## **Compressive Visual Representations**

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#### The multiview self-supervised learning framework



InfoMax approaches (e.g. contrastive methods)



#### Bootstrap Your Own Latent (BYOL) approaches

maximum likelihood estimation



#### InfoMax and maximum likelihood are NOT ideal

Most contrastive and latent bootstrapping methods did not consider this

What all multiview self-supervised methods hope to achieve:



What InfoMax and maximum likelihood actually achieve by maximizing I(Y;Z):



A representation Z that captures only the invariant, i.e. I(X;Y) Any Z that contains I(X;Y) is valid at optimal, no matter it contains how much irrelevant info about X

This Z is obviously not the invariant you want.

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What all multiview self-supervised<br/>methods hope to achieve:What InfoMax and maximum likelihood<br/>actually achieve by maximizing I(Y;Z):View1: XZView2: YView1: XZView2: YView1: XZView2: YView1: XView2: YView1: YView2: YView1: Y

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### The Conditional Entropy Bottleneck (CEB)

Explicitly compress self-supervised models with the CEB objective

Compressing a self-supervised model is very simple!

- 1. Convert the final output representations into explicit distributional forms
- 2. Replace the InfoMax or maximum likelihood objective with CEB

$$CEB \equiv \min_{Z} \beta I(X; Z|Y) - I(Y; Z)$$
$$\equiv \min_{Z} \beta (-H(Z|X) + H(Z|Y)) + H(Y|Z)$$





There is a tractable variational bound for CEB:

$$vCEB \equiv \min_{e(z|x), b(z|y), d(y|z)} \mathbb{E}_{x, y \sim p(x, y), z \sim e(z|x)} \beta(\log e(z|x) - \log b(z|y)) - \log d(y|z)$$

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#### Milestone: supervised-level, self-supervised results

We train a linear classifier on the self-supervised representation, learned without labels. It achieves results as good as fully supervised models, showing how general the representation is.



Comparison is system-wise as in prior work. We use reasonable supervised baselines reported in the SimCLR and BYOL papers.

#### Compressed models are robust to out-of-distribution

github.com/google-research/robustness\_metrics

Method	ImageNet-A	ImageNet-C	ImageNet-R	ImageNet-v2	ImageNet-Vid	YouTube-BB	ObjectNet
SimCLR	1.3	35.0	18.3	57.7	63.8	57.3	18.7
C-SimCLR	<b>1.4</b>	<b>36.8</b>	<b>19.6</b>	<b>58.7</b>	<b>64.7</b>	<b>59.5</b>	<b>20.8</b>
BYOL	1.6	42.7	24.4	62.1	67.9	60.7	23.4
C-BYOL	<b>2.3</b>	<b>45.1</b>	<b>25.8</b>	<b>63.9</b>	<b>70.8</b>	<b>63.6</b>	<b>25.5</b>





**ObjectNet** Changing viewpoints & backgrounds



\*The main paper introduces a new theoretical connection between CEB compression and the model's Lipschitz constant, helping to explain why compressed models are more robust.

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#### Compressed feature representations transfer better

Transfer self-supervised representations pre-trained on ImageNet to other classification tasks

Method	Food101	CIFAR10	CIFAR100	Flowers	Pet	Cars	Caltech-101	DTD	SUN397	Aircraft	Birdsnap
SimCLR	72.5	91.1	74.4	88.4	83.5	49.7	89.5	72.5	61.8	51.6	35.4
C-SimCLR	<b>73.0</b>	<b>91.6</b>	<b>75</b> -2	<b>89.0</b>	<b>84.0</b>	<b>52.7</b>	<b>91.2</b>	<b>73.0</b>	62.3	<b>53.5</b>	<b>38.2</b>

# Thank you!

arxiv.org/abs/2109.12909

Our implementation is available on github

For questions, reach out to Kuang-Huei Lee (leekh@google.com)



