

# Average Individual Fairness

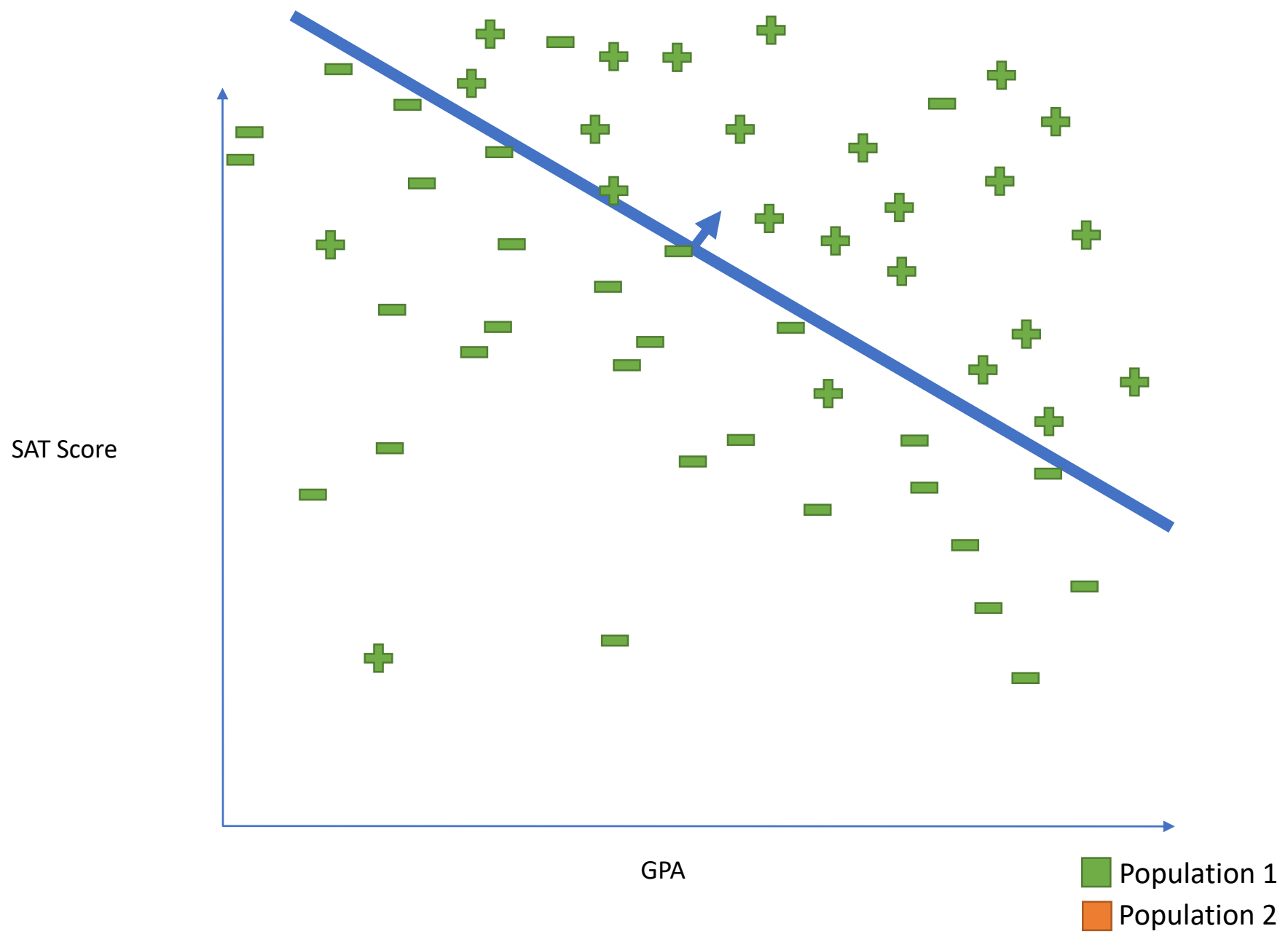
Aaron Roth

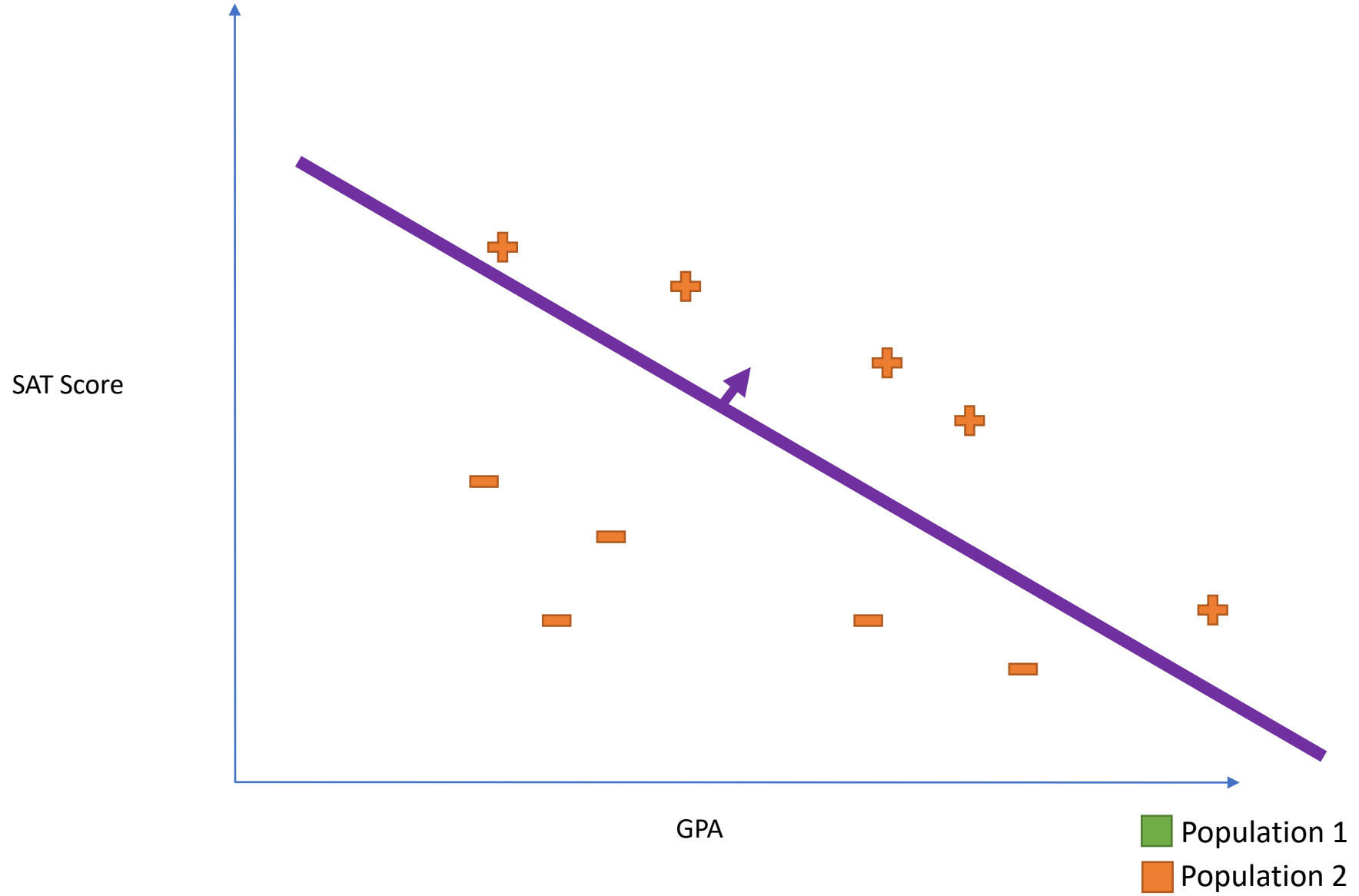


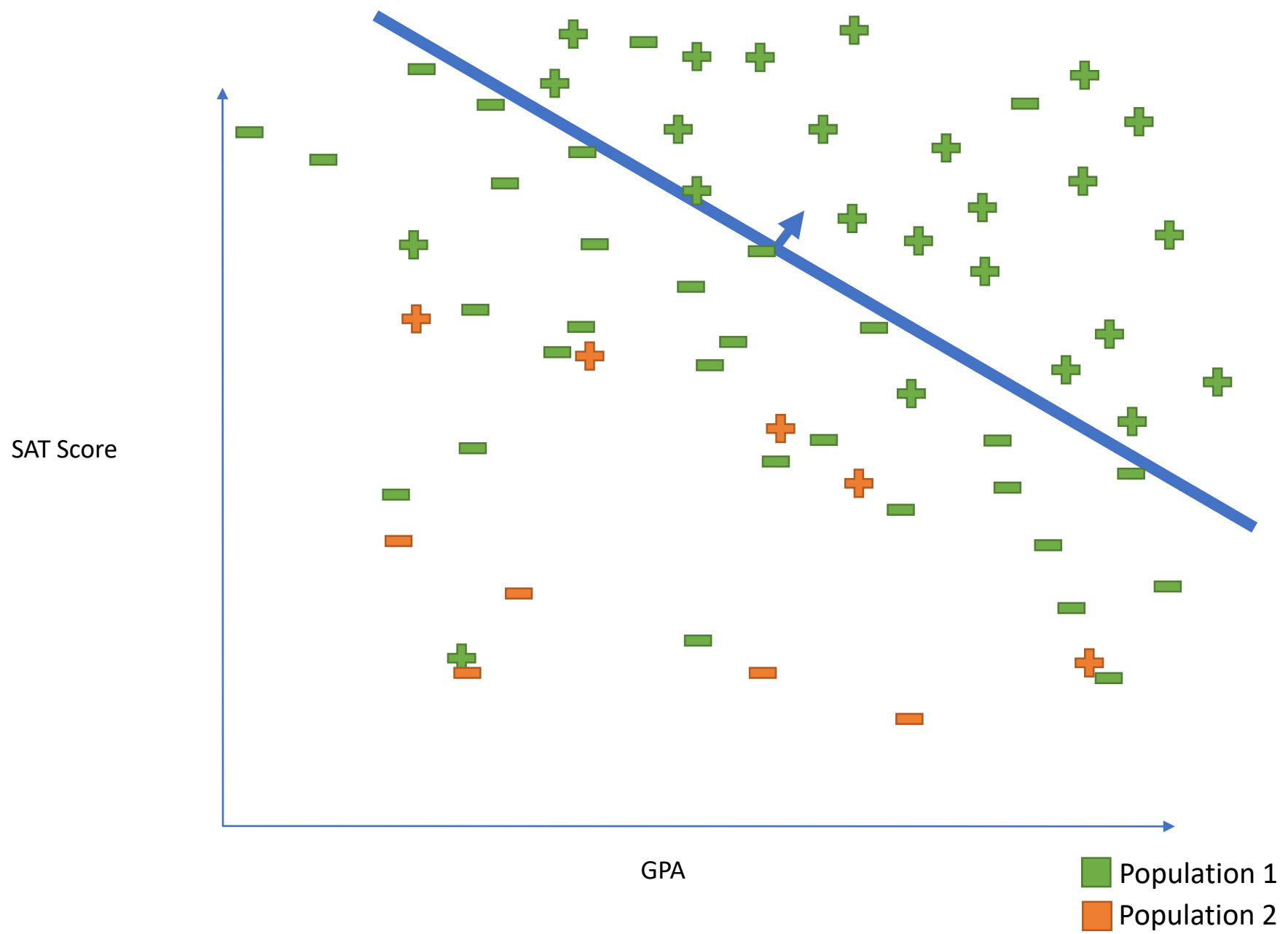
Based on Joint Work with:

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# Why was the classifier “unfair”?

**Question:** Who was harmed?

**Possible Answer:** The qualified applicants mistakenly rejected.

**False Negative Rate:** The rate at which harm is done.

**Fairness:** Equal false negative rates across groups?

[Chouldechova], [Hardt, Price, Srebro], [Kleinberg, Mullainathan, Raghavan]

Statistical Fairness Definitions:

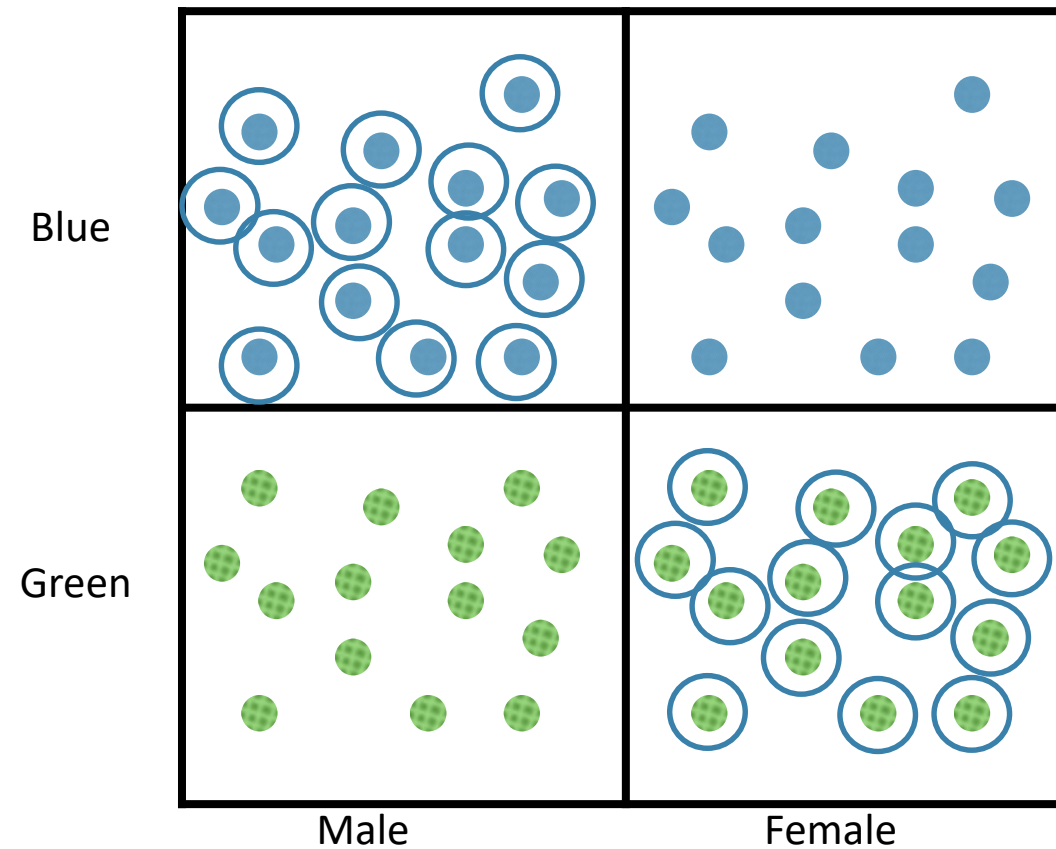
1. Partition the world into groups (often according to a “protected attribute”)
2. Pick your favorite statistic of a classifier.
3. Ask that the statistic be (approximately) equalized across groups.

# But...

- A classifier equalizes false negative rates. What does it promise you?
  - The *rate* in false negative rate assumes you are a uniformly random member of your population.
  - If you have reason to believe otherwise, it promises you nothing...

# For example

- Protected subgroups: “Men”, “Women”, “Blue”, “Green”. Labels are independent of attributes.
- The following allocation equalizes false negative rates across all four groups.



Sometimes individuals are subject to more than one classification task...





# The Idea

- Postulate a distribution over *problems* and *individuals*.
- Ask for a *mapping between problems and classifiers* that equalizes false negative rates across every pair of individuals.
- Redefine *rate*:

*Averaged over the problem distribution.*

*An individual definition of fairness.*

# A Formalization

- An unknown distribution  $P$  over individuals  $x_i \in X$
- An unknown distribution  $Q$  over *problems*  $f_j: X \rightarrow \{0,1\}$ ,  $f_j \in F$
- A hypothesis class  $H \subseteq \{0,1\}^X$  (Note  $f_j$ 's not necessarily in  $H$ )
- Task: Find a *mapping from problems to hypotheses*  $\psi \in (\Delta H)^F$ 
  - A new “problem” will be represented as a new labelling of the training set.
  - Finding the hypothesis corresponding to a new problem shouldn't require resolving old problems. (Allows online decision making)

# What to Hope For (Computationally)

- Machine learning learning is already computationally hard [KSS92,KS08,FGKP09,FGPW14,...] even for simple classes like halfspaces.
- So we shouldn't hope for an algorithm with worst-case guarantees...
  - But we might hope for an efficient reduction to unconstrained (weighted) learning problems.
- “Oracle Efficient Algorithms”
  - This design methodology often results in practical algorithms.

# Computing the Optimal Empirical Solution.

Initialize  $\lambda_i^1 = 1/n$  for each  $i \in \{1, \dots, n\}$

For  $t = 1$  to  $T = O\left(\frac{\log n}{\epsilon^2}\right)$

- **Learner Best Responds:**

- For each problem  $j$ , solve the learning problem  $h_j^t = A(S_j^t)$  for  $S_j^t = \left\{ \left( \lambda_i^t + \frac{1}{n}, x_i, f_j(x_i) \right) \right\}_{i=1}^n$
- Set  $\gamma^t = \mathbf{1}[\sum_i^n \lambda_i^t \geq 0]$

- **Auditor Updates Weights:**

- Multiply  $\lambda_i^t$  by  $(err(x_i, h^t, \hat{Q}) - \gamma)$  for each expert  $i$  and renormalize to get updated weights  $\lambda_i^{t+1}$ .

Output the weights  $\lambda_i^t$  for each person  $i$  and step  $t$ .

# Defining $\psi$

- Parameterized by the sequence of dual variables  $\lambda^T = \{\lambda^t\}_{t=1}^T$

$\psi_{\lambda^T}(f)$ :

For  $t = 1$  to  $T$

- Solve the learning problem  $h^t = A(S^t)$  for  $S^t = \left\{ \left( \lambda_i^t + \frac{1}{n}, x_i, f(x_i) \right) \right\}_{i=1}^n$

Output  $p_f \in \Delta H$  where  $p_f$  is uniform over  $\{h^t\}_{t=1}^T$

(Consistent with ERM solution)

# Computing the Optimal Empirical Solution.

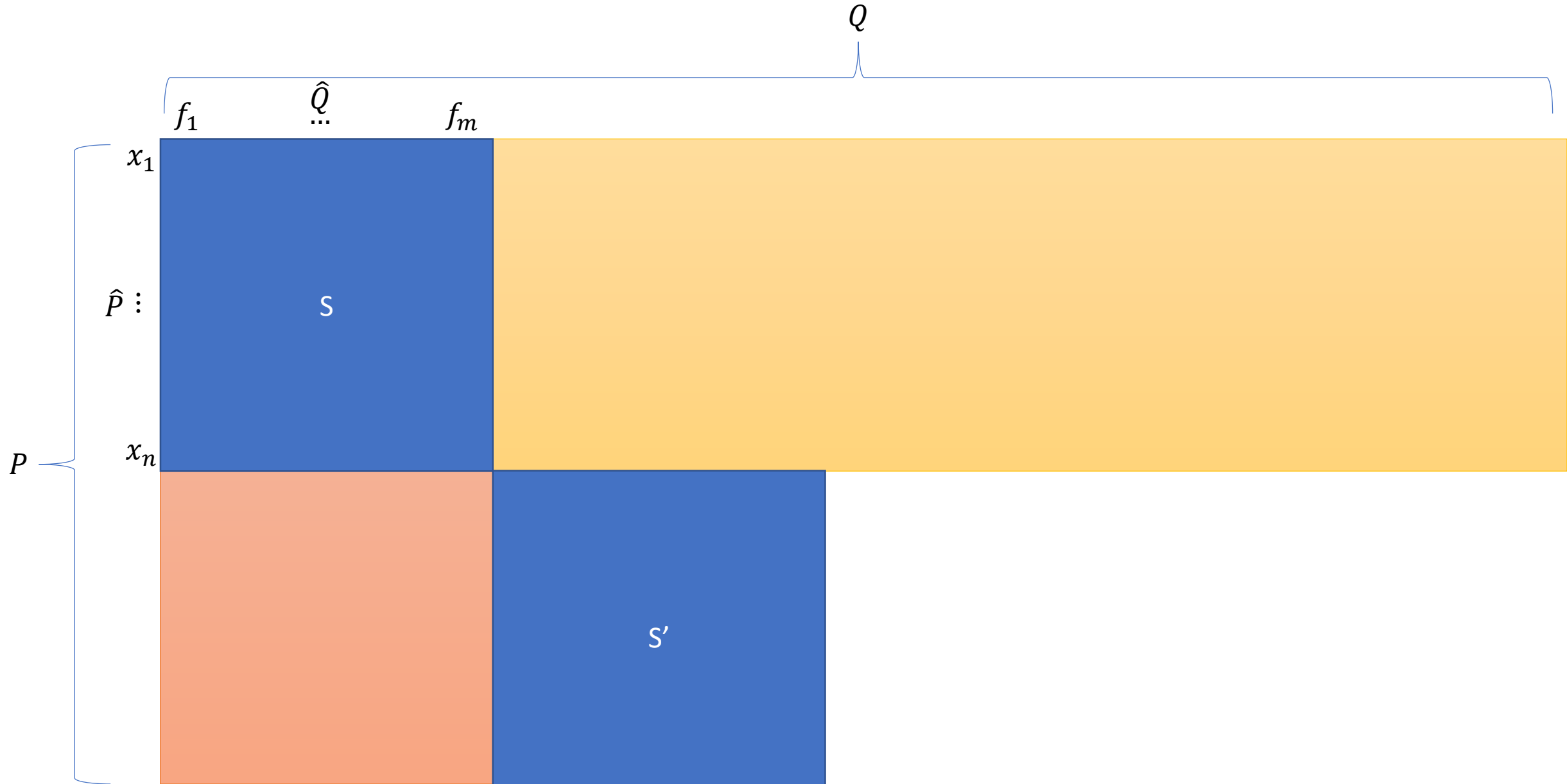
**Theorem:** After  $O\left(m \cdot \frac{\log n}{\epsilon^2}\right)$  calls to the learning oracle, the algorithm returns a solution  $p \in (\Delta H)^m$  that achieves empirical error at most:

$$OPT(\alpha, \hat{P}, \hat{Q}) + \epsilon$$

and satisfies for every  $i, i' \in \{1, \dots, n\}$ :

$$|FN(x_i, p, \hat{Q}) - FN(x_{i'}, p, \hat{Q})| \leq \alpha + \epsilon$$

# Generalization: Two Directions



# Generalization

**Theorem:** Assuming

$$1) m \geq \text{poly} \left( \log n, \frac{1}{\epsilon}, \log \frac{1}{\delta} \right),$$

$$2) n \geq \text{poly} \left( m, \text{VCDIM}(H), \frac{1}{\epsilon}, \frac{1}{\beta}, \log \frac{1}{\delta} \right)$$

the algorithm returns a solution  $\psi$  that with probability  $1 - \delta$  achieves error at most:

$$OPT(\alpha, P, Q) + \epsilon$$

and is such that with probability  $1 - \beta$  over  $x, x' \sim P$ :

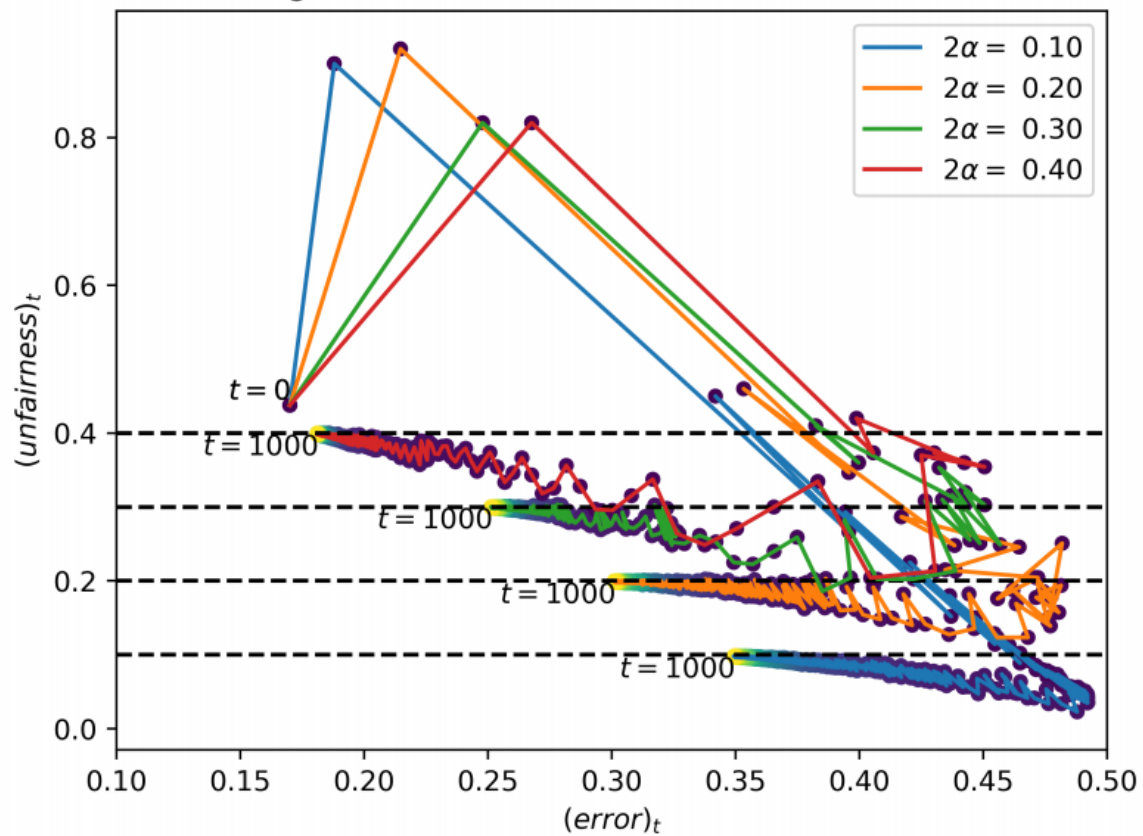
$$|FN(x, \psi, Q) - FN(x', \psi, Q)| \leq \alpha + \epsilon$$



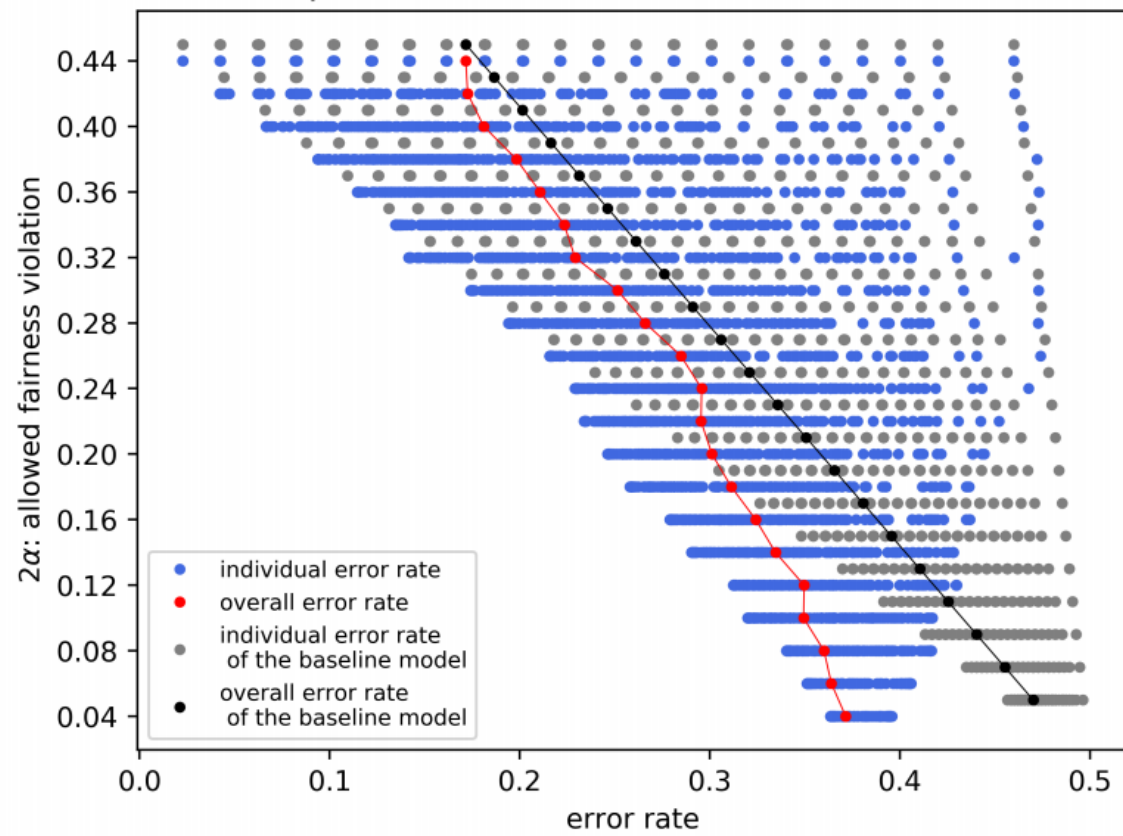
# Does it work?

- It is important to experimentally verify “oracle efficient” algorithms, since it is possible to abuse the model.
  - E.g. use learning oracle as an arbitrary NP oracle.
- A brief “Sanity Check” experiment:
  - Dataset: Communities and Crime
  - First 50 features are designated as “problems” (i.e. labels to predict)
  - Remaining features treated as features for learning.

convergence: communities ( $n = 200, m = 50, d = 20$ )



error spread: communities ( $n = 200, m = 50, d = 20$ )



# Takeaways

- We should think carefully about what definitions of “fairness” really promise to individuals.
- Making promises to individuals is sometimes possible, even without making heroic assumptions.
- Once we fix a definition, there is often an interesting algorithm design problem.
- Once we have an algorithm, we can have the tools to explore inevitable *tradeoffs*.

