## The Probability Flow ODE is Provably Fast

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## Diffusion models

## Problem (Generative Modeling)

Learn a probability distribution from samples, and generate additional samples.
Diffusion models are a modern paradigm for generative modeling with state-of-the-art performance on image, audio, video generation, with applications to inverse problems, molecular modeling, etc.
Picture from Y. Song, Sohl-Dickstein, Kingma, et al. 2020.


What theoretical guarantees can we obtain for diffusion models? Show convergence

- given $L^{2}$-accurate score estimate,
- for general data distributions.

Expensive to evaluate; care about dependence on dimension $d$.

## SDE vs. ODE formulation

## Denoising Diffusion <br> Probabilistic Modeling (SDE)

## Probability Flow (ODE)

$$
\begin{aligned}
& d x_{t}^{\vec{~}}=-x_{t}^{\vec{t}} d t+\sqrt{2} d W_{t} \\
& d x_{t}^{\leftarrow}=x_{t}^{\leftarrow} d t+2 \underbrace{\nabla \log p_{T-t}\left(x_{t}^{\leftarrow}\right)}_{\approx s_{T-t}\left(x_{t}^{*}\right)} d t+\sqrt{2} d W_{t} .
\end{aligned}
$$

- Convergence guarantees with $O(d)$ steps. S. Chen, Chewi, Li, et al. 2023; H. Chen, Lee, and Lu 2023; Benton, De Bortoli, Doucet, et al. 2023
- Lower bound $\Omega(d)$ for trajectory-wise analysis, even for critically damped Langevin diffusion (S. Chen, Chewi, Li, et al. 2023).

$$
\begin{aligned}
& d x_{t}^{\overrightarrow{2}}=-x_{t}^{\overrightarrow{ }} d t-\nabla \log p_{t}\left(x_{t}^{\leftarrow}\right) d t \\
& d x_{t}^{\leftarrow}=x_{t}^{\leftarrow} d t+\underbrace{\nabla \log p_{T-t}\left(x_{t}^{\leftarrow}\right)}_{\approx s_{T-t}\left(x_{t}^{\leftarrow}\right)} d t
\end{aligned}
$$

- Much faster ( $10 x-50 x$ ) in practice (J. Song, Meng, and Ermon 2020)...
- ...but can sometimes be less stable.
- This work: $O(\sqrt{d})$ steps using corrector steps.


## The trouble with SDE's

## DDPM:

$$
\begin{aligned}
& d x_{t}^{\leftarrow}=\left[x_{t}^{\leftarrow}+2 \nabla \log p_{T-t}\left(x_{t}^{\leftarrow}\right)\right] d t+\sqrt{2} d w_{t} \\
& x_{t+h}^{\leftarrow} \approx x_{t}^{\leftarrow}+h\left[x_{t}^{\leftarrow}+2 \nabla \log p_{T-t}\left(x_{t}^{\leftarrow}\right)\right]+\sqrt{2 h} \xi, \xi \sim N\left(0, I_{d}\right)
\end{aligned}
$$

Discretization error from...

- Drift term (order 1 ): $\quad O(L h \sqrt{d}) \rightarrow$ can take $h=O\left(\frac{1}{L \sqrt{d}}\right)$.
- Diffusion term (order $1 / 2$ ): $O(L \sqrt{h d}) \rightarrow$ need to take $h=O\left(\frac{1}{L^{2} d}\right)$.

Trajectories of Brownian motion are not smooth!
Probability flow ODE:

$$
d x_{t}^{\leftarrow}=\left[x_{t}^{\leftarrow}+\nabla \log p_{T-t}\left(x_{t}^{\overleftarrow{ }}\right)\right] d t
$$

## Assumptions

## Assumption

(1) $p_{0}$ has second moment $\mathbb{E}_{p_{0}}\|x\|^{2}=\mathfrak{m}_{2}^{2}$.
(2) For each $t_{k}$, the score estimate $s_{t_{k}}$ has error

$$
\left\|\nabla \log p_{t_{k}}-s_{t_{k}}\right\|_{L^{2}\left(p_{t_{k}}\right)}^{2} \leq \varepsilon_{\mathrm{sc}}^{2} .
$$

(3) $\nabla \log p_{t}$ is L-Lipschitz for every $t$.
(9) The score estimate $s_{t_{k}}$ is $L$-Lipschitz for every $t_{k}$.

## DPUM (Diffusion Predictor + Underdamped Modeling)

## Theorem (DPUM, S. Chen, Chewi, Lee, et al. 2023)

Suppose that the Assumptions hold. If the score error satisfies $\varepsilon_{\mathrm{sc}} \leq \widetilde{O}\left(\frac{\varepsilon}{\sqrt{L}}\right)$, then the output of DPUM gives TV error $\varepsilon$ with number of steps $N=\widetilde{\Theta}\left(\frac{L^{2} d^{1 / 2}}{\varepsilon}\right)$.

## Algorithm (simplified)

Draw $\widehat{x}_{0} \sim N\left(0, I_{d}\right)$. For $n=0, \ldots, L T-1$ :

- Predictor: Starting from $\widehat{x}_{n / L}$, run the discretized probability flow ODE from time $\frac{n}{L}$ to $\frac{n+1}{L}$ with step size $h_{\text {pred }}$ to obtain $\widehat{x}_{\frac{n+1}{L}}^{\prime}$.

$$
x_{t+h}^{\overleftarrow{ }}=e^{h} x_{t}^{\leftarrow}+\left(e^{h}-1\right) s_{T-t}\left(x_{t}^{\leftarrow}\right)
$$

- Corrector: Starting from $\widehat{x}_{\frac{n+1}{L}}^{\prime}$, run underdamped LMC for time $\frac{1}{\sqrt{L}}$ with step size $h_{\text {corr }}$ to obtain $\widehat{x}_{\frac{n+1}{L}}$.


## Challenges

Problem: Cannot use Girsanov's Theorem with ODE's.
Solution: Use Wasserstein analysis with coupling.

- Score perturbation lemma: Bound the time derivative of score.

$$
\mathbb{E}\left[\left\|\partial_{t} \nabla \log q_{t}\left(y_{t}\right)\right\|^{2}\right] \lesssim L^{2} d\left(L+\frac{1}{t}\right)
$$

- By Grönwall, get error bounds within $\frac{1}{L}$ time.


## Challenges

Problem: Cannot use Girsanov's Theorem with ODE's.
Solution: Use Wasserstein analysis with coupling.
Problem: Distance grows exponentially with rate $L$; can only run for time $O(1 / L)$.
Solution: Convert Wasserstein to TV error with a corrector step (short-time regularization). Using data processing inequality for TV distance, we can restart coupling.

- Predictor (P): Simulate the reverse SDE/ODE to track a time-varying distribution.
- Corrector (C): Run MCMC (e.g., Langevin Monte Carlo) to converge towards a stationary distribution.
- Predictor-corrector (PC): Intersperse P \& C steps.



## Challenges

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Problem: Overdamped Langevin needs $O(d)$ steps.
Solution: Use underdamped Langevin (Langevin "with acceleration"), which needs $O(\sqrt{d})$ steps.

$$
\begin{aligned}
& d x_{t}=v_{t} d t \\
& d v_{t}=-\nabla f\left(x_{t}\right) d t-\gamma v_{t} d t+\sqrt{2 \gamma} d B_{t}
\end{aligned}
$$

## Conclusion

- Using an ODE instead of SDE, in conjunction with underdamped corrector, reduces dimension dependence from $O(d)$ to $O(\sqrt{d})$.
- Questions:
- Can we relax smoothness assumptions?
- Is the corrector necessary?
- Is the higher error necessary?
- Other ways to improve parameter dependence and stability?


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