). \tag{5}
$$

for a novel estimator, that we call Logarithmic Smoothing (LS):

$$
\hat{R}_{n}^{\lambda}(\pi) = -\frac{1}{n} \sum_{i=1}^{n} \frac{1}{\lambda} \log \left(1 - \lambda w_{\pi}(x_{i}, a_{i}) c_{i}\right), \qquad (6)
$$

with $w_{\pi}(x, a) = \pi(a|x)/\pi_0(a|x)$.

([5](#page-9-0)) is provably tighter than:

- \cdot Our bound with $l = 1$.
- cIPS (empirical Bernstein).
- \cdot IX bound [[5](#page-20-1)].

[LOGARITHMIC SMOOTHING](#page-10-0)

LOGARITHMIC SMOOTHING

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\forall \lambda \geq 0, \quad \hat{R}_n^{\lambda}(\pi) = -\frac{1}{n} \sum_{i=1}^n \frac{1}{\lambda} \log (1 - \lambda w_{\pi}(x_i, a_i) c_i) \ . \tag{7}
$$

- $\cdot \lambda \rightarrow 0$ recovers IPS.
- Smoothly corrects the IWs.
- Good bias-variance tradeoff.
- Unbounded, with finite variance!
- Sub-Gaussian concentration:

LOGARITHMIC SMOOTHING

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- Sub-Gaussian concentration:

For $\lambda^* = \mathcal{O}(1/\sqrt{n})$, we have with probability at least 1 *− δ*:

 $|R(\pi) - \hat{R}_n^{\lambda_*}(\pi)| \leq \sqrt{2\sigma^2 \ln(2/\delta)},$ where $\sigma^2 = 2\mathbb{E}\left[w_\pi(x, a)^2 c^2\right] / n$.

With $\lambda = \mathcal{O}(1/\sqrt{n})$, and by minimizing $\hat{R}_n^{\lambda}(\pi)$, we reach π_* in:

$$
\cdot \ \mathcal{O}\left(\sqrt{\mathbb{E}\left[\left(\frac{\pi_*(a|x)}{\pi_0(a|x)}c\right)^2\right]/n}\right) \text{ for OPS.}
$$
\n
$$
\cdot \ \mathcal{O}\left(\sqrt{\left(\mathbb{E}\left[\frac{\pi_*(a|x)c^2}{\pi_0(a|x)^2}\right]+ KL(Q^*||P)\right)/n}\right) \text{ in PAC-Bayes OPL.}
$$

- *→* We identify the best policy with enough *n*.
- $→$ Faster identification when π_0 is close to π_* .
- *→* Simple, no additional terms (e.g., Emp. variance in SVP [\[1](#page-19-0)])
- *→* Provably efficient for OPS and OPL.

[EXPERIMENTS](#page-14-0)

EXPERIMENTS

Figure 1: Results for OPE and OPS experiments.

Table 1: OPL Improvement of Guaranteed risk *U* and *R* of the bounds.

[CONCLUSION](#page-16-0)

- Work of theoretical nature with practical implications.
- Principled approach led us to the design of a new estimator.
- A lot more insight can be found in the paper.
- Work of theoretical nature with practical implications.
- Principled approach led us to the design of a new estimator.
- A lot more insight can be found in the paper.
- ... Or let's discuss the work at NeuRIPS, or even by e-mail!

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