## The Probability Flow ODE is Provably Fast

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### Problem (Generative Modeling)

Learn a probability distribution from samples, and generate additional samples.

**Diffusion models** are a modern paradigm for generative modeling with state-of-the-art performance on image, audio, video generation, with applications to inverse problems, molecular modeling, etc.

Picture from Y. Song, Sohl-Dickstein, Kingma, et al. 2020.

Forward SDE (data  $\rightarrow$  noise)  $\mathbf{x}(0)$   $d\mathbf{x} = \mathbf{f}(\mathbf{x}, t)dt + g(t)d\mathbf{w}$   $\mathbf{x}(T)$  $\mathbf{x}(0)$   $\mathbf{x}($ 

What theoretical guarantees can we obtain for diffusion models? Show convergence

- given  $L^2$ -accurate score estimate,
- for general data distributions.

Expensive to evaluate; care about dependence on dimension d.

# SDE vs. ODE formulation

Denoising Diffusion Probabilistic Modeling (SDE)

$$dx_t^{\rightarrow} = -x_t^{\rightarrow} dt + \sqrt{2} dW_t$$
  
$$dx_t^{\leftarrow} = x_t^{\leftarrow} dt + 2 \underbrace{\nabla \log p_{T-t}(x_t^{\leftarrow})}_{\approx s_{T-t}(x_t^{\leftarrow})} dt + \sqrt{2} dW_t.$$

- Convergence guarantees with O(d) steps.
   S. Chen, Chewi, Li, et al. 2023; H. Chen, Lee, and Lu
   2023; Benton, De Bortoli, Doucet, et al. 2023
- Lower bound Ω(d) for trajectory-wise analysis, even for critically damped Langevin diffusion (S. Chen, Chewi, Li, et al. 2023).

## Probability Flow (ODE)

$$dx_t^{\rightarrow} = -x_t^{\rightarrow} dt - \nabla \log p_t(x_t^{\leftarrow}) dt$$
$$dx_t^{\leftarrow} = x_t^{\leftarrow} dt + \underbrace{\nabla \log p_{T-t}(x_t^{\leftarrow})}_{\approx s_{T-t}(x_t^{\leftarrow})} dt.$$

- Much faster (10x-50x) in practice (J. Song, Meng, and Ermon 2020)...
- ...but can sometimes be less stable.
- This work:  $O(\sqrt{d})$  steps using corrector steps.

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#### DDPM:

$$dx_t^{\leftarrow} = [x_t^{\leftarrow} + 2\nabla \log p_{T-t}(x_t^{\leftarrow})] dt + \sqrt{2} dw_t$$
$$x_{t+h}^{\leftarrow} \approx x_t^{\leftarrow} + h [x_t^{\leftarrow} + 2\nabla \log p_{T-t}(x_t^{\leftarrow})] + \sqrt{2h}\xi, \ \xi \sim N(0, I_d).$$

Discretization error from...

- Drift term (order 1):  $O(Lh\sqrt{d}) \rightarrow \text{can take } h = O\left(\frac{1}{L\sqrt{d}}\right).$
- Diffusion term (order 1/2):  $O(L\sqrt{hd}) \rightarrow$  need to take  $h = O(\frac{1}{L^2d})$ . Trajectories of Brownian motion are not smooth!

Probability flow ODE:

$$dx_t^{\leftarrow} = [x_t^{\leftarrow} + \nabla \log p_{T-t}(x_t^{\leftarrow})] dt.$$

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#### Assumption

- $p_0$  has second moment  $\mathbb{E}_{p_0} \|x\|^2 = \mathfrak{m}_2^2$ .
- **2** For each  $t_k$ , the score estimate  $s_{t_k}$  has error

$$\|
abla \log p_{t_k} - s_{t_k}\|^2_{L^2(p_{t_k})} \leq arepsilon_{ ext{sc}}^2.$$

- **③**  $\nabla \log p_t$  is *L*-Lipschitz for every *t*.
- The score estimate  $s_{t_k}$  is *L*-Lipschitz for every  $t_k$ .

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# DPUM (Diffusion Predictor + Underdamped Modeling)

#### Theorem (DPUM, S. Chen, Chewi, Lee, et al. 2023)

Suppose that the Assumptions hold. If the score error satisfies  $\varepsilon_{sc} \leq \widetilde{O}(\frac{\varepsilon}{\sqrt{L}})$ , then the output of DPUM gives TV error  $\varepsilon$  with number of steps  $N = \widetilde{\Theta}\left(\frac{L^2 d^{1/2}}{\varepsilon}\right)$ .

### Algorithm (simplified)

Draw  $\widehat{x}_0 \sim N(0, I_d)$ . For  $n = 0, \dots, LT - 1$ :

• **Predictor:** Starting from  $\hat{x}_{n/L}$ , run the discretized probability flow ODE from time  $\frac{n}{L}$  to  $\frac{n+1}{L}$  with step size  $h_{\text{pred}}$  to obtain  $\hat{x}'_{n+1}$ .

$$x_{t+h}^{\leftarrow} = e^h x_t^{\leftarrow} + (e^h - 1) s_{\mathcal{T}-t}(x_t^{\leftarrow}).$$

• **Corrector:** Starting from  $\hat{x}'_{\frac{n+1}{L}}$ , run underdamped LMC for time  $\frac{1}{\sqrt{L}}$  with step size  $h_{\text{corr}}$  to obtain  $\hat{x}_{\frac{n+1}{L}}$ .

## Challenges

Problem: Cannot use Girsanov's Theorem with ODE's. Solution: Use **Wasserstein analysis** with coupling.

• Score perturbation lemma: Bound the time derivative of score.

$$\mathbb{E}[\|\partial_t 
abla \log q_t^{
ightarrow}(y_t)\|^2] \lesssim L^2 d\left(L+rac{1}{t}
ight).$$

• By Grönwall, get error bounds within  $\frac{1}{L}$  time.

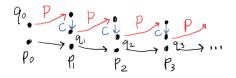
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Problem: Cannot use Girsanov's Theorem with ODE's. Solution: Use **Wasserstein analysis** with coupling.

Problem: Distance grows exponentially with rate L; can only run for time O(1/L). Solution: Convert Wasserstein to TV error with a **corrector** step (short-time regularization). Using data processing inequality for TV distance, we can restart coupling.

- **Predictor (P):** Simulate the reverse SDE/ODE to track a *time-varying* distribution.
- **Corrector (C):** Run MCMC (e.g., Langevin Monte Carlo) to converge towards a *stationary* distribution.
- Predictor-corrector (PC): Intersperse P & C steps.



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Problem: Overdamped Langevin needs O(d) steps. Solution: Use **underdamped Langevin** (Langevin "with acceleration"), which needs  $O(\sqrt{d})$  steps.

$$dx_t = v_t dt$$
  
 $dv_t = -
abla f(x_t) dt - \gamma v_t dt + \sqrt{2\gamma} dB_t$ 

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• Using an ODE instead of SDE, in conjunction with underdamped corrector, reduces dimension dependence from O(d) to  $O(\sqrt{d})$ .

• Questions:

- Can we relax smoothness assumptions?
- Is the corrector necessary?
- Is the higher error necessary?
- Other ways to improve parameter dependence and stability?

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