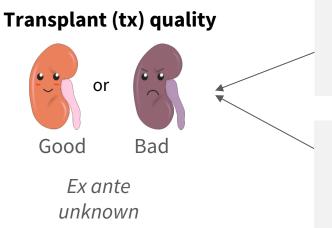
# Counterbalancing Learning and Strategic Incentives in Allocation Markets

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# **MOTIVATION: KIDNEY ALLOCATION WAITLIST**



#### Information about quality

#### 1. Organ score

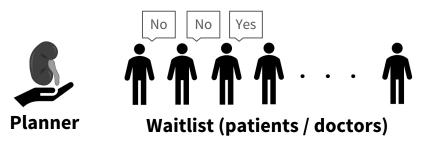
P {successful tx} based on organ features Public (e.g., size, donor age)

#### 2. Doctors' private opinions

Private

Based on their own experience / knowledge

### **MOTIVATION: KIDNEY ALLOCATION WAITLIST**



- Patients waiting for an organ offer
- Upon receiving offer, each patient decides to accept or decline
- Or in most cases, his or her doctor makes decision
- Social planner decides whether / how to make the offers

**Planner's Goal:** Optimize overall tx quality Patient / Doctor's Goal: Optimize <u>my</u> tx quality

i.e. Utilize good organs and discard bad organs

### **BASELINE: FIRST-COME-FIRST-SERVE MECHANISM**

- Commonly used -- aka Sequential Offering
- Object offered to each agent sequentially one-by-one

#### What could go wrong?

X To k-th agent:

availability of object implies previous (k-1) agents have declined it

- X Induces **herding** behavior → **incorrect discard** of objects
- X In kidney allocation: > 20% discard rate, while ~3.6yr wait time
   (De Mel et al. (2020), Mohan et al. (2018), Zhang (2010) for empirical evidence)

### **MAIN PROBLEM AND RESULTS**

Q: Given a single indivisible object of unknown quality, whether and how to allocate it to a queue of privately informed and strategic and agents?

I.e., How to balance planner's learning and agents' strategic incentives?

### **MAIN PROBLEM AND RESULTS**

### **A:**

- 1. FCFS can cause welfare loss due to herding
- Propose a new class of mechanisms involving dynamic batched voting to crowdsource private information, and show existence of such mechanisms that improve welfare
- 3. Simple greedy algorithm to achieve this improvement

### **RELATED LITERATURE**

#### **Social Learning**

- Banerjee (1992), Bikhchandani et al. (1992)
- In kidney markets: De Mel et al. (2020), Mohan et al. (2018), Zhang (2010)

#### Voting

• Austen-Smith and Banks (1996), Condorcet (1785)

#### **Information Design / Bayesian Exploration**

- Arieli et al. (2018), Kamenica and Gentzkow (2011), Papanastasiou et al. (2017)
- Glazer et al. (2021), Immorlica et al. (2019), Kremer et al. (2014), Mansour et al. (2016)



# SET UP

### Object

- Single indivisible object
- **Quality**:  $\omega \in \{G, B\}$ fixed and ex-ante unknown
- **Prior**:  $\mu = P(w=G)$ commonly known

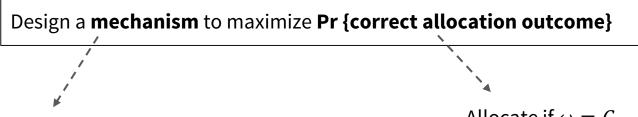
### Agents

For each agent in position *i* 

- **Private signal:**  $s_i \in \{q, b\}$
- **Precision** of signal:  $q = P(s_i = g | w = G) = P(s_i = b | w = B) \in (1/2, 1)$ commonly known
- **Utility**:
  - $\begin{cases} 1 & \text{with object and } \omega = G \\ -1 & \text{with object and } \omega = B \\ 0 & \text{without object} \end{cases}$



#### **Planner's goal**



- 1. Asks (a batch of) agents to report private signals
- 2. Decides whether and how to allocate the object e.g., FCFS, Lottery...

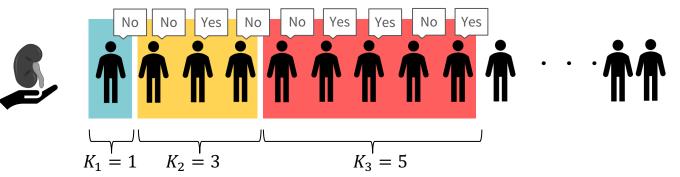
```
Allocate if \omega = G
Discard if \omega = B
```

#### We propose a new class of mechanisms

### **VOTING MECHANISMS**

- Idea: **batch-by-batch dynamic voting** to crowdsource information
- For each batch *j*: 1. Offer to a **batch of**  $K_i$  agents
  - 2. Each agent simultaneously votes to opt in or opt out.
  - 3. If **majority** opts in: Allocate object uniformly at random. Otherwise: Move on to batch j+1.

Results from batch j become public.



Batch size K<sub>j</sub> can be chosen dynamically

#### Kang, Monachou, Koren, Ashlagi (NeurIPS 2021)

### **VOTING MECHANISMS**

- Idea: **batch-by-batch dynamic voting** to crowdsource information
- For each batch *j*: 1. Offer to a **batch of** *K*<sub>*i*</sub> agents

Yes

 $K_2 = 3$ 

No

NO

No

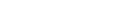
2. Each agent simultaneously votes to opt in or opt out

 $K_{3}' = 5$ 

If majority opts in: Allocate object uniformly at random.
 Otherwise: Move on to batch j+1.

Results from batch j become public.

Batch size K<sub>j</sub> can be chosen dynamically



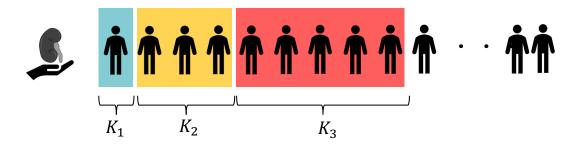
Sequential  $\rightarrow$  Batch



### **VOTING MECHANISMS**

FCFS is also a voting mechanism ( $K_j = 1$  for all j)

We restrict our attention to the class of voting mechanisms

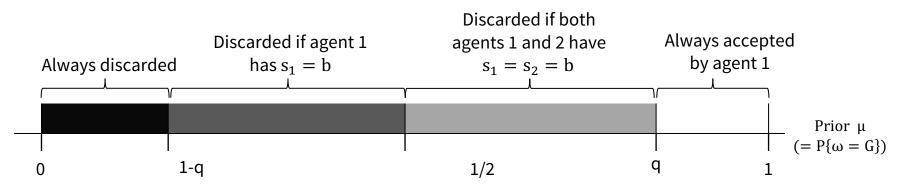


Main problem reduces to:

How to dynamically choose batch size  $K_i$ ?



### FCFS: HAMPERED LEARNING W/ WRONG BATCH SIZE (K=1)



**Figure 1.** Allocation outcome of the sequential offer mechanism based on the value of prior  $\mu \in (0, 1)$  with respect to signal precision q.

- In this extreme case, planner **can learn from only up to two** agents
- Restricted learning leads to poor correctness and welfare loss

### **BALANCING AGENTS' INCENTIVES vs PLANNER'S LEARNING**

Small batch size		Large batch size	
~	<b>Every vote is pivotal</b> : in particular, incentivizes agents with $s_i = b$ signals to truthfully opt out	~	<b>More data points</b> : gives confidence that if object is allocated, then it is likely that quality is good
×	If too small, allocation depends on learning from insufficient sample size	×	If too large, everyone is incentivized to opt in

- Presence of incentives puts upper bound on # of private signals planner can learn from
- Optimal batch size is the **maximum batch size** that agents' **incentives allow** (i.e., IC is tight)

## **MAIN THEORETICAL RESULTS**

#### **Theorem 1.**

- For any *q* > *μ*, there always exists a voting mechanism V ∈ V that is incentivecompatible and improves correctness compared to the sequential offering mechanism V<sub>SEQ</sub>.
- For any  $q \le \mu$ , there is no incentive-compatible voting mechanism and any  $V \in \mathcal{V}$  achieves the same correctness as  $V_{SEQ}$ .

#### **Corollary 1.**

• For any  $q > \mu$ , such a mechanism can be found using a **greedy algorithm**.

## TIGHTER INCENTIVES FOR THE WELL-INFORMED (HIGH q) AND OPTIMISTIC (HIGH $\mu$ ) (Formal proofs and results in the paper)

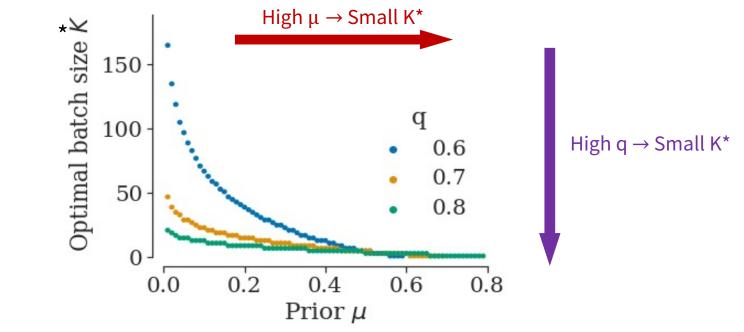


Figure 2. Optimal batch sizes for all possible priors  $\mu$  for three information regimes  $q \in \{0.6, 0.7, 0.8\}$ 

### **VOTING WORKS WELL, EVEN IN ITS SIMPLEST FORM**

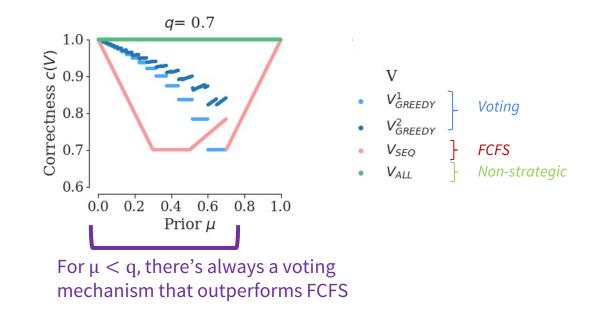


Figure 3. Comparison of correctness in different mechanisms simulated with 345 agents.

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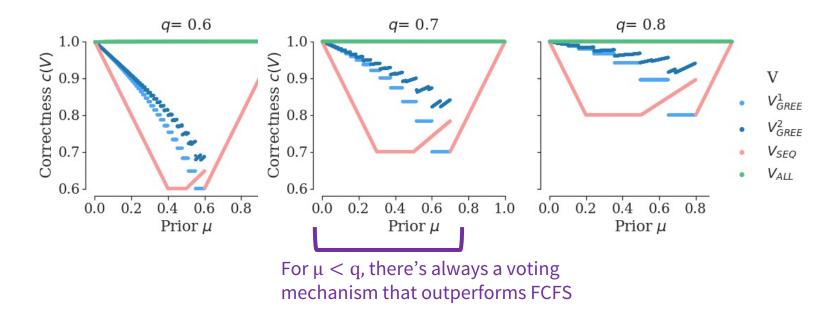


Figure 3. Comparison of correctness in different mechanisms simulated with 345 agents.

### **CONCLUSION**

#### Main takeaways

- **Tension** between: Planner's learning goal vs Agents' strategic incentives
- How to **incorporate voting into mechanism design** to mitigate this tension
- In particular, by introducing **batching** and **randomness**

#### Implications

- Bayesian risk adjustment for organ allocation markets
- Analysis of learning problems with **strategic samples**
- Resembles exploitation vs exploration

#### Limitations

- This is a stylized model!
- Fairness? Voting mechanism (partly) breaks priority for better welfare