Monte-Carlo Tree Search with Boltzmann Exploration

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Monte-Carlo Tree Search





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UCB Applied to Trees (UCT)



Selection

Q(s,a)- Q-Value Estimate

N(s), N(s, a)

UCB Applied to Trees (UCT)

Action selection:

$$\pi_{\text{UCT}}(s) = \operatorname{argmax}_{a} \left[Q(s, a) + c \frac{\log(N(s))}{N(s, a)} \right]$$





Q(s,a)- Q-Value Estimate

N(s), N(s, a)

UCB Applied to Trees (UCT)

Action selection:

$$\pi_{\text{UCT}}(s) = \operatorname{argmax}_{a} \left[Q(s, a) + c \frac{\log(N(s))}{N(s, a)} \right]$$

Recommendation policy:

 $\psi_{\rm UCT}(s) = \operatorname{argmax}_a Q(s, a)$





Q(s,a)- Q-Value Estimate

N(s), N(s, a)- Visit Counts

Boltzmann Tree Search (BTS)

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Action Selection:

$$\pi_{\mathrm{BTS}}(a|s) \propto \exp\left(\frac{Q(s,a)}{\alpha}\right)$$

Selection



Q(s,a)- Q-Value Estimate

N(s), N(s, a)

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Exploration in Action Selection







Q(s,a)- Q-Value Estimate

N(s), N(s, a)

Exploration in Action Selection



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$$\pi_{\text{UCT}}(s) = \operatorname{argmax}_{a}\left[Q(s,a) + c\frac{\log(N(s))}{N(s,a)}\right]$$







- Visit Counts

Exploration in Action Selection



$$\pi_{\text{BTS}}(a|s) \propto \exp\left(\frac{Q(s,a)}{\alpha}\right)$$
$$\pi_{\text{UCT}}(s) = \operatorname{argmax}_{a}\left[Q(s,a) + c\frac{\log(N(s))}{N(s,a)}\right]$$









Entropy in Tree Search







Q(s,a) - Q-Value Estimate

N(s), N(s, a)- Visit Counts



Decaying ENtropy Tree Search (DENTS)





Q(s,a)- Q-Value Estimate

N(s), N(s, a)- Visit Counts

Monte-Carlo Tree Search with Boltzmann Exploration



Decaying ENtropy Tree Search (DENTS)

Action Selection:

$$\pi_{\text{DENTS}}(a|s) \propto \exp\left(\frac{Q(s,a) + \beta(N(s))\mathcal{H}_Q(s,a)}{\alpha}\right)$$



Q(s,a)- Q-Value Estimate

N(s), N(s, a)

Decaying ENtropy Tree Search (DENTS)

Action Selection:

 $\pi_{\text{DENTS}}(a|s) \propto \exp\left(\frac{Q(s,a) + \beta(N(s))\mathcal{H}_Q(s,a)}{\alpha}\right)$

Recommendation Policy:

 $\psi_{\text{DENTS}}(s) = \operatorname{argmax}_a Q(s, a)$

Q(s, a)- Q-Value Estimate

N(s), N(s, a)- Visit Counts



Selection



Alias Method

Distribution with A actions:

- Build alias table with O(A) cost
- Sample actions in O(1) time





Q(s,a)- Q-Value Estimate

N(s), N(s, a)

Alias Method

Distribution with A actions:

- Build alias table with O(A) cost
- Sample actions in O(1) time

Faster action selection using stochastic policies:

- 1. If N(s) is a multiple of A: Build new alias table
- 2. Sample action using alias table





Q(s, a)- Q-Value Estimate



Final Comments

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Discussed:

- How Boltzmann policies explore more during action selection
- Using entropy as an exploration bonus to motivate DENTS
- Faster action sampling using the Alias method

Final Comments



Discussed:

- How Boltzmann policies explore more during action selection
- Using entropy as an exploration bonus to motivate DENTS
- Faster action sampling using the Alias method

See paper for:

- Convergence results for BTS and DENTS
- Discussing setting parameters in BTS, DENTS and related algorithms
- Empirically demonstrating these benefits in toy environments and Go