

Densely connected normalizing flows

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- Assume available dataset D , obtained by sampling an unknown data distribution p_D
- Our goal is to approximate the unknown p_D using a model p_θ
- Minimize divergence between p_D and p_θ :

$$\min \text{KL}(p_D || p_\theta) = \min \mathbb{E}_{\mathbf{x} \in D} [-\ln p_\theta(\mathbf{x})]$$

- Various designs of p_θ : Autoregressive factorization Van Oord et al. (2016), Lower bound using variational distribution Kingma and Welling (2014), Unnormalized distribution Salakhutdinov and Hinton (2009), etc.
- We focus on a bijective formulation of p_θ due to exact likelihood and efficient sampling Rezende and Mohamed (2015)

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- Given the differentiable bijection \mathbf{f}_θ , the change of variable formula is:

$$p_\theta(\mathbf{x}) = p(\mathbf{z}) \left| \det \frac{\partial \mathbf{z}}{\partial \mathbf{x}} \right|, \quad \mathbf{z} = \mathbf{f}_\theta(\mathbf{x})$$

- By defining \mathbf{f}_θ as composition $\mathbf{f}_\theta = \mathbf{f}_{\theta_K} \circ \mathbf{f}_{\theta_{K-1}} \circ \dots \circ \mathbf{f}_{\theta_1}$, we obtain log-likelihood Dinh et al. (2015) and Rezende and Mohamed (2015):

$$\ln p_\theta(\mathbf{x}) = \ln p(\mathbf{z}_K) + \sum_{i=1}^K \ln |\det \mathbf{J}_{f_i}|.$$

$$\mathbf{x} \xleftrightarrow{f_1} \mathbf{z}_1 \xleftrightarrow{f_2} \mathbf{z}_2 \xleftrightarrow{f_3} \dots \xleftrightarrow{f_{i-1}} \mathbf{z}_i \xleftrightarrow{f_i} \dots \xleftrightarrow{f_K} \mathbf{z}_K, \quad \mathbf{z}_K \sim \mathcal{N}(0, \mathbf{I})$$

- Due to the bijective constraint, every \mathbf{z}_i has the same dimensionality
- Model expressiveness is limited by the input dimensionality

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- At arbitrary step i :

$$\dots \xleftarrow{f_{i-1}} \mathbf{z}_i \xrightarrow{\text{aug}} [\mathbf{z}_i, \mathbf{e}_i] \xrightarrow{h_i} \mathbf{z}_i^{(\text{aug})} \xleftarrow{f_{i+1}} \mathbf{z}_{i+1} \xleftarrow{f_{i+2}} \dots$$

- $\text{aug}(\cdot)$ concatenates noise to latent representation \mathbf{z}_i :

$$\text{aug}(\mathbf{z}_i) = [\mathbf{z}_i, \mathbf{e}_i], \quad \mathbf{e}_i \sim \mathcal{N}(0, I)$$

- $h_i(\cdot, \cdot)$ transforms the noise based on previous latent variables $\mathbf{z}_{<i}$:

$$\mathbf{z}_i^{(\text{aug})} = h_i([\mathbf{z}_i, \mathbf{e}_i], \mathbf{z}_{<i}) = [\mathbf{z}_i, \sigma \odot \mathbf{e}_i + \mu], \quad (\mu, \sigma) = g_i(\mathbf{z}_{<i})$$

$$\frac{\partial \mathbf{z}_i^{(\text{aug})}}{\partial [\mathbf{z}_i, \mathbf{e}_i]} = \begin{bmatrix} \mathbf{I} & 0 \\ 0 & \text{diag}(\sigma) \end{bmatrix}$$

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- Likelihood lower bound defined as:

$$\ln p(\mathbf{z}_i) \geq \mathbb{E}_{\mathbf{e}_i \sim p^*(\mathbf{e}_i)} [\ln p(\mathbf{z}_i^{(\text{aug})}) - \ln p^*(\mathbf{e}_i) + \ln |\det \text{diag}(\boldsymbol{\sigma})|].$$

- Trivial "inverse" - remove noise dimensions:

$$\mathbf{z}_i^{(\text{aug})} = [\mathbf{z}_i, \boldsymbol{\sigma} \odot \mathbf{e}_i + \boldsymbol{\mu}] \Rightarrow \mathbf{z}_i = \mathbf{z}_i^{(\text{aug})}_{[:d]}, \quad d = \text{dim}(\mathbf{z}_i)$$

- Resulting scheme with the increased model width at arbitrary steps:

$$\mathbf{x} \xleftrightarrow{f_1} \mathbf{z}_1 \xleftrightarrow{f_2, \text{aug}, h_2} \mathbf{z}_2^{(\text{aug})} \xleftrightarrow{f_3} \dots \xleftrightarrow{f_i, \text{aug}, h_i} \mathbf{z}_i^{(\text{aug})} \xleftrightarrow{f_{i+1}} \dots \xleftrightarrow{f_K} \mathbf{z}_K$$

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- At arbitrary step i :

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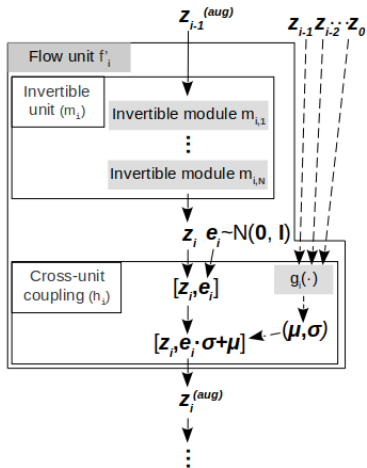
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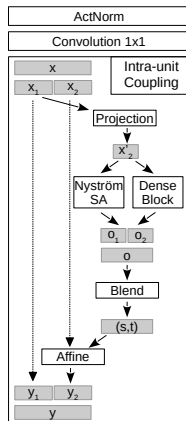
- Resulting scheme with the increased model width at arbitrary steps:

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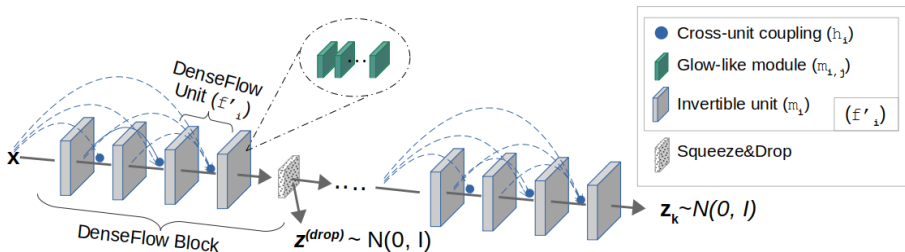
- **Invertible unit:** arbitrary composition of differentiable bijections
- **Cross-unit coupling:** modular coupling layer over latent representations in multiple stages



- Based on Glow modules Kingma and Dhariwal (2018)
- Coupling network fuses:
 - Local correlations produced by Dense block Huang et al. (2017)
 - Global context captured by Nyström Self-attention Xiong et al. (2021)
- More efficient than Flow++ coupling Ho et al. (2019)
- **Intra-unit coupling:** second level of skip connections



- Image-oriented multi-scale architecture
- Dense skip connections provided by cross-unit and intra-unit couplings



Method		CIFAR-10	ImageNet	CelebA	ImageNet
		32x32	32x32	64x64	64x64
Variational Autoencoders	Conv Draw Gregor et al. (2016)	3.58	4.40	-	4.10
	DVAE++ Vahdat et al. (2018)	3.38	-	-	-
	IAF-VAE Kingma et al. (2016)	3.11	-	-	-
	BIVA Maaløje et al. (2019)	3.08	3.96	2.48	-
	Imp. DDPM Nichol and Dhariwal (2021)	2.94	-	-	3.53
Autoregressive Models	Gated PixelCNN Oord et al. (2016)	3.03	3.83	-	3.57
	PixelRNN Van Oord et al. (2016)	3.00	3.86	-	3.63
	PixelCNN++ Salimans et al. (2017)	2.92	-	-	-
	Image Transformer Parmar et al. (2018)	2.90	3.77	2.61	-
	PixelSNAIL Chen et al. (2018)	2.85	3.80	-	-
	SPN Menick and Kalchbrenner (2019)	-	3.85	-	3.53
	Routing transformer Roy et al. (2021)	2.95	-	-	3.43
Normalizing Flows	Real NVP Dinh et al. (2017)	3.49	4.28	3.02	3.98
	GLOW Kingma and Dhariwal (2018)	3.35	4.09	-	3.81
	Residual Flow Chen et al. (2019)	3.28	4.01	-	3.78
	i-DenseNet Perugachi-Diaz et al. (2021)	3.25	3.98	-	-
	Flow++ Ho et al. (2019)	3.08	3.86	-	3.69
	ANF Huang et al. (2020)	3.05	3.92	-	3.66
	VFlow Chen et al. (2020)	2.98	3.83	-	3.66
Hybrid Architectures	MaCow Ma et al. (2019)	3.16	-	-	3.69
	SurVAE Flow Nielsen et al. (2020)	3.08	4.00	-	3.70
	NVAE Vahdat and Kautz (2020)	2.91	3.92	2.03	-
	PixelVAE++ Sadeghi et al. (2019)	2.90	-	-	-
	δ -VAE Razavi et al. (2019)	2.83	3.77	-	-
DenseFlow-74-10 (ours)		2.98	3.63	1.99	3.35

- Our DenseFlow uses **only one** GPU for training!
 - Without gradient checkpointing
 - Without mixed precision

Dataset	Model	GPU type	GPUs	Duration (h)	Likelihood (bpd)
CIFAR-10	VFlow Chen et al. (2020)	RTX 2080Ti	16	~500	2.98
	NVAE Vahdat and Kautz (2020)	Tesla V100	8	55	2.91
	DenseFlow-74-10 (ours)	RTX 3090	1	250	2.98
ImageNet32	VFlow Chen et al. (2020)	Tesla V100	16	~1440	3.83
	NVAE Vahdat and Kautz (2020)	Tesla V100	24	70	3.92
	DenseFlow-74-10 (ours)	Tesla V100	1	310	3.63
CelebA	VFlow Chen et al. (2020)	n/a	n/a	n/a	-
	NVAE Vahdat and Kautz (2020)	Tesla V100	8	92	2.03
	DenseFlow-74-10 (ours)	Tesla V100	1	224	1.99

■ Competitive visual quality on CIFAR10

	Model	FID ↓
Autoregressive Models	PixelCNN Ostrovski et al. (2018) and Van Oord et al. (2016)	65.93
	PixellQN Ostrovski et al. (2018)	49.46
Normalizing Flows	i-ResNet Behrmann et al. (2019)	65.01
	Glow Kingma and Dhariwal (2018)	46.90
	Residual flow Chen et al. (2019)	46.37
GANs	DCGAN Ostrovski et al. (2018) and Radford et al. (2016)	37.11
	WGAN-GP Gulrajani et al. (2017) and Ostrovski et al. (2018)	36.40
	DA-StyleGAN V2 Zhao et al. (2020)	5.79
Hybrid Architectures	SurVAE-flow Nielsen et al. (2020)	49.03
	VAEBM Xiao et al. (2020)	12.19
	DenseFlow-74-10 (ours)	34.90

- Samples generation:
 - Sample the latent distribution to obtain \mathbf{z} : $\mathbf{z} \sim \mathcal{N}(0, \mathbf{I})$
 - Apply the inverse transformation $\mathbf{x} = \mathbf{f}_\theta^{-1}(\mathbf{z})$



- Expressiveness of a NF does not only depend on latent dimensionality but also on its distribution across the model depth
- Expressiveness of a NF can also be improved by conditioning the introduced noise with the proposed densely connected cross-unit coupling
- Combining these insights with Nystrom self attention and the proposed intra-unit coupling increases the NF performance while reducing computational requirements
- GitHub: [matejgrcic/DenseFlow](#)
- ArXiv: [abs/2106.04627](#)
- Contact: matej.grcic@fer.hr
- Questions: email or new issue



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