

LUDWIG-MAXIMILIANS-UNIVERSITÄT MÜNCHEN

FACULTY FOR MATHEMATICS, INFORMATICS, AND STATISTICS DEPARTMENT OF MATHEMATICS

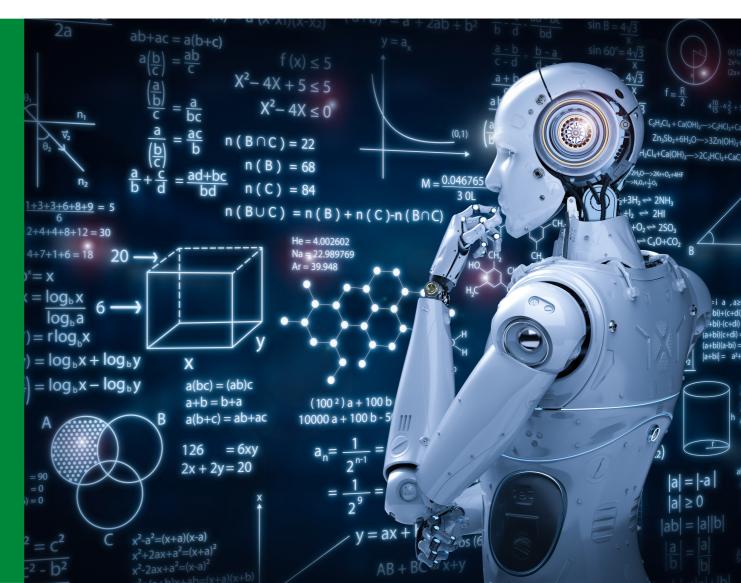
**BAVARIAN AI CHAIR "MATHEMATICAL FOUNDATIONS OF ARTIFICIAL INTELLIGENCE"** 



# A Fractional Graph Laplacian Approach to Oversmoothing

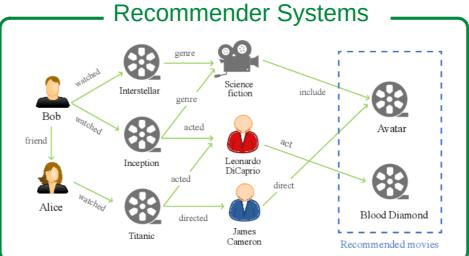
S. Maskey\*, R. Paolino\*, A. Bacho, G. Kutyniok

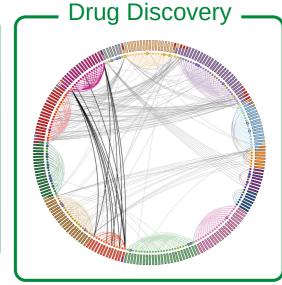
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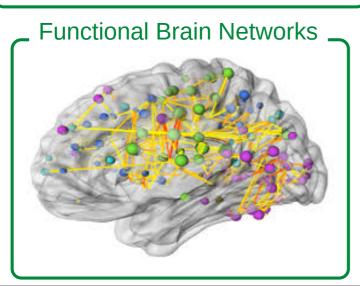


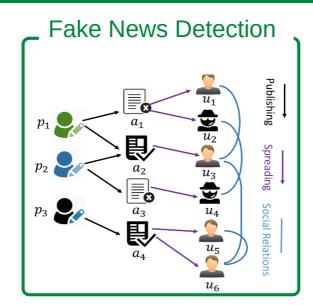
### **The Current Impact of Graph Neural Networks**

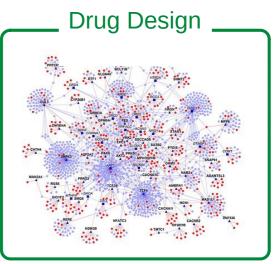
Social Networks











Gilmer, J., et al. (2017). Neural message passing for quantum chemistry.

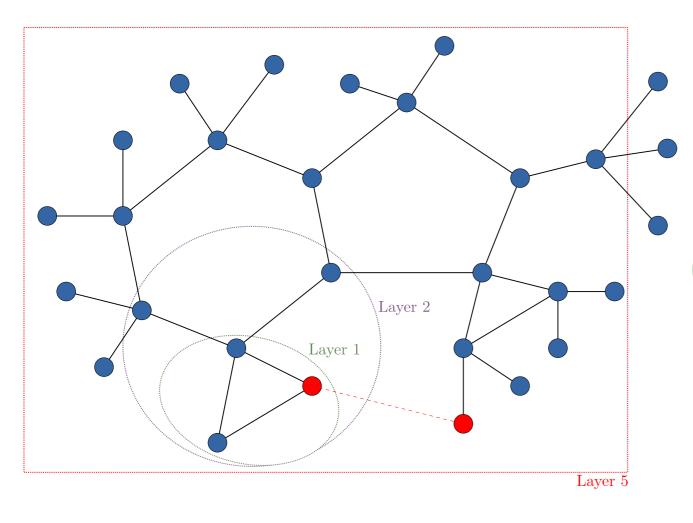
Wang, J., et al. (2018). Billion-scale commodity embedding for e-commerce recommendation in alibaba.

Monti, F., et al. (2019). Fake news detection on social media using geometric deep learning.

Fan, W., et al. (2019). Graph neural networks for social recommendation.



#### **GNNs Fail to Capture Long-Range Interactions**



- → To capture long-range dependencies, GNNs need increased depth.
- $\rightarrow$  The receptive field increases exponentially fast<sup>1,2</sup>.
  - $\rightarrow$  All nodes have the same computational graph.
  - $\rightarrow$  All nodes get the same embedding.
  - $\rightarrow$  The nodes' features converge to similar values.

**→**Oversmoothing

 $\rightarrow$  Not analyzed in directed graphs.

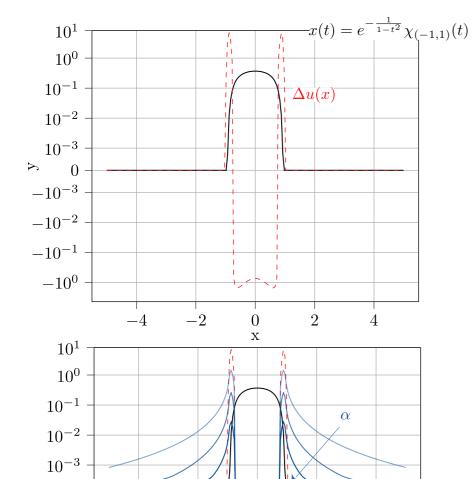
Can we take inspiration from physics to address it?

<sup>&</sup>lt;sup>1</sup>Oono, K., Suzuki, T. (2019). Graph Neural Networks Exponentially Lose Expressive Power for Node Classification.

<sup>2</sup>Cai, C., Wang, Y. (2020). A Note on Over- Smoothing for Graph Neural Networks.



#### **Non-Local Diffusion**



 $\mathbf{X}$ 

GNNs propagate node features similarly to the heat equation

$$\begin{cases} x'(t) = -\Delta x(t), \\ x(0) = x_0. \end{cases}$$

where the Laplacian is a differential  $(\rightarrow local)$  operator

$$-\Delta x(t) = \lim_{r \to 0} c_n \int_{|t| < r} \frac{x(t) - x(s)}{r^{n+2}} ds.$$

**Solution**: replace the local operator  $(-\Delta)$  with the global operator  $(-\Delta)^{\alpha}$  defined as

$$(-\Delta)^{\alpha}x(t) = c_{n,\alpha} \int_{\mathbb{R}^n} \frac{x(t) - x(s)}{|t - s|^{n+2\alpha}} ds, \ \alpha \in (0, 1).$$

 $\rightarrow$  The support increases as  $\alpha$  decreases.



 $-10^{-3}$ 

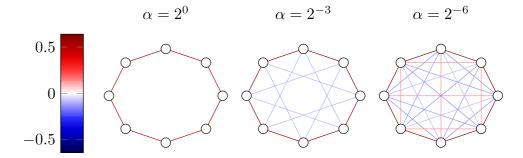
 $-10^{-2}$ 

 $-10^{-1}$ 

 $-10^{0}$ 

## **Fractional Graph Laplacian**

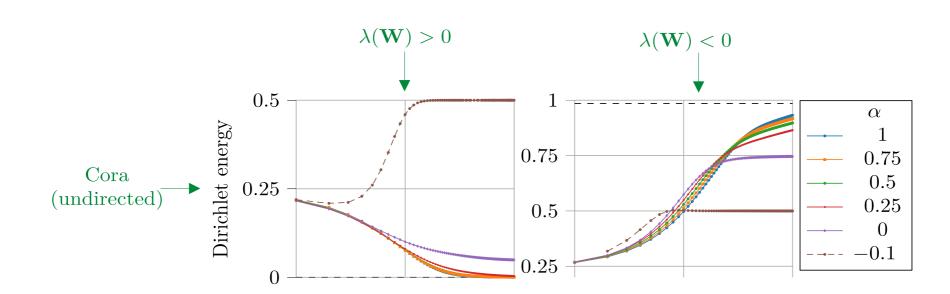
Fractional Graph Laplacian  $\mathbf{U}, \mathbf{\Sigma}, \mathbf{V}^{\mathsf{H}} = \mathrm{SVD}(\mathbf{L}), \, \mathbf{L}^{\alpha} \coloneqq \mathbf{U} \mathbf{\Sigma}^{\alpha} \mathbf{V}^{\mathsf{H}}.$ 



Fractional Graph Heat Eq.  $\mathbf{x}'(t) = -\mathbf{L}^{\alpha} \mathbf{x}(t) \mathbf{W}, \mathbf{x}(0) = \mathbf{x}_{0}.$ 

solution

 $\operatorname{vec}(\mathbf{x})(t) = \exp(-(\mathbf{W} \otimes \mathbf{L}^{\alpha})t) \operatorname{vec}(\mathbf{x}_{0}).$ 





```
% A, x_0 \text{ are given.}
     % Preprocessing
 \mathbf{1} \ \mathbf{D}_{\mathrm{in}} = \mathrm{diag}(\mathbf{A}\mathbf{1})
 \mathbf{p}_{\mathrm{out}} = \mathrm{diag}(\mathbf{A}^\mathsf{T} \mathbf{1})
 \mathbf{3} \; \mathbf{L} = \mathbf{D}_{\mathrm{in}}^{-1/2} \mathbf{A} \mathbf{D}_{\mathrm{out}}^{-1/2}
 4 U, \Sigma, V^H = svd(L)
     \% \alpha, h, \mathbf{W} learnable parameters
     % x<sub>0</sub> initial nodes' features
 5 def training_step(x_0):
            \mathbf{x}_0 = \text{input\_MLP}(\mathbf{x}_0)
            % Forward Euler Scheme
            for n \in \{1, \dots, N\} do
             \mathbf{x}_n = \mathbf{x}_{n-1} - i h \mathbf{U} \mathbf{\Sigma}^{\alpha} \mathbf{V}^{\mathsf{H}} \mathbf{x}_{n-1} \mathbf{W}
            \mathbf{x}_N = \text{output\_MLP}(\mathbf{x}_N)
            return \mathbf{x}_N
10
```

#### **fLode**

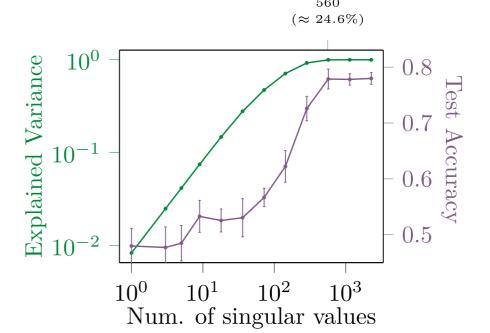
#### Disadvantages:

- 1. Computational cost grows cubically in N.
- 2. Storage cost grows quadratically in N.

#### Advantages:

GitHub

- 1. Easy to implement.
- 2. Versatile across different types of graphs.
- 3. Reduced cost with truncated SVD.







# Thank you very much for your attention!





Maskey\*, S., Paolino\*, R., Bacho, A., Kutyniok, G. (2023). A Fractional Graph Laplacian Approach to Oversmoothing.