

Domain Adaptive Imitation Learning from Visual Observation

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Imitation Learning (IL) with Domain Shift



- Learns behaviors by imitating expert demonstrations without access to true rewards
- Domain shift in IL: Expert domain (source domain) \neq Agent domain (target domain)
- We focus on the case where the demonstrations are provided as visual observations.

A Problem in Imitation Learning with Domain Shift



- Due to domain shift, the learner cannot directly mimic the expert demonstration.
- We proposed D3IL (Dual feature extraction and Dual cycle-consistency for Domain adaptive IL with visual observation) for enhanced feature extraction and policy update.

Methodology

• Our feature extraction model is built based on the ideas of dual feature extraction, image generation, and dual cycle consistency.



Dual Feature Extraction

- The domain feature contains only domain information of the input.
- The behavior feature contains only task-relevant information of the input.



Image Generation

• The generators produce images that contain domain and behavioral characteristics.



Dual Cycle-Consistency

- Input images = Images after applying feature extraction and image generation twice
- Features via first-stage feature extraction = Features via second-stage feature extraction



Reward Generation and Learner Policy Update

- Adversarial learning between reward-generating discriminator D_{rew} and policy π_{θ}
- The imitation reward for an observation o_t is defined by

 $\hat{r}(o_t) = \log D_{rew}(BE_T(o_t)) - \log(1 - D_{rew}(BE_T(o_t)))$



Experiments

- We evaluated D3IL on imitation learning tasks with various types of domain shifts.
- D3IL is also effective when directly obtaining a target domain expert is challenging.



Thank You!

- If you have any questions, feel free to ask during the poster session.
- Poster Session 3 (Wed 13 Dec 10:45 a.m. CST 12:45 p.m. CST)
- Poster Location: Great Hall & Hall B1+B2 #1406
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