

# Learning Discrete Directed Acyclic Graphs via Backpropagation

Andrew J. Wren<sup>∇</sup> Pasquale Minervini<sup>∇Ω</sup>  
Luca Franceschi<sup>∏</sup> Valentina Zantedeschi<sup>∇∇ℓ</sup>

andrew.wren@ntlworld.com

arXiv:2210.15353

Andrew J. Wren is very grateful to his co-authors who supervised him in the University College London MSc Machine Learning thesis project from which this paper derives.

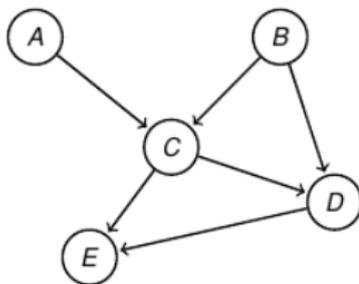
<sup>∇</sup> University College London    <sup>Ω</sup> University of Edinburgh    <sup>ℓ</sup> Inria London

<sup>∏</sup> Amazon Web Services (work done while at UCL, and prior to joining Amazon)    <sup>∇</sup> ServiceNow



- Problem: learning a Bayesian network's DAG from data.
- Question: can a probabilistic discrete backpropagation approach be used?
- Backprop methods.
- Architecture: DAG-DB.
- Experiments and results.
- Conclusion and future work.

- Recall the problem of structure identification: learning a Bayesian network's directed acyclic graph (DAG) from data it has generated.



$$P(A, B, C, D, E) = P(A)P(B)P(C|A, B)P(D|B, C)P(E|C, D)$$

Figure. Example of Bayesian network, with  $d = 5$  nodes.<sup>[1]</sup>

- Given data  $\mathbf{X} = (\mathbf{x}_{n,A}, \dots, \mathbf{x}_{n,E})_{n=1}^N \in \mathbb{R}^{N \times d}$  from a hidden  $d$ -node DAG  $D$ , make prediction  $D_{\text{pred}}$ .

[1]Adapted from Sahani, UCL (2021).

# Problem: learning a DAG from data (2)

- Existing approaches to the problem can mainly be divided between combinatoric, continuous and Bayesian.
- Differences include representation of DAG edges in core calculations, and whether gradient descent (GD) is used.

Approach	DAG edges	GD?	Examples
Combinatoric	Binary	No	PC-Stable <sup>[1]</sup> , FGES <sup>[2]</sup>
Continuous	Float	Yes	NOTEARS <sup>[3]</sup> , GOLEM <sup>[4]</sup>
Bayesian	Binary	Yes	DiBS <sup>[5]</sup> , DAG-GFlowNet <sup>[6]</sup>
Probabilistic	Binary	Yes	<u>DAG-DB</u> <i>presented today</i>

[1]Colombo & Maathuis. *Order-independent constraint-based causal structure learning*. (2014)

[2]Ramsey, Glymour, Sanchez-Romero & Glymour. *A million variables and more...* . (2017)

[3]Zheng, Aragam, Ravikumar & Xing. *DAGs with NO TEARS....* (2018)

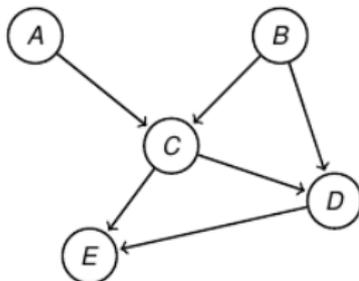
[4]Ng, Ghassami & Zhang. *On the Role of Sparsity and DAG Constraints for Learning Linear DAGs*. (2020)

[5]Lorch, Rothfuss, Schölkopf & Krause. *DiBS: Differentiable Bayesian Structure Learning*. (2021)

[6]Dele, Góis, Emezue, Rankawat, Lacoste-Julien, Bauer & Bengio. *Bayesian Structure Learning with Generative Flow Networks*. (2022)

Underlying approach:

- For data point  $\mathbf{x}$ , predict value at a 'child' node from its 'parents'.



$$P(A, B, C, D, E) = P(A)P(B)P(C|A, B)P(D|B, C)P(E|C, D)$$

*Figure.* Example of Bayesian network.<sup>[1]</sup>

- E.g, predict  $\mathbf{x}_D$  from  $\mathbf{x}_B$  and  $\mathbf{x}_C$ .

[1]Adapted from Sahani, UCL (2021).

Framework:

- **Directed graph.** With  $\mathbf{X} \in \mathbb{R}^{N \times d}$ , looking for graph on  $d$  nodes. Let  $\mathbf{Z}$  be  $d \times d$  *binary* adjacency matrix for a directed graph.
- **Distribution.** A *float* matrix  $\Theta$  (same shape as  $\mathbf{Z}$ ) parametrizes an ExpFam distribution,

$$p(\mathbf{Z}; \Theta) = \exp(\langle \mathbf{Z}, \Theta \rangle - A(\Theta)).$$

- For **sampling**, use ‘Perturb-&-MAP’<sup>[1]</sup> to get  $S$  samples. For each sample  $\mathbf{Z}^{(s)}$ , take the most probable value of  $\mathbf{Z}$  given parameter  $\Theta$  plus noise:

$$\mathbf{Z}^{(s)} = \text{MAP}(\Theta + \epsilon^{(s)}) \text{ with } \epsilon^{(s)} \sim \text{Logistic}(0, 1), \quad s = 1, \dots, S.$$

[1]Papandreou & Yuille. *Perturb-and-MAP random fields: Using discrete optimization to learn and sample from energy models.* (2011)

To learn  $\Theta$ , need a way to **backpropagate** from  $\mathbf{Z}$  to  $\Theta$ .  
Backprop methods which keep  $\mathbf{Z}$  binary include:

- **Straight-Through Estimation (STE)**.<sup>[1]</sup> Very simple.
- **Score-Function Estimation (SFE)**. Aka REINFORCE.
- **Blackbox Estimation (BBE)**. Not probabilistic.
- **Implicit Maximum Likelihood Estimation (I-MLE)**.<sup>[2]</sup>  
Taking advantage  $p(\mathbf{Z}; \Theta) \in \text{ExpFam}$ .

[1] Hinton, Srivastava & Swersky. *Neural networks for machine learning*. (2012); Bengio, Léonard & Courville. *Estimating or Propagating Gradients Through Stochastic Neurons for Conditional Computation*. (2013)

[2] Niepert, Minervini & Franceschi. *Implicit MLE: Backpropagating Through Discrete Exponential Family Distributions*. (2021)

- For **backward pass**, with average loss (plus regularizers)  $L$ , Straight-Through Estimation (STE), approximates gradient of  $L$  w.r.t.  $\Theta$  as

$$\frac{\partial L}{\partial \Theta} \propto \sum_{s=1}^S \frac{\partial L}{\partial \mathbf{z}^{(s)}}.$$

- Or, for **backward pass** with Implicit Maximum Likelihood (I-MLE), perturb  $\Theta$  using each sample  $\mathbf{z}^{(s)}$ ,

$$\tilde{\Theta}^{(s)} = \Theta - \lambda \frac{\partial L}{\partial \mathbf{z}^{(s)}}.$$

- Use noise values from sampling  $\epsilon^{(s)}$  to set

$$\tilde{\mathbf{z}}^{(s)} = \text{MAP}(\tilde{\Theta}^{(s)} + \epsilon^{(s)}).$$

- Approximate gradient of  $L$  w.r.t.  $\Theta$  as

$$\frac{\partial L}{\partial \Theta} \approx \frac{1}{\lambda S} \sum_{s=1}^S \left[ \mathbf{z}^{(s)} - \tilde{\mathbf{z}}^{(s)} \right].$$

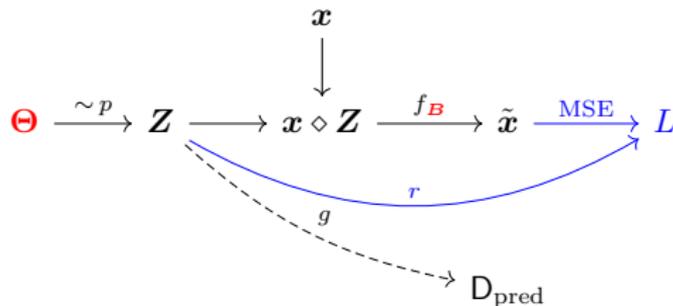
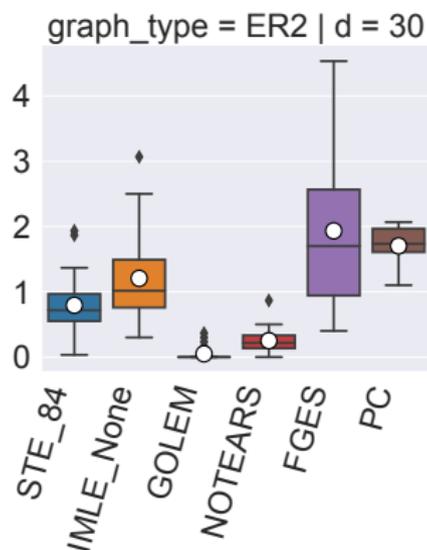


Figure. DAG-DB, including **learnable parameters** and **loss calculation**.

- $\mathbf{x} \diamond \mathbf{Z}$  ensures only ‘parents’ influence predictions for ‘children’.
- $f_{\mathbf{B}}$  is a very simple neural net: linear no bias.
- $r$  is regularizer: NOTEARS-like regularizer pushing  $\mathbf{Z}$  towards being a DAG, plus sparsity regularizer.
- Depending on compute and size of problem,  $\mathbf{Z}$  is transformed into a DAG  $D_{\text{pred}}$  by a maximum DAG algorithm  $g$  in training or only at evaluation.



**ER2:** linear Gaussian additive noise model on random (Erdős-Rényi) graphs with  $d$  nodes, and expected number of edges is  $2d$ . In this example,  $d = 30$  nodes.

Results on synthetic data showing a normalised class **structural Hamming distance**  $nSHD_c$  from the true DAG.

Shows two DAG-DB methods STE\_84 and IMLE\_None, compared with continuous (GOLEM, NOTEARS) and combinatoric (FGES, PC) methods.

Model		SHD <sub>c</sub>	prec <sub>c</sub>
IMLE_None	mean	12.7	0.869
	median	13	<b>1.000</b>
GOLEM		<b>11</b>	<b>1.000</b>
NOTEARS		<b>11</b>	0.467
FGES		<b>11</b>	0.750
PC		<b>11</b>	0.750

Tests on the Sachs cellular biochemistry dataset.<sup>1</sup> Best metric scores are in bold. SHD<sub>c</sub> is un-normalised; prec<sub>c</sub> is a **precision** metric.

<sup>1</sup> Sachs, Perez, Pe'er, Lauffenburger & Nolan. *Causal protein-signaling networks derived from multiparameter single-cell data.* (2005)

## Take home

- Using discrete probabilistic backpropagation, DAG-DB performs competitively at structure identification, often better than combinatoric methods, though not as well as continuous approaches.
- May be easier than many other DAG identification methods to integrate with other neural nets.
- Extend to more types of Bayesian network: non-Gaussian, non-linear, discrete-valued, with interventions.
- What if no 'gold' DAG, e.g. we generate a latent DAG optimised to achieve some goal?

Thank you!