

GRAND-SLAMIN' Interpretable Additive Modeling with Structural Constraints

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Generalized Additive Models (GAMs) with Interactions

• GAMs with Interactions [Hastie (1987)] consider a model of the form:

$$g(\mathbb{E}[y]) = \sum_{j \in [p]} f_j(x_j) + \sum_{(j,k) \in \mathcal{I}} f_{j,k}(x_{j,k})$$

- Class of flexible models
 - Highly Interpretable
 - Provide good performance comparable to black-box methods



Challenges for GAMs with Interactions

• GAMs with Interactions consider a model of the form:

$$g(\mathbb{E}[y]) = \sum_{j \in [p]} f_j(x_j) + \sum_{(j,k) \in \mathcal{I}} f_{j,k}(x_{j,k})$$

- Challenges:
 - \circ Learning all pairwise interaction effects (order ~ p²) computationally challenging.
 - End-to-end Component selection (few components $\{f_j\}$ and $\{f_{j,k}\}$ to be nonzero) is a hard combinatorial optimization problem.
 - Benefit: Component selection aids interpretability.
 - Structural constraints on the interaction effects, e.g., hierarchy, make optimization more complex
 - Benefit: Improve interpretability, practical sparsity and reduce variance.

Key literature on GAMs with Interactions

Existing methods have the following limitations:

- Not flexible (require customized algorithms to adapt)
 - EBM [Lou et al. (2013), Nori et al. (2019)] , ELAAN [Ibrahim et al. (2021)]
- Do not support component selection in an end-to-end fashion
 - GAMI-Net [Yang et al. (2020)], SIAN [Enouen et al. (2022)]
- Do not support structural constraints
 - EBM [Lou et al. (2013), Nori et al. (2019)], NODE-GAM [Chang et al. (2022)]
- Slow when fitting interactions
 - EBM [Lou et al. (2013), Nori et al. (2019)], SIAN [Enouen et al. (2022)], GAMI-Net [Yang et al. (2020)]

Proposal

- 1. **GRAND-SLAMIN**: a general optimization framework, which
 - a. Works in an **end-to-end** fashion for any differentiable loss function.
 - b. Supports **component selection** i.e., selects a sparse subset of main and interaction effects.
 - c. Supports **structural constraints** e.g., weak hierarchy and strong hierarchy.
 - d. Has **statistical guarantees** we provide novel non-asymptotic error bounds.
 - e. Is GPU-compatible **sparse back-propagation** for efficient training.

Goal

$$f = \sum_{j \in [p]} f_j(x_j) + \sum_{(j,k) \in \mathcal{I}} f_{j,k}(x_{j,k})$$

Component Selection:

$$\mathrm{nnz}(f_j,f_{j,k}) \leq K$$

Structural Constraints:

Weak Hierarchy: $f_{j,k} \neq 0 \implies f_j \neq 0$ OR $f_k \neq 0$ Strong Hierarchy: $f_{j,k} \neq 0 \implies f_j \neq 0$ AND $f_k \neq 0$

Optimization Formulation

$$\min_{\{f_j\},\,\{f_{j,k}\},\{z_j\}\in\{0,1\}^p,\{z_{j,k}\}\in\{0,1\}^{|\mathcal{I}|}} \hat{\mathbb{E}}[l(y,f)] + \lambda \left(\sum_{j\in[p]} z_j + lpha \sum_{(j,k)\in\mathcal{I}} z_{j,k}
ight) \ f = \sum_{j\in[p]} f_j(x_j) z_j + \sum_{(j,k)\in\mathcal{I}} f_{j,k}(x_{j,k}) q(z_j,z_k,z_{j,k})$$

No structural constraint:

Weak Hierarchy:

Strong Hierarchy:

$$egin{aligned} q(z_j, z_j, z_{j,k}) &= z_{j,k} \ q(z_j, z_j, z_{j,k}) &= (z_j + z_k - z_j z_k) z_{j,k} \ q(z_j, z_j, z_{j,k}) &= z_j z_k z_{j,k} \end{aligned}$$

Smooth Reformulation

$$f=\sum_{j\in [p]}f_j(x_j)z_j+\sum_{(j,k)\in \mathcal{I}}f_{j,k}(x_{j,k})q(z_j,z_k,z_{j,k})$$

Parameterize as follows:

• Components, i.e., f_j and $f_{j,k}$ with Soft trees [Jordan and Jacob (1993)]



• Smooth binary variables, i.e., z_j , z_k and $z_{j,k}$ with Smooth-Step function [Hazimeh et al. (2020)]



Allows optimization with first-order methods e.g., SGD!

Statistical Theory Takeaways:

- First to discuss statistical properties of GAMs with interactions with **tree-shape functions**
- Under a well-specified model, non-asymptotic prediction error **rates of** $n^{-2/3}$ and $n^{-1/(2+a)} \approx n^{-0.42}$ are achievable for main effects and interaction models, respectively.
 - Prediction error (resulting from the noise in observations) converges to zero as we increase the total number of samples, *n*.
- Asymptotically, when $n \rightarrow \infty$ and other parameters in the problem stay constant, an **error rate of** $n^{-0.5}$ is achievable for the interactions model

Results

Comparison with Sparse GAMs with interactions

- Competitive with EB²M and NODE-GA²M
- Our key advantages:
 - Hierarchical interactions (not supported by NODE-GA²M and EB²M).
 - faster training times
 - Improved variable selection.

Dataset	EB ² M	NODE-GA ² M	GRAND-SLAMIN (ours)
Magic	93.12 ± 0.001	94.27 ± 0.13	93.86 ± 0.3
Adult	91.41 ± 0.0004	91.75 ± 0.14	91.54 ± 0.14
Churn	91.97 ± 0.005	89.62 ± 5.61	92.40 ± 0.41 (SH)
Satimage	97.65 ± 0.0007	98.7 ± 0.07	98.81 ± 0.04
Texture	99.81 ± 0.0004	100.0 ± 0.0	100.0 ± 0.0
MiniBooNE	97.86 ± 0.0001	98.44 ± 0.02	97.77 ± 0.05 (WH)
Covertype	90.08 ± 0.0003	95.39 ± 0.12	98.11 ± 0.08
Spambase	98.84 ± 0.01	98.78 ± 0.06	98.55 ± 0.07 (SH)
News	73.03 ± 0.002	73.53 ± 0.06	73.24 ± 0.04 (SH)
Optdigits	99.79 ± 0.0003	99.93 ± 0.02	99.98 ± 0.0
Bankruptcy	93.85 ± 0.01	92.02 ± 1.03	92.51 ± 0.54 (WH)
Madelon	88.04 ± 0.02	60.07 ± 0.82	89.25 ± 1.03 (WH)
Activity	74.96 ± 8.77	99.86 ± 0.04	99.24 ± 1.45
Multiple	99.96 ± 0.0002	99.94 ± 0.02	99.95 ± 0.02

Comparison with Sparse Hierarchical interactions

- Our models outperform GAMI-Net and SIAN in many datasets.
- Our key advantages:
 - Our Hierarchical interactions is end-to-end.
 - Faster training times
 - Improved variable selection.

	Weak I	Hierarchy	Strong Hierarchy		
Dataset	GAMI-Net	GRAND-SLAMIN	SIAN	GRAND-SLAMIN	
Magic	91.72 ± 0.05	93.16 ± 0.55	93.02 ± 0.06	93.37 ± 0.16	
Adult	91.01 ± 0.04	91.34 ± 0.32	90.67 ± 0.05	91.46 ± 0.15	
Churn	90.05 ± 0.77	92.28 ± 0.75	92.98 ± 0.20	92.40 ± 0.41	
Spambase	98.67 ± 0.04	98.45 ± 0.15	98.28 ± 0.04	98.55 ± 0.07	
MiniBooNE	96.11 ± 0.41	97.77 ± 0.05	95.9	97.62 ± 0.30	
News	72.54 ± 0.05	73.15 ± 0.08	72.28	73.24 ± 0.04	
Bankruptcy	92.46 ± 0.12	92.51 ± 0.54	90.71	90.45 ± 1.87	
Madelon	88.14 ± 0.94	89.25 ± 1.03	83.18	86.23 ± 1.89	

Variable Selection

GRAND-SLAMIN with structural constraints, in particular SH, can reduce the number of features selected.

	EB ² M	NODE-GA ² M	GAMI-Net	SIAN	GRAND-SLAMIN (ours)		
Dataset	None	None	WH	SH	None	WH	SH
Magic	10 ± 0	10 ± 0	10 ± 0	10 ± 0	10 ± 0	9 ± 1	7 ± 0
Adult	14 ± 0	14 ± 0	14 ± 1	14 ± 0	13 ± 1	11 ± 1	11 ± 1
Churn	19 ± 0	19 ± 0	18 ± 2	19 ± 0	19 ± 0	11 ± 1	12 ± 2
Satimage	36 ± 0	36 ± 0	-	-	36 ± 0	36 ± 0	22 ± 2
Texture	40 ± 0	40 ± 0	-	-	40 ± 0	37 ± 2	17 ± 2
MiniBooNE	50 ± 0	50 ± 0	16 ± 12	34	50 ± 0	50 ± 0	28 ± 3
Covertype	54 ± 0	54 ± 0	-	-	34 ± 1	54 ± 1	54 ± 0
Spambase	57 ± 0	57 ± 0	52 ± 2	55 ± 1	57 ± 0	56 ± 3	54 ± 2
Bankruptcy	95 ± 0	95 ± 0	60 ± 15	69	95 ± 0	60 ± 26	7 ± 16
Madelon	500 ± 0	500 ± 0	61 ± 56	490	26 ± 19	19 ± 15	24 ± 9
Activity	533 ± 0	346 ± 6	-	-	182 ± 15	440 ± 22	159 ± 21
Multiple	649 ± 0	649 ± 0	-	-	648 ± 1	629 ± 9	649 ± 0

Efficient Training with Sparse Backpropagation



(a) Number of selected effects at each epoch.

(b) Training time (seconds) for each epoch.

Sparse backpropagation up to 10× faster than standard backpropagation - no loss in accuracy

• Components with zero z's are removed from computational graph during training

Variance reduction with structural constraints

Estimation of main effects (in the presence of interaction effects) is more stable with structural constraints

• Smaller error bars across seeds/runs!



Check out our paper!

Paper: <u>https://openreview.net/pdf?id=F5DYsAc7Rt</u> GRAND-SLAMIN Code: <u>https://github.com/mazumder-lab/grandslamin</u> Email: <u>shibal@mit.edu</u>

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