

TopP&R: Robust Support Estimation Approach for Evaluating Fidelity and Diversity in Generative Models



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Real image distribution

Unknown!





Fake image distribution



Comparison



 $f_{\theta}(\cdot)$: Pretrained embedding network

- C : Extracted real image features
- Extracted fake image features



 $f_{\theta}(\cdot)$: Pretrained embedding network

- C : Extracted real image features
- Extracted fake image features



(1) Ideal estimation of distribution



: real image features
: fake image features
: fake noisy features

(1) Ideal estimation of distribution



(2) Non-ideal estimation of distribution



Correctly measured scores

Fidelity = Q(supp(P)) = 0.16

Diversity = P(supp(Q)) = 0.16

: real image features
: fake image features



(2) Non-ideal estimation of distribution

Incorrectly measured scores

Fidelity = Q(supp(P)) = 0.75Diversity = Q(supp(P)) = 0.5

: real image features
: fake image features





(c) Given $\widehat{supp}(P)$ for real features \mathcal{X} and $\widehat{supp}(Q)$ for generated features \mathcal{Y} ,



$$TopP_{\mathcal{X}}(\mathcal{Y}) \coloneqq \frac{\sum_{j=1}^{m} \mathbb{1}(Y_j \in \widehat{supp}(P) \cap \widehat{supp}(Q))}{\sum_{j=1}^{m} \mathbb{1}(Y_j \in \widehat{supp}(Q))}$$
$$TopR_{\mathcal{Y}}(\mathcal{X}) \coloneqq \frac{\sum_{i=1}^{n} \mathbb{1}(X_i \in \widehat{supp}(Q) \cap \widehat{supp}(P))}{\sum_{i=1}^{n} \mathbb{1}(X_i \in \widehat{supp}(P))}$$







Exclude noisy features under statistical confidence level we set







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TopP \xrightarrow[n \to \infty]{} precision
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 $TopR \xrightarrow[n \to \infty]{} recall$

See our proposition 4.1 and theorem 4.2

Selecting a threshold that effectively removes noisy samples

(1) Reference

- : significant feature
- 😑 : noisy features
 - : support of estimated distribution
 - : ground truth support of distribution



Selecting a threshold that effectively removes noisy samples

(2) When $\delta = 0.01$ (over-estimated case)

- : significant feature
- 😑 : noisy features
 - : support of estimated distribution
 - : ground truth support of distribution



Selecting a threshold that effectively removes noisy samples

(3) When $\delta = 0.3$ (under-estimated case)

- : significant feature
- 😑 : noisy features
 - : support of estimated distribution
 - : ground truth support of distribution



Selecting a threshold that effectively removes noisy samples

(4) $\delta \in [0, 1]$

- : significant feature
- 😑 : noisy features
 - : support of estimated distribution
 - : ground truth support of distribution

$\delta \in [0,1]$ What is the optimal threshold?



Tracking when homological feature appear and disappear



 b_4 b_3 b_2 b_1 d_2 d_1 (10)

Tracking when homological feature appear and disappear

I death of 0-dimensional homology happens

■ ■ : birth of 0-dimensional homology happens

: 0-dim homological feature or connected component





Tracking when homological feature appear and disappear



- • : death of 0-dimensional homology happens
- ■ : birth of 0-dimensional homology happens
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Tracking when homological feature appear and disappear



- • : death of 0-dimensional homology happens
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 \bigcap







Experiments & Results – perturbation experiment



Experiments & Results – ranking experiment

Metric's consistency "with FID and KID scores" & "with different embeddings"



Thank you

Project Page



Quick Start!

pip install top-pr



Use our method by only pip command!